

SCHOOL OF ELECTRONICS ENGINEERING

M. Tech Internet of Things & Sensor Systems

(M.Tech MTS)

Curriculum

(2023-24 admitted students)

VISION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

Transforming life through excellence in education and research.

MISSION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

World class Education: Excellence in education, grounded in ethics and critical thinking, for improvement of life.

Cutting edge Research: An innovation ecosystem to extend knowledge and solve critical problems.

Impactful People: Happy, accountable, caring and effective workforce and students.

Rewarding Co-creations: Active collaboration with national & international, industries & universities for productivity and economic development.

Service to Society: Service to the region and world through knowledge and compassion.

VISION STATEMENT OF THE SCHOOL OF ELECTRONICS ENGINEERING

To be a leader by imparting in-depth knowledge in Electronics Engineering, nurturing engineers, technologists and researchers of highest competence, who would engage in sustainable development to cater the global needs of industry and society.

MISSION STATEMENT OF THE SCHOOL OF ELECTRONICS ENGINEERING

- Create and maintain an environment to excel in teaching, learning and applied research in the fields of electronics, communication engineering and allied disciplines which pioneer for sustainable growth.
- Equip our students with necessary knowledge and skills which enable them
 to be lifelong learners to solve practical problems and to improve the quality
 of human life.

M. Tech Internet of Things & Sensor Systems

PROGRAMME EDUCATIONAL OBJECTIVES (PEOs)

- 1. Graduates will be engineering practitioners and leaders, who would help solve industry's technological problems
- 2. Graduates will be engineering professionals, innovators or entrepreneurs engaged in technology development, technology deployment, or engineering system implementation in industry
- 3. Graduates will function in their profession with social awareness and responsibility
- 4. Graduates will interact with their peers in other disciplines in industry and society and contribute to the economic growth of the country
- 5. Graduates will be successful in pursuing higher studies in engineering or management
- 6. Graduates will pursue career paths in teaching or research

M. Tech Internet of Things & Sensor Systems

PROGRAMME OUTCOMES (POs)

- PO_01: Having an ability to apply mathematics and science in engineering applications.
- PO_02: Having an ability to design a component or a product applying all the relevant standards and with realistic constraints, including public health, safety, culture, society and environment
- PO_03: Having an ability to design and conduct experiments, as well as to analyse and interpret data, and synthesis of information
- PO_04: Having an ability to use techniques, skills, resources and modern engineering and IT tools necessary for engineering practice
- PO_05: Having problem solving ability- to assess social issues (societal, health, safety, legal and cultural) and engineering problems
- PO_06: Having adaptive thinking and adaptability in relation to environmental context and sustainable development
- PO_07: Having a clear understanding of professional and ethical responsibility
- PO_08: Having a good cognitive load management skills related to project management and finance

M. Tech Internet of Things & Sensor Systems

PROGRAMME SPECIFIC OUTCOMES (PSOs)

On completion of M. Tech. (Internet of Things & Sensor Systems) programme, graduates will be able to

- PSO1: Competent, and innovative with a strong cognizance in the area of sensors, IoT, data science, controllers and signal processing through the application of acquired knowledge and skills
- PSO2: Apply advanced techniques and tools of sensing and computation to solve multi-disciplinary challenges in industry and society.
- PSO3: To exhibit independent and collaborative research with strategic planning, while demonstrating the professional and ethical responsibilities of the engineering profession.

	Category Credit Detail								
SI.No.	Description	Credits	Maximum Credit						
1	DC - Discipline Core	24	24						
2	DE - Discipline Elective	12	12						
3	PI - Projects and Internship	26	26						
4	OE - Open Elective	3	3						
5	SE - Skill Enhancement	5	5						
	Total Credits	70							

	Discipline Core											
sl.no	Course Code	Course Title	Course Type	Ver sio n	L	Т	P	J	Credits			
1	MITS507L	Signal Processing and Data Analytics	Theory Only	1.0	3	0	0	0	3.0			
2	MITS509L	Sensor Technology and Data Acquisition	Theory Only	1.0	3	0	0	0	3.0			
3	MITS509P	Sensor Technology and Data Acquisition Lab	Lab Only	1.0	0	0	2	0	1.0			
4	MITS510L	IoT Architecture	Theory Only	1.0	3	0	0	0	3.0			
5	MITS510P	IoT Architecture Lab	Lab Only	1.0	0	0	2	0	1.0			
6	MITS511L	Microsystems Fabrication Technology	Theory Only	1.0	3	0	0	0	3.0			
7	MITS512L	Microcontrollers and Interfacing	Theory Only	1.0	3	0	0	0	3.0			
8	MITS512P	Microcontrollers and Interfacing Lab	Lab Only	1.0	0	0	2	0	1.0			
9	MITS513L	Wireless Sensor Networks and Data Communication	Theory Only	1.0	3	0	0	0	3.0			
10	MITS514L	Robotics and Control Systems	Theory Only	1.0	2	0	0	0	2.0			
11	MITS514P	Robotics and Control Systems Lab	Lab Only	1.0	0	0	2	0	1.0			

	Discipline Elective										
sl.no	Course Code	Course Title	Course Type	Ver sio n	L	Т	P	J	Credits		
1	MEDS501L	Embedded System Design	Theory Only	1.0	3	0	0	0	3.0		
2	MEDS601L	Electromagnetic Interference and Compatibility	Theory Only	2.0	3	0	0	0	3.0		
3	MEIC506L	Wireless Communications	Theory Only	1.0	3	0	0	0	3.0		
4	MITS601L	Flexible and Wearable Sensors	Theory Only	1.0	3	0	0	0	3.0		
5	MITS603L	Chemical and Environmental Sensor	Theory Only	1.0	3	0	0	0	3.0		
6	MITS604L	Cloud and Fog Computing	Theory Only	1.0	3	0	0	0	3.0		
7	MITS605L	IoT Security and Trust	Theory Only	1.0	3	0	0	0	3.0		
8	MITS608L	RF and Microwave Sensors	Theory Only	1.0	3	0	0	0	3.0		
9	MITS611L	Automotive Sensors and In-Vehicle Networking	Theory Only	1.0	3	0	0	0	3.0		
10	MITS612L	Fibre Optic Sensors and Photonics	Theory Only	1.0	3	0	0	0	3.0		
11	MITS613L	System-on-chip	Theory Only	1.0	3	0	0	0	3.0		
12	MITS614L	Deep Learning	Theory Only	1.0	3	0	0	0	3.0		
13	MITS615L	Web Design and Development	Theory Only	1.0	3	0	0	0	3.0		
14	MITS616L	Edge and Distributive Computing	Theory Only	1.0	3	0	0	0	3.0		

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	Projects and Internship										
sl.no	Course Code	Course Title	Course Type	Ver sio	L	Т	Р	J	Credits		
				n							
1	MITS696J	Study Oriented Project	Project	1.0	0	0	0	0	2.0		
2	MITS697J	Design Project	Project	1.0	0	0	0	0	2.0		
3	MITS698J	Internship I/ Dissertation I	Project	1.0	0	0	0	0	10.0		
4	MITS699J	Internship II / Dissertation II	Project	1.0	0	0	О	0	12.0		

		Open Elective							
sl.no	Course Code	Course Title	Course Type	Ver	L	т	Р	J	Credits
				sio					
				n					
1	MFRE501L	Francais Fonctionnel	Theory Only	1.0	3	0	0	0	3.0
2	MGER501L	Deutsch fuer Anfaenger	Theory Only	1.0	3	0	0	0	3.0
3	MSTS601L	Advanced Competitive Coding	Soft Skill	1.0	3	0	0	0	3.0

	Skill Enhancement											
sl.no	Course Code	Course Title	Course Type	Ver sio n	L	т	P	J	Credits			
1	MENG501P	Technical Report Writing	Lab Only	1.0	0	0	4	0	2.0			
2	MSTS501P	Qualitative Skills Practice	Soft Skill	1.0	0	0	3	0	1.5			
3	MSTS502P	Quantitative Skills Practice	Soft Skill	1.0	0	0	3	0	1.5			

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Course Code	Course Title	L	T	Р	С
MITS507L	Signal Processing and Data Analytics	3	0	0	3
Pre-requisite	NIL	Syllabus version			
		1.0			

- 1. To introduce the concepts of discrete time signal processing and the characterization of random signals.
- 2. To present the basic theory of modeling the signals and the methods of estimating theunknowns using prediction filters
- 3. To provide a comprehensive understanding on applying FFT, DCT, and wavelettechniques for extracting the signal features.
- 4. To provide an overview of analysing big data using intelligent techniques and an in-depth introduction to two main areas of Machine Learning: supervised and unsupervised.

Course Outcomes:

- 1. Apply FFT, DCT wavelet techniques for extracting the features from the big data
- 2. Develop algorithms that can be used to analyse the real-world univariate and multivariate time series data.
- 3. Design an approach to leverage data using the steps in the machine learning process.
- 4. Understand and apply both supervised and unsupervised classification methods to detectand characterize patterns in real-world data.
- 5. Estimate the signal parameters and identify the model using ARMA models and prediction filters.
- 6. Understand the methods of visualization and analysis of big data.

Module:1 Discrete Random Signal Processing

7 hours

Random Processes, Ensemble Average, Gaussian Process, Multi variate Gausssian Process, Stationary process, Autocorrelation, Auto Covariance, Ergodicity, White noise, Power Spectrum, Filtering of Random Process

Module:2 | Signal Modeling

6 hours

ARMA, AR, MA Models. Wiener filter, Linear prediction, Kalman Filter.

Module:3 | Feature extraction

6 hours

FFT, Power spectrum, DCT, filter banks, Wavelet, Wavelet Packets, Cepstrum

Module:4 | Time series analysis

6 hours

Basic analysis, Univariate time series analysis, Multivariate time series analysis, non stationary time series.

Module:5 Reduction of dimensionality

6 hours

Bayesian decision, Linear discrimination, Principal Component analysis, SVD, Independent Component Analysis.

Module:6 | Machine learning

6 hours

Supervised learning, generative algorithms, Support Vector machines, Unsupervised learning, K means clustering, Neural network (SOM, ART), Expectation maximization.

Module:7	Big Data Analytics	6 hours						
Introduction	n Big data analytics, visualization and data exploration, basic and in	termediate						
	near and logistic regression, decision tree.							
Module:8	Contemporary Issues	2 hours						
	Total Lecture:	45 hours						
Text Book	x(s)							
1. J. G. Proakis, DG. Manolakis and D. Sharma, "Digital signal processing								
principles,algorithms and applications", 2012, 4 th ed., Person education, USA.								
	phocles J. Orfanidis, "Inroduction to signal Processing" 2010, 2 nd	ed., Prentice						
	II, NewDelhi India.							
Reference								
	penhiem V. A.V and Schaffer R. W, "Discrete- time signal Processi	ng", 2014, 3 rd						
	Prentice Hall, New Delhi, India							
	omas A. Runkler, "Data Analytics: Models and Algorithms for Intalysis", 2016, 2 nd ed., Springer Verlag, UK	telligent Data						
	vin P. Murphy, "Machine Learning: A Probabilistic Perspective"	2012. 1 st						
	, MITPress, USA	,						
Mode of Ev	/aluation: CAT / Assignment / Quiz / FAT							
Recommen	ded by Board of Studies 28-07-2022							
Approved b	y Academic Council No. 67 Date 08-08-2022							

Course Code	Course Title	L	T	Р	С
MITS509L	Sensor Technology and Data Acquisition	3	0	0	3
Pre-requisite	NIL	Syl	Syllabus version		
			1.0		

- 1. To provide in depth knowledge in physical principles applied in sensing, measurement and a comprehensive understanding on how measurement systems are designed, calibrated, characterized, and analyzed.
- 2. To introduce the students to sources and detectors of various Optical sensing mechanisms and provide in-depth understanding of the principle of measurement, and theory of instruments and sensors for measuring velocity and acceleration
- 3. To give a fundamental knowledge on the basic laws and phenomena on which operation of sensor transformation of energy is based.
- 4. To impart a reasonable level of competence in the design, construction, and execution of mechanical measurements strain, force, torque and pressure
- 5. To explore the fundamentals of data acquisition using sensors, NI data acquisition hardware, and LabVIEW.

Course Outcomes

- 1. Use concepts in common methods for converting a physical parameter into an electrical quantity
- 2. Choose an appropriate sensor comparing different standards and guidelines to make sensitive measurements of physical parameters like pressure, flow, acceleration, etc.
- 3. Design and develop sensors using optical methods with desired properties
- 4. Evaluate performance characteristics of different types of sensors
- 5. Locate different types of sensors used in real life applications and paraphrase their importance
- 6. Create analytical design and development solutions for sensors and Develop PC-based data acquisition and signal conditioning.
- 7. Compete in the design, construction, and execution of systems for measuring physical quantities and develop virtual experiment models

Module:1	Sensor fundamentals, characteristics and data	8 hours
	acquisition	

Sensor Classification, Performance and Types, Error Analysis characteristics. Introduction to data acquisition, Virtual instrumentation, Principles of Analog Signal conditioning: Differential and instrumentation amplifiers, I to V and V to I converters. Converters: Comparators, DACs, ADCs, Sample and hold.

Module:2 Optical Sources and Detectors 4 hours

Electronic and Optical properties of semiconductor as sensors, LED, Semiconductor lasers, Fiber optic sensors, Thermal detectors, Photo multipliers, photoconductive detectors, Photodiodes, Avalanche photodiodes, CCDs.

Module:3Intensity Polarization and Interferometric Sensors4 hoursIntensitysensor, Microbending concept, Interferometers, Mach Michelson, Fabry Perot and Sagnac, Phase sensor: Phase detection, Polarization maintaining fibers.Zehnder, Polarization

Module:4 | Strain, Force, Torque and Pressure sensors and data | 8 hours

acquisition techniques.

Strain gages, strain gage beam force sensor, piezoelectric force sensor, load cell, torque sensor, Piezo-resistive and capacitive pressure sensor, optoelectronic pressure sensors, vacuum sensors. Design of signal conditioning circuits for strain gauges, piezo, capacitance and optoelectronics sensors, Design and development of data acquisition systems for strain, force, pressure and piezo sensors.

Module:5 | Position, Direction, Displacement and Level Sensors 8 hours and data acquisition techniques.

Potentiometric and capacitive sensors, Inductive and magnetic sensor, LVDT, eddy current, transverse inductive, Hall effect, magneto resistive, magnetostrictive sensors. Fiber optic liquid level sensing, Fabry Perot sensor, ultrasonic sensor, capacitive liquid level sensor. Signalcondition circuits for reactive and self generating sensors. Design and development of data acquisition systems for position, direction, displacement and level sensors.

Module:6 Velocity and Acceleration sensors

4 hours

Electromagnetic velocity sensor, Doppler with sound, light, Accelerometer characteristics, capacitive, piezo-resistive, piezoelectric accelerometer, thermal accelerometer, rotor, monolithicand optical gyroscopes.

Module:7 Flow, Temperature and Acoustic sensors and data 7 hours acquisition techniques

Flow sensors: pressure gradient technique, thermal transport, ultrasonic, electromagnetic and Laser an emometer. microflow sensor, coriolis mass flow and drag flow sensor. Temperature sensors- thermoresistive, thermoelectric, semiconductor and optical. Piezoelectric temperature sensor. Acoustic sensorsmicrophones-resistive, capacitive, piezoelectric, fiber optic, solid state - electrect microphone. Design and development of data acquisition system for flow temperature and acoustic sensors. Development of sensor systems using Lab view case studies

Mod	ule:8	Contemporary Issues				2 hours			
					Total Hours	45 hours			
Text	Book(s)								
1	Jacob Fi	raden, "Hand Book of M	Modern Se	ensors:	physics, De	esigns and			
	Application	ons", 2015, 3 rd edition, Spr	inger, New	/ York.		_			
2.	Jon. S. W	Vilson, "Sensor Technolog	gy Hand B	ook", 2	.011, 1 st editio	on, Elsevier,			
	Netherlar	nd.							
Refe	Reference Books								
1.	GerdKeis	ser,"Optical Fiber Commu	nications",	, 2017,	5 th edition, I	McGraw-Hill			
	Science, Delhi.								
2.	John G \	Webster, "Measurement,	Instrumer	itation	and sensor H	Handbook",			
	2017, 2 nd	dedition, CRC Press, Flori	da.						
3.	Eric Udd	l and W.B. Spillman, "F	iber optic	senso	ors: An intro	duction for			
	engineers	s andscientists", 2013, 2 nd	^l edition, W	/iley, N	ew Jersey.				
4.	Bahaa E	. A. Saleh and Malvin C	arl Teich,	"Fund	amentals of	photonics",			
	2012, 1 st	edition, John Wiley, New	York.						
Mod	e of Evalua	ation: CAT, Digital Assign	ments, Qu	iz, Onl	ine course, Pa	aper			
publi	cation, Pro	ojects, Hackathon/Makeath	non and FA	AT.					
Reco	ommended	l by Board of Studies	07-06-20	23	·				
Appr	oved by A	cademic Council	No. 70	Date	24-06-2023				

Course Code	Course Title	L	Т	Р	С
MITS509P	Sensor Technology and Data Acquisition	0	0	2	1
	Lab				
Pre-requisite	NIL	Syllabus version			ion
		1.0			

- 1. To provide in depth knowledge in physical principles applied in sensing, measurement and a comprehensive understanding on how measurement systems are designed, calibrated, characterized, and analyzed.
- 2. To introduce the students to sources and detectors of various Optical sensing mechanisms and provide in-depth understanding of the principle of measurement, and theory of instruments and sensors for measuring velocity and acceleration
- 3. To give a fundamental knowledge on the basic laws and phenomena on which operation of sensor transformation of energy is based.
- 4. To impart a reasonable level of competence in the design, construction, and execution of mechanical measurements strain, force, torque and pressure

Course Outcomes

- Choose an appropriate sensor comparing different standards and guidelines to make sensitive measurements of physical parameters like pressure, flow, acceleration, etc.
- 2. Design and develop sensors using optical methods with desired properties
- 3. Evaluate performance characteristics of different types of sensors
- 4. Locate different types of sensors used in real life applications and paraphrase their importance
- Perform different types of data acquisition and identify the correct sensor for their measurements. Develop integrated, high-performance data acquisition systems that produce accurate measurements
- 6. Acquire data from sensors, such as thermocouples and strain gages, using NI DAQ hardware and analyze the results in LabVIEW and MATLAB
- 7. Apply advanced understanding of LabVIEW and the NI-DAQmx API to create applications

Indicative Experiments

- 1. Design of signal conditioning circuits for strain gauges- Strain, Force, pressure, and torque measurement
 - I. Strain measurement with Bridge Circuit
 - II. Beam force sensor using Strain Gauge Bridge
 - III. Beam deflection sensing with Strain Gauge Bridge
 - IV. Diaphragm pressure sensor using Strain Gauge Bridge
 - V. Shear strain and angle of shift measurement of hollow shaft

After completing the 1st set of characteristics. Design a weighing machine having arange of 0-5 Kg with a sensitivity of 5 mg. What modification he/she has to do tochange the upper range to 100 Kg with a sensitivity of 100 mg.

- 2. Develop a displacement measurement system with the following sensors:
 - i. Inductive transducer (LVDT)
 - ii. Hall effect sensor

3.	After studying the characteristics of a temperature measurement sys								
	suitablesensor.	'		3					
		ple principles							
	ii. Thermistor	and linearization	on of NTC T	hermistor					
		Temperature							
		ctor Temperat							
	v. Current output absolute temperature sensor								
4.	Develop a sensor system for force		<u> </u>						
5.	Measurement of shear strain and								
	for many applications. Based of								
	suggest a non-contact method a								
6.	LabVIEW Graphical Programmir								
_	read data into MATLABand Simulink and write data into DAQ device								
7.	Acquire and generate analog sign								
	Acquire and generate non-clocke		os usina MI	dovisos					
	Measure frequency, pulse width a Generate Pulse Width Modulated		es using ivi	devices					
	Generale Puise Width Modulated	Total Labor	atory Hours	30 hours					
Tov	t Book(s)	TOTAL LABOR	atory riours	5 30 110013					
1	Jacob Fraden, "Hand Book of	Modern Ser	nsors: nhysi	cs Designs and					
'	Applications", 2015, 3 rd edition, Sp			cs, besigns and					
2.	Jon. S. Wilson, "Sensor Technol	ogy Hand Boo	ok", 2011, 1	st edition, Elsevier,					
	Netherland.	3,							
Ref	erence Books								
1.	GerdKeiser,"Optical Fiber Comn	nunications", 2	2017, 5 th ed	lition, McGraw-Hill					
	Science, Delhi.								
2.	John G Webster, "Measuremen		ation and se	ensor Handbook",					
	2017, 2 nd edition, CRC Press, Flo								
3.	Eric Udd and W.B. Spillman,								
	engineers and scientists", 2013, 2								
4.	Bahaa E. A. Saleh and Malvin		Fundament	als of photonics",					
	2012, 1st edition, John Wiley, New York.								
				Mode of assessment: Continuous assessment / FAT / Oral examination and others					
	de of assessment: Continuous asse	essment / FAT	/ Oral exam	nination and others					
Rec			/ Oral exam	nination and others 24-06-2023					

Course Code	Course Title	L	T	Р	С			
MITS510L	IoT Architecture	3	0	0	3			
Pre-requisite	NIL	Sylla	bus v	/ersi	on			
		1.0						
Course Objecti	Course Objectives							

- 1. Introduce evolution of internet technology and need for IoT.
- 2. Discuss on IoT reference layer and various protocols and software.
- 3. Train the students to build IoT systems using sensors, single board computers and open sourceIoT platforms.
- 4. Make the students to apply IoT data for business solution in various domain in secured manner.

Course Outcomes

- 1. Identify the IoT networking components with respect to OSI layer.
- 2. Build schematic for IoT solutions.
- 3. Design and develop IoT based sensor systems.
- 4. Select IoT protocols and software.

Evaluate the wireless technologies for IoT.	
6. Appreciate the need for IoT Trust and variants of IoT.	
Module:1 Evolution of IoT	7 hours
Review of computer communication concepts (OSI layers, co	mponents, packet
communication, Networks, TCP-IP, subnetting, IPV4 addressing	g and challenges).
IPV6 addressing. IoT architecturereference layer.	
Module:2 Introduction to IoT components	6 hours
Characteristics IoT sensor nodes, Edge computer, cloud and	
single boardcomputers, open source hardwares, Examples of lo	T infrastructure
Module:3 loT protocols and softwares	6 hours
MQTT, UDP, MQTT brokers, publish subscribe modes, HTTP, Cogateway protocols,	OAP,XMPP and
Module:4 IoT point to point communication technologies	s 6 hours
IoT Communication Pattern, IoT protocol Architecture, Selection	of Wireless
technologies (6LoWPAN, Zigbee, WIFI, BT, BLE, SIG, NFC, LOR	A, Lifi, Widi)
Module:5 Introduction to Cloud computation and Bigdata	6hours
analytics	
Evolution of Cloud Computation, Commercial clouds and the	eir features, open
source IoT platforms, cloud dashboards, Introduction to big d	eir features, open lata analytics and
source IoT platforms, cloud dashboards, Introduction to big deladoop.	lata analytics and
source IoT platforms, cloud dashboards, Introduction to big defined Hadoop. Module:6 IoT security	lata analytics and 6hours
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weighted	lata analytics and 6hours ght cryptography,
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weig Quadruple TrustModel for IoT-A – Threat Analysis and model	lata analytics and 6hours ght cryptography,
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weig Quadruple TrustModel for IoT-A – Threat Analysis and model security	Ghours
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weig Quadruple TrustModel for IoT-A – Threat Analysis and model security Module:7 IoT application and its Variants.	6hours of the formula is a second of the following sec
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weig Quadruple TrustModel for IoT-A – Threat Analysis and model security Module:7 IoT application and its Variants. Case studies: IoT for smart cities, health care, agriculture, significant content of the protocol in the pro	Ghours Ghours Ghours Ghours Ghours Ghours Mart meters.M2M,
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weigh Quadruple TrustModel for IoT-A — Threat Analysis and model security Module:7 IoT application and its Variants.	Ghours Ghours Ghours Ghours Ghours Ghours Mart meters.M2M,
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weig Quadruple TrustModel for IoT-A – Threat Analysis and model security Module:7 IoT application and its Variants. Case studies: IoT for smart cities, health care, agriculture, so Web of things, Cellular IoT, Industrial IoT, Industry 4.0, IoT standard.	6hours ht cryptography, for IoT-A, Cloud 6 hours mart meters.M2M, dards.
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weig Quadruple TrustModel for IoT-A – Threat Analysis and model security Module:7 IoT application and its Variants. Case studies: IoT for smart cities, health care, agriculture, so Web of things, Cellular IoT, Industrial IoT, Industry 4.0, IoT standard.	6hours ght cryptography, for IoT-A, Cloud 6 hours mart meters.M2M, dards. 2 hours
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weig Quadruple TrustModel for IoT-A — Threat Analysis and model security Module:7 IoT application and its Variants. Case studies: IoT for smart cities, health care, agriculture, so Web of things, Cellular IoT, Industrial IoT, Industry 4.0, IoT stand Module:8 Contemporary Issues	6hours ght cryptography, for IoT-A, Cloud 6 hours mart meters.M2M, dards. 2 hours
source IoT platforms, cloud dashboards, Introduction to big of Hadoop. Module:6 IoT security Need for encryption, standard encryption protocol, light weig Quadruple TrustModel for IoT-A — Threat Analysis and model security Module:7 IoT application and its Variants. Case studies: IoT for smart cities, health care, agriculture, si Web of things, Cellular IoT, Industrial IoT, Industry 4.0, IoT stand Module:8 Contemporary Issues Total Ho	6hours ght cryptography, for IoT-A, Cloud 6 hours mart meters.M2M, dards. 2 hours 0urs 45 hours

Designing IoT solutions withthe IoT Architecture Reference Model", Springer

	Open, 2016						
2.	Jan Holler, Vlasios Tsiatsis, Cat	therine Mulligan, Stamatis Karnouskos,					
	Stefan Avesand, David Boyle, "From Machine to Machine to Internet of						
	Things", Elsevier Publications, 2014.						
Refe	Reference Books						
1.		Yang, Huansheng Ning, The Internet of					
	Things: From RFID to the Next-C	Generation Pervasive Network, Aurbach					
	publications, March, 2008.						
2.	Vijay Madisetti , Arshdeep Bahqa, Adrian McEwen (Author), Hakim						
	Cassimally "Internet of Things A Hands-on-Approach" Arshdeep Bahga &						
	Vijay Madisetti, 2014.						
3.	Asoke K Talukder and Roopa R Ya	vagal, "Mobile Computing," Tata McGraw					
	Hill, 2010.						
4	Barrie Sosinsky, "Cloud Computing	g Bible", Wiley-India, 2010					
5	RonaldL. Krutz, Russell Dean Vines	s,Cloud Security: A Comprehensive Guide					
	to SecureCloud Computing, Wiley-I	ndia, 2010					
Mode		signments, Quiz, Online course, Paper					
	ication, Projects,Hackathon/Makeath	•					
Publi	realieri, i rejecte, raenali ieri, maneali	ion and then					
Reco	ommended by Board of Studies	07-06-2023					
Appr	oved by Academic Council	No. 70 Date 24-06-2023					

Course Code	Course Title	L	Т	Р	С
MITS510P	IoT Architecture Lab	0	0	2	1
Pre-requisite	NIL	Syllabus version			ion
		1.0			

- 1. Introduce evolution of internet technology and need for IoT.
- 2. Discuss on IoT reference layer and various protocols and software.
- 3. Train the students to build IoT systems using sensors, single board computers and open source
- 4. IoT platforms.
- 5. Make the students to apply IoT data for business solution in various domain in secured manner.

Course Outcomes

- 1. Identify the IoT networking components with respect to OSI layer.
- 2. Build schematic for IoT solutions
- 3. Design and develop IoT based sensor systems.
- 4. Select IoT protocols and software.
- 5. Evaluate the wireless technologies for IoT.
- 6. Appreciate the need for IoT Trust and variants of IoT.

Indicative Experiments

- 1. | C programming
- 2. | C++/JAVA programming
- 3. Python programming
- 4. Thinkspeak/thingsboard cloud platforms
- 5. Nodered
- 6. IoT usecases

Total Laboratory Hours | 30 hours

Text Book(s)

- Alessandro Bassi, Martin Bauer, Martin Fiedler, Thorsten Kramp, Rob van Kranenburg, Sebastian Lange, Stefan Meissner, "Enabling things to talk – Designing IoT solutions withthe IoT Architecture Reference Model", Springer Open, 2016
- 2. Jan Holler, Vlasios Tsiatsis, Catherine Mulligan, Stamatis Karnouskos, Stefan Avesand, David Boyle, "From Machine to Machine to Internet of Things", Elsevier Publications, 2014.

Reference Books

- 1. LuYan, Yan Zhang, Laurence T. Yang, Huansheng Ning, The Internet of Things: From RFID to the Next-Generation Pervasive Network, Aurbach publications, March, 2008.
- 2. Vijay Madisetti , Arshdeep Bahga, Adrian McEwen (Author), Hakim Cassimally "Internet of Things A Hands-on-Approach" Arshdeep Bahga & Vijay Madisetti, 2014.
- 3. Asoke K Talukder and Roopa R Yavagal, "Mobile Computing," Tata McGraw Hill, 2010.
- 4 Barrie Sosinsky, "Cloud Computing Bible", Wiley-India, 2010
- 5 RonaldL. Krutz, Russell Dean Vines, Cloud Security: A Comprehensive Guide to SecureCloud Computing, Wiley-India, 2010

Mode of assessment: Continuous assessment / FAT / Oral examination and others

Recommended by Board of Studies	07-06-2023		
Approved by Academic Council	No. 70	Date	24-06-2023

Course Code	Course Title	L	Т	Р	С
MITS511L	Microsystems Fabrication Technology	3	0	0	3
Prerequisite	NIL	Syll	abus	version	on
		1.0			

- 1. To introduce the fundamental concepts of MEMS based sensors and actuators.
- 2. To acquaint the students with various materials and material properties for Microsystem designing.
- 3. To provide comprehensive understanding of various micromachining techniques and expose the students to design, simulation and analysis software.
- 4. Enhancing the basics of thick film and hybrid technologies for sensor development.

Course Outcomes

- 1. Identify and understand the fundamental concepts and background of MEMS and Microsystems
- 2. Familiar with the basics of various sensors and actuators.
- 3. The students were acquainted with various materials for Microsystem designing.
- 4. Determine and compare the scaling effects in miniaturizing devices.
- 5. Recognize and interpret various micromachining techniques and design, analysis and applications of various MEMS devices micromachining tools and techniques
- 6. Acquainted with thick film and hybrid technologies for sensor development.
- 7. Incorporate simulation and micro-fabrication knowledge for developing various MEMS devices.

Module:1Introduction to MEMS and Microsystems7 hoursMEMS and Microsystems, Miniaturization, Benefits of Microsystems, Typical
MEMS andMicrosystems products, Evolution of Micro fabrication and Applications.Module:2Introduction to Sensors and Actuators6 hoursVarious domains and classification of transducers: electrostatic, piezoelectric,
thermal. Sensing principles: electrostatic, resistive, chemical etc. SAW devices.
Micro actuators, Design of Micro accelerometers, Engineering Science for
Microsystem design and fabrication.

Module:3Materials for Microsystems6 hoursSilicon, Silicon compounds, Silicon Piezo resistors, Gallium Arsenide, Quartz, Piezoelectric materials, Polymers, Shape Memory Alloys, ferroelectric and rheological materials.Shape Memory Alloys, ferroelectric and fe

Module:4 Scaling Effects in Microsystems 6 hours
Introduction to Scaling, Scaling laws, Scaling in Geometry, Scaling in Rigid body dynamics, Scaling in Electromagnetic, Electrostatic, magnetic, optical and Thermal domains. Scaling in Fluid mechanics.

Module:5 Micromachining Technologies 6 hours

Overview of silicon processes techniques, Photolithography, Ion Implantation,
Diffusion, Chemical Vapor Deposition, Physical vapor Deposition, Epitaxy, Etching,
Bulk micromachining, Surface Micromachining, LIGA and other techniques.

Module:6 MEMS and micro systems applications 6 hours

Details of application in actual systems, introduction to RF- MEMS, MOEMS, future of smart structures and MEMS leading to NEMS. Packaging, test and calibration of MEMS.

		Hybrid Technology				6 hours
		hybrid technology in				
		anufacturing Screen ma				
		ick- vs. thin-film techno				
		ace mount technology (SMT) Activ	e and	passiv	ve devices (SMD),
	Connection technologies, Packaging.					
Module:8 Contemporary Issues				2 hours		
ı						
Total	Hours					45 hours
Text	Book(s)					
1.		thasuresh, K J Vinoy, S				
		smartsystems", 2012, 1				
2.		lsu, "MEMS & Microsys	tem, Desi	gn and	l Manu	facture", 2017, 1 st
		aw HillIndia, New Delhi.				
	rence Boo					
1.		NP, "MEMS", 2017, 1 st e				
2		Menz, Jürgen Mohr, Oliv	er Paul, "N	Microsy	rstem T	echnology", 2011,
		iley, New York.				
3		T. Smith R.C. and Wang a andControl', 2011, 1 st e				
4		Tabib – Arar, 'Microad				
		lechanical, Chemical and				
	Academic	publishers, New York.				
Mode	e of Evalu	iation: CAT, Digital As	ssignments	s, Qui	z, Onl	ine course, Paper
public	cation, Pro	jects,Hackathon/Makeat	hon and F	AT.		·
Reco	mmended	by Board of Studies	07-06-20	23		
		ademic Council	No. 70	Date	24-06	-2023

Course Code	Course Title	L	Т	Р	С
MITS512L	Microcontrollers and Interfacing	3	0	0	3
Prerequisite	NIL	Syllabus Version			sion
		1.0			

- 1. Introduce low power microcontrollers and to develop the skill set of programming low power sensing applications.
- 2. Impart the knowledge of various peripheral related to sensing and communication using wired or wireless means.
- 3. Upgrade the students by introducing them Advanced ARM Cortex microcontrollers
- 4. Develop the skill set of students to build IoT systems and sensor interfacing.

Course Outcomes

- 1. Design and develop embedded programs for low power microcontrollers for sensor applications.
- 2. Develop ARM basic and advanced programs.
- 3. Interface and deploy analog and digital sensors
- 4. Develop communication system with sensor units
- 5. Design develop IoT systems using Wi-Fi CC3200.
- 6. Program the single board computers to read sensor data and posting in cloud.

Module:1MSP430 microcontrollers7 hoursArchitecture of the MSP430, Memory, Addressing modes, Reflections on the CPU instruction set. Clock system, Exceptions: Interrupts and resets. Functions and subroutines, Mixing C and assembly language, Interrupts, Interrupt service routines, Issues associated with interrupts, Low-power modes of operation.Module:2ARM Cortex MX microcontroller6 hoursARM Cortex M4: Assembly language basics, Thumb-2 Technology, ARM Instruction
instruction set. Clock system, Exceptions: Interrupts and resets. Functions and subroutines, Mixing C and assembly language, Interrupts, Interrupt service routines, Issues associated with interrupts, Low-power modes of operation. Module:2 ARM Cortex MX microcontroller 6 hours ARM Cortex M4: Assembly language basics, Thumb-2 Technology, ARM Instruction
subroutines, Mixing C and assembly language, Interrupts, Interrupt service routines, Issues associated with interrupts, Low-power modes of operation. Module:2 ARM Cortex MX microcontroller 6 hours ARM Cortex M4: Assembly language basics, Thumb-2 Technology, ARM Instruction
routines, Issues associated with interrupts, Low-power modes of operation. Module:2 ARM Cortex MX microcontroller 6 hours ARM Cortex M4: Assembly language basics, Thumb-2 Technology, ARM Instruction
Module:2ARM Cortex MX microcontroller6 hoursARM Cortex M4: Assembly language basics, Thumb-2 Technology, ARM Instruction
ARM Cortex M4: Assembly language basics, Thumb-2 Technology, ARM Instruction
ARM Cortex M4: Assembly language basics, Thumb-2 Technology, ARM Instruction
set, Cortex M4 architecture, advantages, peripherals, instruction set, floating point
operations, AdvancedCortex MX Microcontroller, core, architecture, on-chip wi-fi.
Module:3 Display and Communication 6 hours
modules
GPIO, LCD display, graphical display, relays, Peripheral programming SPI, I2C,
UART, Zigbeecontroller.
Module:4 Sensors interfacing 6 hours
Sensors interfacing techniques- Port Programming, ADC, SPI thermometer, I2C
thermometer, PWM generation and demodulation, DTH11, single wire thermometer,
Frequency counters.
Module:5 Microcontrollers for IoT 6 hours
ESP8266, NodeMCU, TI-CC3200, Access point and station point mode, HTTP,
MQTT,transmission and receiving, Intel-Gallileo boards.
Module:6 Single board computers 6 hours
Raspberry pi board, porting Raspbian, sensor interface examples, Python
programming for cloudaccess, sensor systems using Arduino boards
Module:7 Cloud interfacing 6 hours
Interfacing and data logging with cloud: Thing speak, Things board, Blync platform.
Module:8 Contemporary Issues 2 hours
Total Hours 45 hours
Text Book(s)
1. John H. Davies, "MSP430 Microcontroller Basics", 2011, 2 nd ed., Newnes

	publishing, NewYork.					
	3					
2.	1					
	Applications", 2014, 4 th ed., Springer, New York.					
Refe	Reference Books					
1.	1. Sergey Y. Yurish, "Digital Sensors and Sensor Systems: Practical Design",					
	2011, 1st ed., IFSApublishing, New York.					
2.	Jonathan W Valvano, "Introduction to ARM Cortex –M3 Microcontrollers",					
	2012, 5 th ed., Create Space publishing, New York.					
3.	Muhammad Ali Mazidi, Shujen Che	en, Sarn	nadNai	mi, SepehrNaimi, "TI ARM		
	Peripherals Programming and Inter					
	ed., Mazidi and Naimi publishing, N			e Language , Loto, L		
—						
Mod	de of Evaluation: CAT, Digital Ass	signmei	nts, Q	uiz, Online course, Paper		
bubl	olication, Projects, Hackathon/Makeath	าon and	FAT.			
'	, , ,					
Rec	commended by Board of Studies 0	7-06-20)23			
App	proved by Academic Council N	lo. 70	Date	24-06-2023		
	pproved by reducting obtaining 146. 76 Bate 2 1 66 2020					

Course Code	Course Title	L	Т	Р	С
MITS512P	Microcontrollers and Interfacing Lab	0	0	2	1
Prerequisite:	NIL	Sy	llabu	s Ver	sion
		1.0			

- 1. Introduce low power microcontrollers and to develop the skill set of programming lowpower sensing applications.
- 2. Impart the knowledge of various peripheral related to sensing and communication usingwired or wireless means.
- 3. Upgrade the students by introducing them Advanced ARM Cortex microcontrollers
- 4. Develop the skill set of students to build IoT systems and sensor interfacing.

Course Outcomes

- 1. Design and develop embedded programs for low power microcontrollers for sensor applications.
- 2. Develop ARM basic and advanced programs.
- 3. Interface and deploy analog and digital sensors
- 4. Develop communication system with sensor units
- 5. Design develop IoT systems using Wi-Fi CC3200.
- 6. Program the single board computers to read sensor data and posting in cloud.

Inc	dicative Experiments							
1.	, ,							
	Sub Task 1: Port programming of MSP430 microcontrollers							
	Sub Task 2: Analog to Digital Conversion using MSP430							
	microcontroller							
	Sub Task 3: LCD display of characters and numbers.							
	Sub Task 4: Timer							
2.	Working with ARM (Keil and energia)							
	Sub Task 1: Peripheral programming of ARM7 board							
	Sub Task 2: PWM generation							
	Sub Task 3:Configuring CC3200, wifi configuration, HTTP and							
	MQTTProtocol							
3.	Low power wireless transmission using Zigbee							
	Sub Task 1: Interfacing Zigbee controller with MSP 430							
	microcontrollerusing SPI/UART.							
	Sub Task 2: Programming sleep and wake up mode of MSP 430.							
4.	IoT systems							
	Working with Raspberry pi using Python.							
	Arduino platform							
	Working with open source clouds							
	Total Laboratory Hours 30 hours							

Text Book(s)						
1. John H. Davies, "MSP430 Microcontroller Basics",	2011, 2 nd ed., Newnes					
publishing, NewYork.						
Reference Books						
1. Sergey Y. Yurish,"Digital Sensors and Sensor Sys	stems: Practical Design",					
2011, 1st ed., IFSApublishing, New York.	G					
Mode of assessment: Continuous assessment / FAT / Oral examination and others						
Recommended by Board of Studies 07-06-2023						
Approved by Academic Council No. 70 Date 24-06-2023						

Course Code Course Title		L	Т	Р	С
MITS513L	TS513L Wireless Sensor Networks and Data		0	0	3
Communication					
Pre-requisite	NIL	Syllabus Version			
		1.0			

- 1. To identify and expose the students to the central elements in the design of communication protocols for the WSNs.
- 2. To disseminate the design knowledge in analyzing the specific requirements for applications in WSNs regarding energy supply, memory, processing, and transmission capacity
- 3. To get the perception of mobile ad hoc networks, design, implementation issues, and solutions based on different algorithms and protocols for power management, sensor data routing and query processing.
- 4. To associate, hardware platforms and software frameworks used to realize dynamic Wireless sensor network

Course Outcomes

- 1. Assess the applicability and limitations of communication protocols for a real time WSNapplication.
- 2. Confirms the behavior of mobile ad hoc networks (MANETs) and correlates the infrastructure-based networks.
- 3. Proactive in understating the routing protocols function and their implications on datatransmission delay and bandwidth.
- 4. Able to establish networks with an attempt to reduce issue of broadcast and flooding techniques.
- 5. Contribute appropriate algorithms to improve existing or to develop new wireless sensornetwork applications.
- 6. Familiarize the protocol, design requirements, suitable algorithms, and the state-of-the-art cloudplatform to meet the industrial requirement.
- 7. On a profound level to implement hardware & software for wireless sensor networks in day today life

Module:1	Network for embedded systems	6 hours			
RS232, RS48	5, SPI, I2C, CAN, LIN, FLEXRAY.				
Module:2	Embedded wireless communication and	6 hours			
	Protocols				
Bluetooth, Zig	bee, Wifi, MiWi, Nrf24, Wireless LAN &PAN, UWB				
Module:3	Wireless sensor network (WSN)	6 hours			
Characteristic	and challenges, WSN vs Adhoc Networks, Se	ensor node			
architecture, F	Physical layer and transceiver design considerations in WS	SNs, Energy			
usage profile,	Choice of modulation scheme, Dynamic modulation scalin	ng, Antenna			
considerations	S.				
Module:4	6 hours				
Fundamentals of MAC protocols - Low duty cycle protocols and wakeup concepts,					
Contention Basedprotocols, Schedule-based protocols - SMAC - BMAC, Traffic-					
adaptive medi	adaptive medium access protocol (TRAMA), The IEEE 802.15.4 MAC protocol.				
Module:5	Sensor Network Architecture	7 hours			

Data Dissemination, Flooding and Gossiping-Data gathering Sensor Network Scenarios, Optimization Goals and Figures of Merit, Design Principles for WSNs-Gateway Concepts, Need for gateway, WSNand Internet Communication, WSN

Tun	Tunneling						
Mod	Module:6 IP based WSN 6 hours						
Circ	uit switch	ing, packet switching, c	oncept of IF	PV4, IP	V6, 6LOWPA	N and IP, IP	
base	ed WSN,6	SLOWPAN based WSN.					
		Tiny OS				6 hours	
Tiny	OS for W	SN and IoT, M2M comm	nunication, <i>F</i>	Alljoyn	network		
Mod	lule:8	Contemporary Issue	S			2 hours	
	al Hours					45 hours	
	t Book(s)						
1.		Karl, Andreas Willig, '					
		Networks"2011, 1st ed.,					
2		eng, Abbas Jamalipour,				Networking	
		ctive",2014, 1 st ed., Wiley	y-IEEE Pres	ss, USA	١.		
	erence Be						
1.		egus W. Dargie, Christia					
	SensorNetworks: Theory and Practice", 2014, 1st ed., John Wiley & Sons,						
	New Jersey.						
2	2 Ian F. Akyildiz, Mehmet Can Vuran, "Wireless Sensor Networks", 2011,						
	1 st ed., JohnWiley & Sons, New Jersey.						
3	Zach Shelby, Carsten Bormann, "6LoWPAN: The Wireless Embedded						
Internet", 2009, 1sted., John Wiley & Sons, New Jersey.							
Mode of Evaluation: CAT, Digital Assignments, Quiz, Online course, Paper							
		rojects,Hackathon/Make					
		ed by Board of Studies					
App	roved by <i>i</i>	Academic Council	No. 70 E	Date 2	24-06-2023		

MITS514L Robotics and Control Systems 2 0 0 2 Pre-requisite NIL Syllabus version 1.0	Course Code Course Title			T	Р	С
	MITS514L	Robotics and Control Systems	2	0	0	2
1.0	Pre-requisite	NIL	Sylla	abus	vers	ion
				1.	0	•

- 1. To impart knowledge on performance specification, limitations and structure of controllers
- 2. To impart knowledge on design of controllers using root-locus and frequency domain techniques
- 3. To get an exposure on Robotic control systems and open source soft ware

Course Outcomes

- 1. Able to model the system and simulate the model.
- 2. Perform system analysis in time domain and frequency domain.
- 3. Analyze the system stability based on time domain, frequency domain and root locus techniques.
- 4. Develop digital control algorithms. Have a basic understanding of Robotics.
- 5. Have an understanding of the basic building blocks of robotic systems
- 6. Understand Dynamics of Robot control and path planning
- 7. Understand robot simulation and programming using ROS

Module:1 Time Domain Analysis and Design

3 hours

First order, Second order control system response for step, ramp and impulse inputs. characteristic equation -Poles and Zeroes concept- stability and Routh criterion

Module:2 Root Locus Techniques

3 hours

Review of root locus construction – Lead/ Lag compensator design using root locus.

Module:3 Frequency Response Techniques

3 hours

Bode plots and stability- gain and phase margins- Lead/ Lag compensator design using Bode plots.

Module:4 Analog and Digital Controllers

5 hours

P, PI, PD, PID Controller- Basic control action - Effects of Derivative, Integral control actions-Design of P, PI, PID controllers – Tunable PID Controllers – Ziegler – Nichols Methods for Controller Tuning, Fuzzy logic controllers.

Module:5 Robotics-Sensors and Actuators for Robotics

6 hours

Types of Robots-Robot components, classifications, and specifications. Mathematical Modeling of Robots, Robots as Mechanical Devices, Common Kinematic Arrangements, Robotic actuators: Electric-DC, Servo & Stepper, hydraulic and pneumatic actuators, Drives for motors. Sensors for localization, navigation, obstacle avoidance and path planning in known and unknown environments: Tactile sensors, Proximity and range sensors, Acoustic sensors, Vision sensor systems

Module:6 Kinematics, Dynamics and Path Planning

4 hours

Kinematics of manipulators: Representing Positions, Representing Rotations, Rotational Transformations, Composition of Rotations, Parameterizations of Rotations, Rigid Motions, Homogeneous transformations, Denavat – Hartenberg

representation, Inverse kinematics. The Configuration Space, Path Planning,						
Trajectory planning, SLAM						
Module:7 Robot Operating System	4 hours					
Introduction to ROS and Gazebo, setting up worksp.						
simulations – SLAM using turtlebots	accs, launering basic resolic					
Module:8 Contemporary Issues	2 hours					
module:0 Contemporary issues	Z IIOUI 3					
Total Hours	30 hours					
	30 11001 5					
Text Book(s)	2015 5th Do					
1 Katsuhiko Ogata, "Modern Control Engineering",	2015, 5" ed., Prentice Hall,					
New JerseyUSA.						
2 Mark W. Spong, Seth Hutchinson, M. Vidyas	agar, "Robot Modeling and					
Control", 2nd Edition, Wiley Publisher, 2020.						
Reference Books						
	Age International (p) Limited. New Delhi, India.					
2 Norman S Nise, "'Control systems engineering'	,2018, Wiley India edition,					
Wiley						
Richard Dorf, Robert Bishop,"Modern Control Systems", 2016, 13 th Edition,						
Pearson, India.						
4 R K Mittal. I.J.Nagrath, 'Robotics and control",2017,Mcgraw Hill education						
Mode of Evaluation: CAT, Digital Assignments, Quiz, Online course, Paper						
publication, Projects, Hackathon/Makeathon and FAT.						
passion, rejector advantementation and river						
Recommended by Board of Studies 07-06-2023						
Approved by Academic Council No. 70 Date 24-06-2023						

Course Code Course Title		L	T	Р	С
MITS614L	Deep Learning	3	0	0	3
Prerequisite:	NIL	Sy	llabus	s Vers	sion
		1.0			

- 1. To introduce the fundamental theory and concepts of machine learning and artificial intelligence
- 2. To provide a comprehensive foundation to artificial neural networks, neuro-modeling, and their applications to pattern recognition.
- 3. To explore the learning paradigms of supervised and unsupervised shallow/deep neural networks.
- 4. To provide exposure to the recent advances in the field of and facilitate in depth discussions on chosen topic
- 5. To impart adequate knowledge on deep learning frameworks and their applications to solving engineering problems

Course Outcomes

- 1. Gain knowledge about basic concepts of machine learning algorithms and identify machinelearning techniques suitable for the given problem.
- 2. Understand the differences between shallow neural networks and deep neural networks forsupervised and unsupervised learning.
- 3. Develop and train neural networks for classification, regression and clustering.
- 4. Understand the foundations of neural networks, how to build neural networks and learn how to leadsuccessful machine learning projects
- 5. Identify the deep feed forward, convolution and recurrent neural networks which are moreappropriate for various types of learning tasks in various domains
- 6. Implement deep learning algorithm and solve real world problems

Module:1 Foundations of Machine Learning-I

hour

Supervised and unsupervised learning, parametric vs non-parametric models, parametric models for classification and regression- Linear Regression, Logistic Regression, Naïve Bayes classifier, simple non-parametric classifier-K-nearest neighbour, support vector machines.

Module:2 Foundations of Machine Learning-II

5 hours

Clustering- distance based- K-means, density based, association rule mining, validation techniques- cross validations, feature selection and dimensionality reduction, principal component analysis-Eigenvalues, Eigen vectors, Orthogonality-challenges motivating deep learning

Module:3 Neural Networks for Classification and Regression

6 hours

ANN as a technique for regression and classification, structure of an artificial neuron, activation functions- linear activation, sigmoid and softmax. Feedforward neural networks- shallow model-single layer perceptron, multi-layer perceptron as complex decision classifier- learning XOR-Gradient based learning, Backpropagation algorithm, risk minimization, loss function, regularization, heuristicsfor faster training and avoiding local minima.

Module:4 Deep Feed Forward Neural Networks

6 hours

Feed forward neural networks- deep model- output units and hidden units, training deep models- hyper parameters and validation sets-cross validation, capacity, overfitting and under fitting, bias vs variance trade off, cross validation - vanishing

gradient problem, new optimization methods (adagrad, adadelta, rmsprop, adam),								
regularization methods (dropout, batch normalization, dataset augmentation), early								
stopping.								
	odule:5 Convolutional Neural Networks	7 hours						
	nvolution operation- kernel and feature map, sparse co							
	through parameter sharing, pooling function for invariant representation,							
conv	volution and pooling as strong prior, convolution wit	th stride, effect of zero						
pade	lding, single-channel and multi-channel data types use	ed in ConvNet, variants						
	pasic convolution- locally connected, tiled ConvNet-							
	thwise separable convolutions, fully connected layers							
	er patterns, layer sizing parameters, case studies LeN							
	odule:6 Recurrent Neural Networks	6 hours						
	quence learning with neural nets, unrolling the recurre							
	ection through time (BPTT), vanishing gradient proble							
	RU), Long short term memory (LSTM), Bidirectional LST							
	odule:7 Deep Learning Tools and Applications	8 hours						
	ols:TensorFlow, Keras, PyTorch, Caffe, Theano, MXNe							
	ection with RCNN - YOLO, SSD. Speech recognition w							
IVIOC	dule:8 Contemporary Issues	2 hours						
	al Hours	45 hours						
Tex	tt Book(s)	1						
	t Book(s) Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress	urville. "Deep learning"						
Tex	t Book(s) Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lear	urville. "Deep learning"						
1 2	t Book(s) Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lean Approach"O'Reilly Media Inc., 2017, USA.	urville. "Deep learning"						
Text 1 2 Refe	t Book(s) Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lean Approach"O'Reilly Media Inc., 2017, USA. Gerence Books	urville. "Deep learning" rning- A Practitioner's						
1 2 Refe	t Book(s) Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lean Approach"O'Reilly Media Inc., 2017, USA. ierence Books Bishop, C., M., Pattern Recognition and Machine Lea	rning- A Practitioner's						
7	Et Book(s) Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lean Approach"O'Reilly Media Inc., 2017, USA. Bishop, C., M., Pattern Recognition and Machine Lean Rich E and Knight K, "Artificial Intelligence", 2011, 2nd	rning- A Practitioner's arning, Springer, 2011 dec., TMH, New Delhi,						
1 2 Refe	Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lead Approach"O'Reilly Media Inc., 2017, USA. Bishop, C., M., Pattern Recognition and Machine Lead Rich E and Knight K, "Artificial Intelligence", 2011, 2nd Bengio, Yoshua. "Learning deep architectures for	rning- A Practitioner's arning, Springer, 2011 dec., TMH, New Delhi,						
1 2 Refe	Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lear Approach"O'Reilly Media Inc., 2017, USA. Erence Books Bishop, C., M., Pattern Recognition and Machine Lear Rich E and Knight K, "Artificial Intelligence", 2011, 2nd Bengio, Yoshua. "Learning deep architectures for trends inMachine Learning, 2(1)- 2009	rning- A Practitioner's arning, Springer, 2011 ded., TMH, New Delhi, Al- Foundations and						
7	Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lead Approach"O'Reilly Media Inc., 2017, USA. Bishop, C., M., Pattern Recognition and Machine Lead Rich E and Knight K, "Artificial Intelligence", 2011, 2nd Bengio, Yoshua. "Learning deep architectures for	rning- A Practitioner's arning, Springer, 2011 ded., TMH, New Delhi, Al- Foundations and						
Text 1 2 Refe 1. 2 3 4	Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lear Approach"O'Reilly Media Inc., 2017, USA. Ference Books Bishop, C., M., Pattern Recognition and Machine Lear Rich E and Knight K, "Artificial Intelligence", 2011, 2nd Bengio, Yoshua. "Learning deep architectures for trends inMachine Learning, 2(1)- 2009 Tom M. Mitchell, "Machine Learning", McGraw-Hill E	rning- A Practitioner's arning, Springer, 2011 d ed., TMH, New Delhi, Al- Foundations and Education (India) Pvt Ltd,						
Text	Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lear Approach"O'Reilly Media Inc., 2017, USA. Bishop, C., M., Pattern Recognition and Machine Lear Rich E and Knight K, "Artificial Intelligence", 2011, 2nd Bengio, Yoshua. "Learning deep architectures for trends inMachine Learning, 2(1)- 2009 Tom M. Mitchell, "Machine Learning", McGraw-Hill E 2013.	rning- A Practitioner's arning, Springer, 2011 d ed., TMH, New Delhi, Al- Foundations and Education (India) Pvt Ltd,						
Reference 1. 2 3 4 Mood publish	Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lear Approach"O'Reilly Media Inc., 2017, USA. Bishop, C., M., Pattern Recognition and Machine Lear Rich E and Knight K, "Artificial Intelligence", 2011, 2nd Bengio, Yoshua. "Learning deep architectures for trends inMachine Learning, 2(1)- 2009 Tom M. Mitchell, "Machine Learning", McGraw-Hill E 2013. de of Evaluation: CAT, Digital Assignments, Quiz, Mication, Projects, Hackathon/Makeathon and FAT.	rning- A Practitioner's arning, Springer, 2011 d ed., TMH, New Delhi, Al- Foundations and Education (India) Pvt Ltd,						
Reference 1. 2 3 4 Mood publication Records 1. Records 2. 3 1. 3 1. 3 1. 3 1. 3 1. 3 1. 3 1. 3	Bengio, Yoshua, Ian J. Goodfellow, and Aaron Co 2015, MITPress Josh Patterson and Adam Gibson, "Deep Lear Approach"O'Reilly Media Inc., 2017, USA. Bishop, C., M., Pattern Recognition and Machine Lear Rich E and Knight K, "Artificial Intelligence", 2011, 2 ⁿ Bengio, Yoshua. "Learning deep architectures for trends inMachine Learning, 2(1)- 2009 Tom M. Mitchell, "Machine Learning", McGraw-Hill E 2013. de of Evaluation: CAT, Digital Assignments, Quiz, dication, Projects, Hackathon/Makeathon and FAT.	rning- A Practitioner's arning, Springer, 2011 d ed., TMH, New Delhi, Al- Foundations and Education (India) Pvt Ltd,						

Course Code Course Title				Р	С
MITS514P Robotics and Control Systems Lab			0	2	1
Prerequisite:	NIL	Syll	labus	vers	ion
			1.	0	

- 1. To impart knowledge on performance specification, limitations and structure of controllers
- 2. To impart knowledge on design of controllers using root-locus and frequency domain techniques

Course Outcomes

- 1. Realize the need of control system and its recent developments. Able to model the system and simulate the model.
- 2. Analyze the behavior of the first and second order systems in time domain and frequency domain.
- 3. Analyze the system stability based on time domain, frequency domain and root locus techniques.
- 4. Identify the need for incorporating the three term controller based on the customized requirement of the control action
- 5. Analyze the systems behavior in digital domain and develop digital control algorithm for the corrective action.
- 6. Design and development of Bot control and mapping algorithms using ROS.

Indi	cative Experiments					
1.	Speed measurement and regulation of DC motor using armature control system					
2.	Speed regulation and torque measurement of AC Servomotor using armature control system					
3.	Modeling and performance analysis of stepper motor position control system					
4.	Performance analysis of BLDC motor control system and its parameter estimation					
5.	Step response analysis of second order system using Matlab					
6.	Installing ROS (Robotics operating system) and initializing catkin workspace					
7.	Creating an environment in Gazebo					
8.	Launching Turtlebots and manual mapping in Gazebo					
9.	Autonomous Navigation of Turtlebots in Gazebo					
10.). Implementing SLAM in custom environments					
	Total Laboratory Hours 30 hours					
Tex	t Book(s)					
1.	M. Gopal "Modern Control System Theory", 2014, 2 nd ed. New Age International, NewDelhi, India.					
	Mark W. Spong, Seth Hutchinson, M. Vidyasagar, "Robot Modeling and Control", 2nd Edition, Wiley Publisher, 2020.					

Refe	Reference Books					
1.	M. Gopal,"Digital control and sta	te variable m	nethods", 20	12, 4 th ed.,		
	Tata McGraw Hill, USA.					
2.	Webb & Reis, "Programmable Lo	ogic Controlle	er - Principle	s and		
	Applications", 2012, 5thed., PHI, I	New Delhi, Ind	dia.			
3.	I. J. Nagrath and M. Gopal, "Cor			g", 2017, 6 th		
	Ed., New AgeInternational (p) Li	mited. New D	elhi, İndia.			
Mod	Mode of assessment: Continuous assessment / FAT / Oral examination and others					
Rec	Recommended by Board of Studies 07-06-2023					
App	roved by Academic Council	No. 70	Date	24-06-2023		

Course Code	Course Title	L	Т	Р	С
MITS615L	Web Design and Development	3	0	0	3
Pre-requisite	NIL	Sylla	bus	ver	sion
			1	.0	

- 1. To acquire specific scripting knowledge to develop interactive applications.
- 2. To understand the basics of android application development.
- 3. To apply the programming skills in developing application pertaining to Industrial, medical, agricultural, etc.

Course Outcomes:

- 1. Design dynamic web forms to acquire and process user & sensor data
- 2. Interactive forms using Java Script with a focus on internet of things
- 3. Implement mobile application using android SDK
- 4. Solve the need for smart systems in a distributed environment
- 5. Understand the IoT architecture and building blocks for various domains
- 6. Devise multidisciplinary case to case modelling and execute wide range of application

Module:1 Markup Language

7 hours

Introduction to Markup language, HTML document structure, HTML forms, Style (CSS), Multiple CSS stylesheets, DHTML, Tools for image creation and manipulation, User experience design, IoT development using charts

Module:2 Scripting Language

6 hours

Introduction to JavaScript, Functions, DOM, Forms, and Event Handlers, Object Handlers, Input validation, J2ME, application design using J2ME, IoT development using Real time rules, platforms, alerts

Module: 3 Android Programing Framework

6 hours

Mobile app development: Android Development environment, Simple UI Layouts and layout properties, GUI objects, Event Driven Programming, opening and closing a Database

Module:4 Industrial Internet Application

6 hours

IIoT Fundamentals and Components, Industrial Manufacturing, Monitoring, Control, Optimization and Autonomy, Introduction to Hadoop and big data analytics

Module:5 Applications in agriculture

6 hours

Smart Farming: Weather monitoring, Precision farming, Smart Greenhouse, Drones for pesticides.

Module:6 Applications in IoT enabled Smart Cities

6 hours

Energy Consumption Monitoring, Smart Energy Meters, Home automation, SmartGrid and Solar Energy Harvesting, Intelligent Parking, Data lake services scenarios.

Module:7 Healthcare applications

6 hours

Architecture of IoT for Healthcare, Multiple views coalescence, SBC-ADL to construct the system architecture. Use Cases: Wearable devices for Remote monitoring of

Physiologicalparameter, ECG, EEG, Diabetes and Blood Pressure.							
Module:8	2 hours						
	Total Lecture hours:	45 hours					
Text Book	(s)						
1.	John Dean, Web Programming with HTML5, CSS and Ja						
	2018, Jonesand Bartlett Publishers Inc., ISBN-10: 97812840	91793					
2.	DiMarzio J. F., Beginning Android Programming with And	roid					
	Studio, 2016, 4 th ed., Wiley, ISBN-10: 9788126565580						
Reference							
1.	Fadi Al-Turjman, Intelligence in IoT- enabled Smart Cities, 2019,						
	1 st edition, CRCPress,ISBN-10: 1138316849						
2.	Giacomo Veneri, and Antonio Capasso, Hands-on Industrial Internet						
	of Things: Create a powerful industrial IoT infrastructure using						
	Industry 4.0, 2018, Packt Publishing.						
3.	Subhas Chandra Mukhopadhyay, Smart Sensing Technology						
	for Agriculture and Environmental Monitoring, 2012, Springer,						
ISBN-10: 3642276377							
Mode of Evaluation: CAT / Assignment / Quiz / FAT							
Recommended by Board of Studies 07-06-2023							
Approved b	by Academic Council No. 70 Date 24-06-2023						

Course Code	Code Course Title			Р	С		
MEDS501L	L Embedded System Design				3		
Pre-requisite	NIL Sy	llab	us v	ers'	ion		
1.0							
Course Objectives							

The course aimed at

- 1. Ability to understand comprehensively the technologies and techniques underlying in building an embedded solution to a wearable, mobile and portable system.
- 2. Analyze UML diagrams and advanced Modelling schemes for different use cases.
- 3. Understand the building process of embedded systems

Course Outcome

The students will be able to

- 1. Define an embedded system and compare with general purpose system.
- 2. Appreciate the methods adapted for the development of a typical embedded system.
- 3. Get introduced to RTOS and related mechanisms.
- 4. Classify types of processors and memory architecture
- 5. Differentiate the features of components and networks in embedded systems
- 6. Develop real-time working prototypes of different small-scale and medium-scale embedded Systems.
- 7. Apprehend the various concepts in Multi-Tasking

Module:1 Introduction to Embedded System 5 hours Embedded system processor, hardware unit, software embedded into a system, Example of an embedded system, Embedded Design life cycle, Layers of Embedded Systems. Module:2 Embedded System Design Methodologies Embedded System modelling [FSM, SysML, MARTE], UML as Design tool, UML notation. Requirement Analysis and Use case Modelling, Design Examples Module:3 Building Process For Embedded Systems 4 hours Preprocessing, Compiling, Cross Compiling, Linking, Locating, Compiler Driver, Linker Map Files, Linker Scripts and scatter loading, Loading on the target, Embedded File System. Module:4 | System design using general purpose 7 hours processor Microcontroller architectures (RISC, CISC), Embedded Memory, Strategic selection of processor and memory, Memory Devices and their Characteristics, Cache Memory and Various mapping techniques, DMA. Module:5 | Component Interfacing & Networks 9 hours Memory Interfacing, I/O Device Interfacing, Interrupt Controllers, Networks for Embedded systems- USB, PCI, PCI Express, UART, SPI, I2C, CAN, Wireless Applications - Bluetooth, Zigbee, Wi-Fi., 6LoWPAN, Evolution of Internet of things (IoT). Module:6 | Operating Systems 7 hours Introduction to Operating Systems, Basic Features & Functions of an Operating System, Kernel & its Features [polled loop system, interrupt driven system, multi rate system], Processes/Task and its states, Process/Task Control Block, Threads, Scheduler, Dispatcher. Module:7 | Multi Tasking Context Switching , Scheduling and various Scheduling algorithms, Inter-process Communication (Shared Memory, Mail Box, Message Queue), Inter Task Synchronization (Semaphore, Mutex), Dead Lock, Priority Inversion (bounded and unbounded), Priority Ceiling Protocol & Priority Inheritance Protocol Module:8 Contemporary Issues 2 hours **Total Lecture hours:** 45 hours

Text Book(s) Raj Kamal, "Embedded systems Architecture, Programming and Design", Tata McGraw- Hill, 2016. Wayne Wolf "Computers as components: Principles of Embedded Computing System Design", The Morgan Kaufmann Series in Computer Architecture and Design, 2013. Reference Books Lyla B. Das," Embedded Systems an Integrated Approach", Pearson Education, 2013. Shibu K V," Introduction to Embedded Systems", McGraw Hill Education(India) Private Limited, 2014 Sriram V Iyer, Pankaj Gupta " Embedded Real Time Systems Programming", Tata McGraw- Hill, 2012 Steve Heath, "Embedded Systems Design", EDN Series, 2013. Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final

28-07-2022

No. 67

Date

08-08-2022

Assessment Test

Recommended by Board of Studies

Approved by Academic Council

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Proceedings	of the	6/th	Academic	Council	(08.08.	20221

Course Code	Course Title	L	Т	Р	С
MEDS601L	Electromagnetic Interference and Compatibility	3	0	0	3
Pre-requisite	NIL	Syl	labus	vers	ion
			1	.0	

The course is aimed at:

- 1. Imparting knowledge about EMI environment
- 2. Teaching EMI coupling principles, EMI control techniques and design of PCBs for EMC
- 3. Giving exposure to EMI Standards, Regulations and Measurements

Course Outcomes

At the end of the course, the student will be able to

- 1. Understand terminologies of EMI and EMC
- 2. Analyze and understand various EMI coupling mechanisms
- 3. List various EMI Test and Measurement methods
- 4. Analyze various techniques needed to suppress EMI
- 5. Perceive different EMC regulations followed worldwide
- 6. Ability to design an Electromagnetic Compatible systems.
- 7. Analyze and comprehend different techniques needed for Signal Integrity and ability to understand various models for EMI/EMC

Module:1EMI Environment4 hoursEMI-EMC Definitions and units of Parameters, Sources of EMI, conducted and radiated EMI, Transient EMIModule:2EMI Coupling Mechanisms6 hoursConducted, Radiated and Transient Coupling, Common Coupling, Radiated Common Mode and Ground Loop Coupling, Radiated Differential Mode Coupling, Near Field Cable to Cable Coupling, Power Mains and Power Supply Coupling.Coupling, Power Mains and ShoursModule:3EMI Test and Measurements8 hours

EMI Specification / Standards / Limits: Units of specifications, Civilian standards Military standards. EMI Test Instruments / Systems, EMI Test, EMI Shielded Chamber, Open Area Test Site, TEM Cell Antennas, Conductors Sensors/Injectors/Couplers. EMI Measurement Methods: Military Test Method and Procedures, Calibration Procedures, Modeling interferences

Module:4 EMI Control Techniques

7 hours

Shielding, Filtering, Grounding, Bonding, Isolation Transformer, Transient Suppressors, Cable Routing, Signal Control, Component Selection and Mounting, Electrostatic discharge protection schemes

Module:5 EMC Standards and Regulations

5 hours

National and Intentional standardizing organizations- FCC, CISPR, ANSI, DOD, IEC, CENEEC, FCC CE and RE standards, CISPR, CE and RE Standards, IEC/EN, CS standards, SAE Automotive EMC standard, Frequency assignment - spectrum conversation.

Module:6 | System Design for EMC

8 hours

PCB Traces Cross Talk, Impedance Control, Power Distribution Decoupling, Zoning, Motherboard Designs and Propagation Delay Performance Models,

System Enclosures, Power line filter placement, Interconnection and Number of Printed Circuit Boards, PCB and subsystem decoupling								
	Module:7 Signal Integrity and EMI/EMC Models 5 hours							
Effe	Effect of terminations on line wave forms, Matching schemes for Signal Integrity,							
Effe	ects of li	ne discontinuities, Statistica	al EMI/EN	/IC mode	ls.			
Мо	dule:8	Contemporary Issues				2 hours		
Gu	est Lecti	ires from Industry and, Re	search ar	nd Develo	pment	Organizations		
			Total I	Lecture I	nours:	30 hours		
Text Book(s)								
1. Clayton R. Paul,IntroductiontoElectromagneticcompatibility,2010, 2 edition., Wiley & Sons, New Jersey								
Reference Books								
1.	1. HenryW.ott, Electromagnetic Compatibility Engineering, 2011, 1sted. John							
	Wiley and Sons, NewJersey.							
2.	Patrick G. André and Kenneth Wyatt, EMI Troubleshooting Cookbook for							
Product Designers 2014, 1st ed., SciTech Publishing, New Jersey								
Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final								
Assessment Test								
Recommended by Board of Studies 07-06-2023								
Apı	Approved by Academic Council No. 70 Date 24-06-2023							

Course Code	Course Title	L	Т	Р	С
MEIC506L	Wireless Communications	3	0	0	3
Pre-requisite	NIL	Syllabus version		ion	
		1.0			

- 1. To understand the different technologies in wireless communication systems.
- 2. To analyze the concepts of physical layer transmission techniques.
- 3. To Design and infer on next-generation wireless communication systems.

Course Outcomes

Students will be able to

- 1. Describe the evolution of different wireless communication systems and standards.
- 2. Analyze the mobile radio propagation, fading, and the channel modeling.
- 3. Interpret code division multiple-access techniques for wireless communications.
- 4. Apply the power and rate control methods in OFDM and OTFS.
- 5. Analyze the modern multi-antenna communication systems.
- 6. Explain the future wireless communications technologies.

Module:1 Evolution of Wireless Communications 4 hours Introduction to wireless communications, Evolution of modern wireless communication systems- 2G/3G/4G/5G, Types of services, Requirement for the services, Spectrum limitations, Noise and interference limited systems, Multiple access schemes.

Module: 2 Wireless Propagation Channels

6 hours

Large scale propagation-Propagation effects, Reflection, Diffraction and scattering, Free space propagation model, Two-ray ground reflection model, Log-distance path loss model, Log-normal shadowing, Outdoor propagation models, Okumura model, Hata model, COST-231, Link power budget analysis, Small Scale Propagation-Parameters of mobile multipath channels, Types of small scale fading, Rayleigh and Rician distributions, Jakes Doppler spectrum.

Module:3 Code-Division Multiple Access

6 hours

Introduction to CDMA, Mechanism, Spreading codes, Multi-user CDMA, Advantages of CDMA, CDMA forward and reverse channels, Soft handoff, CDMA features, Power control, Performance analysis of CDMA system.

Module:4 | OFDM and OTFS

8 hours

Principle of orthogonal frequency division multiplexing (OFDM) - Implementation of transceivers, Cyclic prefix, Peak-to-Average Power Ratio (PAPR), Inter carrier interference, BER analysis of OFDM, Orthogonal time frequency spreading (OTFS), Signal representation, Implementation as overlay, Diversity and channel gain.

Module:5 Massive MIMO

8 hours

MIMO system model, MIMO Configurations - SISO, SIMO, MISO, MIMO, Diversity combining techniques, Selection combining (SC), Maximal Ratio Combining (MRC) and Switch-and-Stay Combining (SSC), Diversity gain, MIMO receivers – Zero-Forcing (ZF), Minimum Mean Square Error (MMSE), Coding techniques -Alamouti,

STBC, Beamforming techniques, Spatial Multiplexing, Multi-user MIMO-advantages and challenges, receivers, Massive MIMO- Channel model, Channel hardening, Matched filter receiver, Pilot contamination.

Module:6 Key Wireless Communication Technologies 6 hours

Cooperative communications-Fundamentals of Relaying, Relaying with Multiple and
Parallel Relays, Applications. Device-to-Device Communications - Advanced
Interference Processing, Non-orthogonal multiple access (NOMA)-Power domain,
Code domain, Interference alignment, Radio wave propagation for mmWave Large-scale and Small-scale propagation channel effects, Applications of mmWave
Communications.

Module:7 5G and B5G -New Radio

5 hours

5G System Overview - Physical Layer, Logical channels, Procedures - Carrier Aggregation and License-Assisted Access, Coordinated multipoint (CoMP), Dual Connectivity, and HetNet Support, Beyond 5G applications, Network Design, Spectrum Usage, Physical and MAC Layer Aspects, Real-Time Processing and RF Transceiver Design.

Module:8 | Contemporary Issues

2 hours

Guest Lecture from Industries and R & D Organizations

Total Lecture hours: 45 h

45 hours

Text Book(s)

- 1. Andreas F. Molisch, Wireless Communications: From Fundamentals to Beyond 5G, 2022, 3rd Edition, Wiley-IEEE Press. USA ISBN: 978-1-119-11720-9.
- 2. Feng Ouyang, Digital Communication for Practicing Engineers, 2019. 1st Edition, Wiley-IEEE Press, USA, ISBN: 978-1-119-41800-9.

Reference Books

- 1. Suvra Sekhar Das, Ramjee Prasad. OTFS: orthogonal time frequency space modulation a waveform for 6G, 2021, River Publishers, Denmark, ISBN: 978-8770226561.
- 2. Emil Björnson, Jakob Hoydis and Luca Sanguinetti, Massive MIMO Networks: Spectral, Energy, and Hardware Efficiency, 2017, Foundations and Trends® in Signal Processing, Now publishers, Netherlands, ISBN: 978-1-68083-985-2.
- 3. Theodore S. Rappaport, Robert W. Heath, Robert C. Daniels, James N. Murdock, Millimeter Wave Wireless Communications, 2021, 1st edition, Pearson, UK, ISBN-13: 9780132172288.
- 4. John W. Leis, Communication Systems Principles Using MATLAB, 2018, 1st Ed., Wiley-IEEE Press, USA, ISBN: 978-1-119-47067-0.

Mode of Evaluation: Continuous Assessment Test, Digital Assignment, Quiz, Final Assessment Test

Recommended by Board of Studies	07-06-2023		
Approved by Academic Council	No. 70	Date	24-06-2023

Course Code	Course Title	L	Т	Р	С
MITS601L	Flexible and Wearable Sensors	3	0	0	3
Prerequisite:	NIL	Syllabus version			on
		1.0			

- 1. To provide the overview of flexible electronics technology and the issues with materials processing for thin film electronics.
- 2. To expose the students for the materials selection and patterning methods for thin film electronics development.
- 3. To describe the process involved in transferring the flexible electronics from foils to textiles and also the challenges, opportunities and the future of wearable devices.
- 4. To expose the students to the design, challenges of wearable sensors employed for sensing the physical and biological parameters and the process involved in the conversion of conducting and semiconducting fibers to smart textiles.

Course Outcome:

- 1. Realize the technology developments in the flexible electronics technology.
- 2. Ability to identify the suitable materials and its processing for the development of thin filmelectronics
- 3. Ability to design the pattern and develop with suitable patterning methods.
- 4. Realize the process involved in the transformation of electronics from foils to textiles
- 5. Acquire the design knowledge for developing wearable sensors for physical and chemicalparameters
- 6. Gain the competency in transferring the conducting and semiconducting fibers to smarttextiles

Module:1 Overview of flexible electronics technology 5 hours

History of flexible electronics - Materials for flexible electronics: degrees of flexiblility, substrates, backplane electronics, front plane technologies, encapsulation - Fabrication technology for flexible electronics - Fabrication on sheets by batch processing, fabrication on web by Roll-to-Roll processing - Additive printing.

Module:2 Amorphous and nano-crystalline silicon 7 hours materials and Thin film transistors

Fundamental issues for low temperature processing - low temperature amorphous and nano- crystalline silicon - characteristics of low temperature dielectric thin film deposition – low temperature silicon nitride and silicon oxide characteristics - Device structures and materials processing - Device performance - Contacts for the device - Device stability.

Module:3 Materials and Novel patterning methods for flexible 7 hours electronics

Materials considerations for flexible electronics: Overview, Inorganics semiconductors and dielectrics, organic semiconductors and dielectrics, conductors - Print processing options for device fabrication: Overview, control of feature sizes of jet printed liquids, jet printing for etch mask patterning, methods for minimizing feature size, printing active materials.

Module:4 Flexible electronics from foils to textiles 6 hours

Introduction -Thin film transistors: Materials and Technologies - Review of semiconductors employed in flexible electronics - Thin film transistors based on IGZO - Plastic electronics for smart textiles - Improvements and limitations.

Module:5 Wearable haptics 6 hours

World of wearables - Attributes of wearables - Textiles and clothing: The meta wearable - Challenges and opportunities - Future of wearables - Need for wearable haptic devices - Categories of wearable haptic and tactile display.

Module:6 Wearable Bio, Chemical and Inertial sensors 6 hours

Introduction-Systems design - Challenges in chemical and biochemical sensing - Application areas -Wearable inertial sensors - obtained parameters from inertial sensors - Applications for wearable motion sensors - Practical considerations for wearable inertial sensor - Application in clinical practice and future scope

Module:7 Knitted electronic textiles

6 hours

From fibers to textile sensors - Interlaced network -Textile sensors for physiological state monitoring - Biomechanical sensing - Noninvasive sweat monitoring by textile sensors and other applications. FBG sensor in Intelligent Clothing and Biomechanics.

Module:8	Contemporary Issues	2 hours
	Total Lecture hours:	45 hours

Text Book(s)

- 1. Michael J. McGrath, Cliodhna Ni Scanaill, Dawn Nafus, "Sensor Technologies: Healthcare, Wellness and Environmental Applications", 201, 1st Edition, Apress Media LLC, New York.
- 2. William S. Wong, Alberto Salleo, Flexible Electronics: Materials and Applications, 2011, 1stEdition, Springer, New York.

Reference Books

- 1. Edward Sazonov, Michael R. Newman, "Wearable Sensors: Fundamentals, Implementationand Applications", 2014, 1st Edition, Academic Press, Cambridge.
- 2. Kate Hartman, "Make: Wearable Electronics: Design, prototype, and wear your owninteractive garments", 2014, 1st Edition, Marker Media, Netherlands.
- 3. Guozhen Shen, Zhiyong Fan, "Flexible Electronics: From Materials to Devices", 2015, 1stEdition, World Scientific Publishing Co, Singapore.
- Yugang Sun, John A. Rogers, "Semiconductor Nanomaterials for Flexible Technologies: From Photovoltaics and Electronics to Sensors and Energy Storage (Micro and Nano Technologies)', 2011, 1st Edition, William Andrew, New York.

Mode of Evaluation: CAT / Assignment / Quiz / FAT				
Recommended by Board of Studies	28-07-2022			
Approved by Academic Council	No. 67	Date	08-08-2022	

Course Code	Course Title	L	Т	Р	С
MITS603L	Chemical and Environmental Sensor	3	0	0	3
Pre-requisite:	NIL	Syllabus Version		rsion	
		1.0			

- 1. To extend engineering principles to electrochemical sensor development with a clearunderstating of oxidation and reduction of an electrolytic cell.
- 2. To propound the conception of ion selective and enzyme stabilized electrodes for the detection of chemical and biomolecules.
- 3. To be expedient in applying specific interaction methods in the recognition of ion selectivegases using metal oxide based sensors.
- 4. Ability to analyze the modes of vibration and develop the suitable mass and thermalsensitive sensors.

Course Outcomes

- 1. Realize the need for half-cell and to analyze potential developed in any electrochemical cell. Apply the same for ion selective measurement
- 2. Be familiar with a wide range of chemical sensing methods and material characteristics tobe applied in biosensors.
- 3. Ability to design gas sensors for commercial and industrial applications.
- 4. Gain knowledge of nanomaterials for biological and medical applications
- 5. Able to discuss, develop and apply site specific antigen-antibody sensors design for mostcommon diseases like metabolic disorders

 Evaluate process design criteria for gas treatment and air quality analysis

Module:1 Electrochemistry

7 hours

Thermodynamics, , Enthalpy, Entropy, Gibbs free Energy, Law of Mass Action, simple Galvanic Cells, Electrode – Electrolyte Interface, Fluid Electrolytes, Dissociation of Salt, Solubility Product, Ion Product, pH Value, Ionic Conductivity, Ionic Mobility, Phase Diagrams.

Module:2 Transduction Principles

6 hours

Transduction Elements- Electrochemical Transducers-Introduction Potentiometry and Ion-Selective Electrodes: The Nernst Equation Voltametry and amperometry, conductivity, FET, Modified Electrodes, Thin-Film Electrodes and Screen-Printed electrodes, photometri sensors

Module:3 Chemical Sensing Elements

6 hours

Ionic recognition, molecular recognition-chemical recognition agent, spectroscopic recognition, biological recognition agents. Immobilization of biological components, performance factors of Urea Biosensors, Amino Acid Biosensors, Glucose Biosensors and Uric Acid, factors affecting theperformance of sensors.

Module:4 Potentiometric and Amperometric Sensors

6 hours

Potentiometric- Ion selective electrodes- pH linked, Ammonia linked, CO2 linked, Silver sulfide linked, Iodine selective, amperometric -bio sensors and gas sensors, Amperometric enzyme electrodes: substrate and enzyme activity, Detection mode and transduction method, mediated and modified electrodes, pH glass and ion selective electrodes, solid state and redox electrodes,

Module	e:5	Optical E	Biosensor and Immu	nunosensors Biosensor			6 hours		
Fiber	optic	biosenso	or, Fluorophore	and	chromophore	based	d biosensor,		
Biolumi	inescer	ice and	chemiluminescence	based	biosensors, N	lon lable	ed and labled		

immune sensors, Microbial Biosensors: electrochemical, photomicrobial, Microbial thermistor. Application of microbial biosensors in glucose, ammonia, acetic acid, alcohol, BOD, methane sensing Module:6 Sensors in exhaust gas treatment 6 hours Engine combustion process, Catalytic exhaust after treatment, Emission limits, Exhaust sensors and Enginecontrol, Emission test cycles, On-board diagnose (OBD): Diagnose Strategies, Exhaust sensors for OBD, Control Sensors: Hydro-Carbon Sensors, NOx-Sensors, Temperature Sensors, Oxygen Sensors. Module:7 Measurement techniques for air quality 6 hours Measurement techniques for particulate matter in air. Specific gaseous pollutants analysis and control- Measurement of oxides of sulphur, oxides of nitrogen unburnt hydrocarbons, carbon-monoxide, dust mist and fog. Module:8 **Contemporary Issues** 2 hours

		Total Lecture:	45 hours
Text E	Book(s)		
1.	Janata, Jiri,"Principles of Chemical s	ensors", 2014, 2 nd edition, Spring	er, New York.
Refere	ence Book(s)		
1.	Brian R Eggins, "Chemical Senso 2010, 1 st edition, John Wiley Sons Lt		nTS Series),
2.	Peter Grundler, "Chemical Sensors 2011, 1 st edition, Springer, New York		d Engineers",
3.	R.G.Jackson, "Novel Sensors and Institute ofPhysics.	d Sensing", 2012, 1 st edition,	Philadelphia
4.	Florinel-Gabriel Banica "Chemica Fundamentals and Applications" 20		ew Jersey.
5.	M. Campbell, "Sensor Systems Two:Environmental Monitoring", 201	for Environmental Monitorir 1, 1 st Edition, Springer, New York	ng: Volume
Mode	of Evaluation: CAT / Assignment / Qu	iz / FAT	
Recon	nmended by Board of Studies	28-07-2022	

No. 67

Date

08-08-2022

Approved by Academic Council

Course Code	Course Title	L	Т	Р	С
MITS604L	Cloud and Fog Computing	3	0	0	3
Prerequisite	NIL	Sylla	Syllabus Version		
		1	.0		

The course is aimed to

- 1. Introduce cloud computing and enabling technologies
- 2. Explore the need for fog and edge computation
- 3. Impart the knowledge to log the sensor data and to perform further data analytics

Course Outcome:

At the end of the course student will be able to

- 1. Deploy their data in the cloud for simple applications
- 2. Apply the analytics in cloud to extract information
- 3. Appreciate and deploy fog data processing layers
- 4. Integrate sensor data to cloud through fog computation layers
- 5. Understand and implement edge computation
- 6. Develop edge analytics using python and tensor flow
- 7. Perform data pushing and processing in commercial clouds.

Module 1CloudComputingbasicsandenablingtechnologies7 hoursBasics of cloud computing-Need for clouds- concepts and models: Roles and boundaries –
Cloud characteristics – Cloud delivery models – Cloud deployment models. Broadband
Networks and Internet Architecture – Data Center Technology – Virtualization Technology.

Module 2 Cloud Virtualisation

6 hours

Server oriented – Virtual Machines (IaaS), Modern Serverless Configurations- Functions/ (PaaS)Lambda functions – App, Biz function, logics, data ingestion (elasticity, scalability – on demand) DB services, Analytics services (SaaS).

Module 3 Cloud Application Development in Python

6 hours

Python for Cloud: Amazon Web Services – Google Cloud – Windows Azure. Python forMapReduce.

Module 4 | Federated Cloud Service Management and IoT

6 hours

Cloud Service management (federated) —Cloud Life Cycle-service and management-Cloudarchitectures -Self organizing cloud architectures

Module 5 | Fog computing

6 hours

Need for Fog computation, Fog data processing layers – Security and Identity Management – Business process integration – Big data interfaces – Wireless sensors and actuators, Fog in 5G, Architecture Harmonization Between Cloud Radio Access Networks and Fog Networks, Fog applications.

Module 6 | Fog and edge computing

6 hours

Need for edge computation-Edge computing architectures, Device registration, Remote diagnostics, SW update, Geo distributed computing-concept of cloud orchestration, Edge Networks (Low bandwidth networks/ Security/ protcols). WAN vs Low bandwidth networks.

Module 7	Overview of Edge Data Analytics tools	6 hours
Python adv	/ance libraries(Pandas, Scikit Learn), Tensor flow and Yolo	
Module 8	Contemporary Issues	2 hours

				Tota	al Lecture:	45 hours
Text	Books	:				
1.	Thom	nas Erl, Zaigham Mahmoo	d, and Ric	ardo Puttini,	"Cloud Con	nputing:
	Conc	epts,Technology & Architectu	ure", Arcitura	a Education, 20	013.	
2.	Arsho	leep Bahga, Vijay Madisetti, '	"Cloud Com	puting: A Hand	ds-on Approa	ach", 2013.
3.		u Vermesan, Peter Friess,		•	rom Resear	ch and
		ation toMarket Deployment",				
4.		ael Missbach, Thorsten S				
	Robe	rt_Madl,Mark Tempes, Georg	ge Andersor	n, "SAP on Clo	ud", Springe	r, 2016.
5		Mutumba Bilay , Peter Gutso				
		orm Integration: The Compre	ehensive Gu	uide", Rheinwe	erg publishin	g, 2 nd edition,
	2019,					
Refe	erence	Books:				
1.	Honb	o Zhou, "The Internet of Thi	ngs in the	Cloud: A Middl	leware Pers	pective", CRC
	Press	s, 2012.				
2.	SC.	Hung et al.: Architecture	Harmoniza	ation Between	Cloud RA	Ns and Fog
		orks, IEEE Access: The Jo	urnal for ra	pid open acce	ess publishi	ng, Vol.3, pp:
	3019	<i>–</i> 3034, 2015.				
Mod	le of Ev	valuation: CAT / Assignment	/ Quiz / FAT	-		
Rec	Recommended by Board of Studies 28-07-2022					
App	roved l	oy Academic Council	No. 67	Date	08-08-2022	

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Course Code	Course Title	L	Т	Р	С	
MITS605L	IoT Security and Trust	3	0	0	3	
Pre-Requisite:	NIL	Sylla	bus	Vers	sion	
			1.0			
Objectives:						
To impart the	knowledge and technical skills in designing secured	d and	trus	table	loT	
systems.						
Outcome:						

At the end of the course students will be able to

- 1. Design and implement cryptography algorithms using C programs
- 2. Solve network security problems in various networks
- 3. Build security systems using elementary blocks
- 4. Build Trustable cloud based IoT systems
- 5. Solve IoT security problems using light weight cryptography
- 6. Appreciate the need for cyber security laws and methods.

Module 1 Fundamentals of encryption for cybersecurity.

Cryptography – Need and the Mathematical basics- History of cryptography, symmetric ciphers, block ciphers, DES - AES. Public-key cryptography: RSA, Diffie-Hellman Algorithm, Elliptic Curve Cryptosystems, Algebraic structure, Triple Data Encryption Algorithm (TDEA) Blockcipher,

Module 2 | IoT security framework

IIOT security frame work, Security in hardware, Bootprocess, OS & Kernel, application, run time environment and containers. Need and methods of Edge Security, Network Security: Internet, Intranet, LAN, Wireless Networks, Wireless cellular networks, Cellular Networks and VOIP.

Module 3 | Elementary blocks of IoT Security & Modelsfor Identity 6 Hours Management

Vulnerability of IoT and elementary blocks of IoT Security, Threat modeling - Key elements. Identity management Models and Identity management in IoT, Approaches using User-centric, Device-centric and Hybrid.

Module 4 Identity Management and Trust Establishment

6 Hours

Trust management lifecycle, Identity and Trust, Web of trust models. Establishment: Cryptosystems – Mutual establishment phases – Comparison on security analysis. Identitymanagement framework.

Module 5 Access Control in IoT and light weightcryptography

6 Hours

Capability-based access control schemes, Concepts, identity-based and identity-driven, Lightweight cryptography, need and methods, IoT use cases

Module 6 Security and Digital Identity in CloudComputing 6 Hours

Cloud security, Digital identity management in cloud, Classical solutions, alternative solutions, Management of privacy and personal data in Cloud.

Мо	dule 7	Cyber Crimes, Hackers and Forensics		6 Hours
		nes and Laws – Hackers – Dealing with the	rise tide of C	Cyber Crimes – Cyber
For	rensicsa	nd incident Response – Network Forensics.		
Мо	dule:8	Contemporary Issues		2 Hours
				4=11
		Total Lectur	e:	45 Hours
Tex	kt Book	<u> </u>		
1.		R. Vacca, "Computer and Information Securit		
		nit Narendra Mahalle , Poonam N. Railka	r, "Identity M	lanagement for
		et of Things", River Publishers, 2015.		
2.		Stallings, "Cryptography and Network se	curity: Princip	oles and Practice", 5th
		, 2014, Pearson Education, India.		
3.		ne Laurent, Samia Bouzefrane, "Digital Identi	•	
4.	Joseph	n Migga Kizza, "Computer Network Security",	Springer, 200	05.
Re		Books:		
1.		of Paar and Jan Pelzl, "Understanding its andPractitioners", Springer, 2014.	Cryptography	/ – A Textbook for
2.		ız A.Forouzan : Cryptography & Netwo	rk Security	– The McGraw Hill
	-	any,2007.		
3.		e Kaufman, Radia Perlman, Mike S		
		eCommunication in a public World", PTR Pre	-	-
4.	Alasda	ir Gilchrist, "IoT security Issues", Oreilly publ	ications, 2017	7.
Мо	de of Ev	/aluation: CAT / Assignment / Quiz / FAT		
Re	comme	nded by Board of Studies 28-07-202	22	
Apı	proved l	by Academic Council No. 67	Date	08-08-2022

Course Code	Course Title	L	Т	Р	С
MITS608L	RF and Microwave Sensors	3	0	0	3
Prerequisite:	NIL	Syll	abus	vers	ion
			1.0		

- 1. To introduce the students with different RF and Microwave sensors,
- 2. To familiarize antenna design with a good understanding of their parameters and applications.
- 3. To introduce comprehensive knowledge of wearable antenna.
- 4. To explore and understand basics of RFID technology.

Course Outcome:

- 1. Select a proper antenna design to be used in the RF spectral region
- 2. Model specific radiation pattern and evaluate them in different domains
- 3. Correlate the principle behind different radar systems and determine various applications based on the radar systems.
- 4. Apply the basic knowledge in the measurement of RF radiation.
- 5. Gain knowledge about the RFID technology.

Module:1 | RF Sensors

6 hours

Microwave Antenna-Introduction, types of Antenna, fundamental parameters of antennas, radiation mechanism, Fresnel and Fraunhofer regions. Antenna for communication and Antenna for sensing, radiometer and radar

Module:2 Antenna for personal area communication.

6 hours

Concepts of Printed Antennas, Broadband Microstrip Patch Antennas, Antennas for Wearable Devices, Design Requirements, Modeling and Characterization of Wearable Antennas, WBAN Radio Channel Characterization and Effect of Wearable Antennas, Domains of Operation, Sources on the Human Body, Compact Wearable Antenna for different applications.

Module:3 Radar

5 hours

Introduction to RADAR, RADAR range equation, MTI and pulse Doppler RADAR, Tracking RADAR, SAR pulse RADAR, CW RADAR

Module:4 | Applications of Radar

6 hours

Automotive, remote sensing, agriculture, medicine, detection of buried objects, NDT, defense factors affecting the performance of RADAR, RADAR transmitters, Receivers,

Module:5 | Radiometers

6 hours

Radiative transfer theory, SMMR, Types of radiometers - and Bolometers, Applications in automotive, agriculture, medicine, weather forecasting

Module:6 | Microwave power Sensors

6 hours

Diode Sensors: Diode detector principles, dynamic range average power sensors, signal waveform effects on the measurement uncertainty of diode sensors. Thermocouple Sensors: Principles of Thermocouple sensor, power meters for thermocouple sensors.

Module:7 RFID Sensors	8 hours
Introduction, Components of RFID syste standards, RFID applications.	ms, hardware and software components, RFID
Module:8 Contemporary Issues	2 hours
Total Lecture I	nours: 45 hours
Text Book(s)	
1. Finkenzeuer Klaus, "RFID Handbook Jersey.	", 2011, 3 rd edition, John Wiley and Sons, New
2. Constantine A. Balanis, "Antenna T JohnWiley and Sons, New Jersey.	heory Analysis and Design", 2016, 4 th edition,
Reference Books	
B. Hoffman - Wellenhof, H.Lichten Practice ", 5 th edition, Springer, New Y	egger and J.Collins, "GPS: Theory and ork, 2012.
Lillesand & Kiefer, "Remote Sensing JohnWiley and Sons, New Jersey.	g and Image Interpretation", 2011, 6 th edition,
Mode of Evaluation: CAT / Assignment / C	uiz / FAT
Recommended by Board of Studies 28-07	-2022
Approved by Academic Council No. 67	7 Date 08-08-2022

Course Code	Course Title	L	T	Р	С
MITS611L	Automotive Sensors and In-Vehicle Networking	3	0	0	3
Prerequisite	NIL	Sy	llabus	s vei	sion
			1	.0	

- 1. Acquaint with the basic automotive parts and the need for sensor integration in differentautomotive systems
- 2. Discuss the basics of various Power train sensors and associated systems for propervehicle dynamics and stability in Automotive systems.
- 3. Comprehend various sensors for vehicle body management and discuss various sensors and technologies for passenger convenience, safety and security systems.
- 4. Acquaint various communication standards and protocols followed within the automotive systems.

Course Outcome

- 1. Identify and understand the basic automotive parts and the requirement of sensors andtheir integration in different automotive systems.
- 2. Discus and identify the basics of various Power train sensors.
- 3. Comprehend and analyse various systems like ABS, ESP, TCS, etc for understanding vehicle dynamics and stability.
- 4. Comprehend the various sensors for vehicle body management, convenience & security systems.
- 5. Identify various technologies developed for passenger convenience, Air Bag deploymentand Seat Belt Tensioner System, etc with the students
- 6. Recognize various communication standards and protocols followed within the automotive systems.
- 7. Develop and create analytical designing of novel prototype models for various automotive electronic systems.

Module:1 Introduction to Automotive Engineering, Automotive 7 hours Management systems

Power-train, Combustion Engines, Transmission, Differential Gear, Braking Systems, Introduction to Modern Automotive Systems and need for electronics in Automobiles, Application areas of electronics in the automobiles, Possibilities and challenges in the automotive industry, Enabling technologies and Industry trends.

Module:2 | Power train Sensors

6 hours

 λ sensors, exhaust temperature sensor, NOx sensor, PM sensor, fuel quality sensor, level sensor, torque sensor, speed sensor, mass flow sensor, manifold pressure sensor.

Module:3 Sensors for Chassis management

6 hours

Wheel speed sensors/direction sensors, steering position sensor (multi turn), acceleration sensor(inertia measurement), brake pneumatic pressure sensor, ABS sensor, electronic stability sensor.

Module:4 Sensors for vehicle body management, Sensors for automotive vehicle convenienceand security systems

6 hours

Gas sensors (CO₂), Temperature/humidity sensor, air bag sensor, key less entering sensor, radar sensors. Tire pressure monitoring systems, Two wheeler and Four wheeler security systems, parking guide systems, anti-lock braking system, future safety technologies, Vehicle diagnostics and health monitoring, Safety and Reliability, Traction Control, Vehicle

•	ontrol, Accelerators and tilt sensors for sensing skidding and ar	ti-collision, Anti-
collision tech	nniques using ultrasonic Doppler sensors.	
	Air Bag and Seat Belt Pre tensioner Systems	6 hours
	nsor Functions, Distributed Front Air Bag sensing systems,	
Sensingsyst	ems, Side-Impact Sensing, and Future Occupant Protection sys	tems.
Module:6	Passenger Convenience Systems	6 hours
Electromech	anical Seat, Seat Belt Height, Steering Wheel, and Mirr	or Adjustments,
Central Loc	king Systems, Tire Pressure Control Systems, Electromecl	nanical Window
Drives, etc.		
Module:7	Modern Trends and Technical Solutions	6 hours
	nnectivity by Networking:-In vehicle communication standard	
	plutions, Portable or embedded connectivity- Endorsing Depen	
,	tems:- Terminology and concepts , Why by-wire, FLEXRAY, F	•
	ependability, Drive-by-wire case studies- prototype developm	ent-future of In
vehicle com	munication.	
Module:8	Contemporary Issues	2 hours
	Total	45 hours
Text Book(3)	
1.	Automotive Electrics, Automotive Electronics: Systems & Com 2014, 5 th Edition, BOSCH.	ponents,
2.	John Turner, Automotive Sensors, 2010, 1 st Edition, Momentur York.	m Press, New
Reference		
1	Automotive Sensors Handbook, 8 th Edition, 2011, BOSCH.	
	Jiri Marek, Hans-Peter Trah, Yasutoshi Suzuki, IwaoYokom	ori Concoro
2.	for AutomotiveTechnology, 2010, 4th Edition, Wiley, New York	
3.	Ernest O. Doebelin, "Measurement Systems – Application a 2017, 6 th Edition,McGraw-Hill, New Delhi.	nd Design",
Mode of Eva	lluation: CAT / Assignment / Quiz / FAT	
Recommer	ided by Board of Studies 28-07-2022	
L		
Approved b	by Academic Council No. 67 Date 08-08-202	22

Course Code	Course Title	L	Т	Р	С
MITS612L	Fiber Optic Sensors and Photonics	3	0	0	3
Prerequisite	NIL	Syll	abus	Versi	on
			1.0		

- 1. To introduce the theory and technology of fiber optics sensing to improve their understanding inrapidly growing field.
- 2. To predict the optical parameters in optical devices to understand the phenomena induced due tointensity based effects.
- 3. To estimate the phase, charge distribution due to polarization effects and its application inoptical sensing.
- 4. To analyses and decide the process flow conditions and steps involved for different polymerswith appropriate optical characteristic for polymer waveguides based sensing.

Course Outcomes

- 1. Attainment of basic knowledge of optical waveguides and optical devices employed in opticalsensors.
- 2. Will be conversance in optical parameters involved in active and passive components
- 3. Entrust the characteristics of a suitable optical materials for the sensing device in a givenapplication.
- 4. Identify and apply the knowledge in designing interferometric devices which is more effectively used in sensing.
- 5. Will be aware of different polymers and their chemical, optical characteristics to formulateminiaturized optical devices.

Module:1 Theory of Optical Waveguides 7 hours

Wave theory of optical waveguides, formation of guided modes, Slab waveguide, Rectangular waveguide, Radiation fields from waveguide, Effective index method, Marcatili's method, Beam propagation method. Basic characteristic of Optical Fiber Waveguides, Acceptance angle, Numericalaperture, skewrays- Electromagnetic Modes in Cylindrical Waveguides.

Module:2 Active and Passive Optical Components 7 hours

Electro-optic and acousto optic wave guide devices, directional couplers, optical switch, phase and amplitude modulators, filters etc. Yjunction, powersplitters, arrayed wave guide devices, fiber pigtaling, end-fiber prism coupling, FBG and fabrication of FBG, Tapered couplers.

Module:3 Intensity and Polarization Sensors 7 hours

Intensity sensor: Transmissive concept –Reflective concept-Micro bending concept—Transmission and Reflection with other optic effect-Interferometers –Mach Zehnder-Michelson-Fabry-Perot and Sagnac— Phase sensor: Phase detection-Polarization maintaining fibers. Displacement and temperature sensors: reflective and Micro bending Technology- Applications of displacement and temperature sensors.

Module:4 Interferometric Sensors 7 hours

Pressure sensors: Transmissive concepts, Microbending –Intrinsic concepts–Interferometric concepts, Applications. Flow sensors: Turbine flowmeters- Differential pressure flowsensors –Laser Doppler velocity sensors-Applications- Sagnac Interferometer for rotation sensing. Magnetic and electric fieldsensors: Intensity and phase modulation types—applications.

Module:5 Polymer based waveguide in sensing	7 hours
Polymer based waveguide, materials, properties, fabrication process of	•
waveguide, Polymer based optical components - Passive, Active polymer	
Resonator, structure, theory, Filter using Ring Resonator-application in sens	ing
Maria de la Companya del Companya de la Companya de la Companya del Companya de la Companya de l	
Module:6 Fiber based Chemical Senors	5 hours
Fiber based Chemical Sensing: Absorption, Fluorescence, Chem Vibrational Spectroscopic, SPR.	ni-luminescence,
Module:7 Fiber based Bio-Senors	3 hours
Fiber based Bio-molecules sensing: High Index, SPR, Hollow core fiber pro	bes Label Free
bio- molecules.	,
Module:8 Contemporary Issues	2 hours
Total Lecture hours:	45 hours
Text Book(s):	1
1. David A. Krohn, Trevor W. MacDougall, Alexis Mendez, "Fiber C Fundamentals and Applications" SPIE Press, 4th ed. 2015. ISBN: 162	
2. Eric Udd , William B. Spillman Jr., "Fiber Optic Sensors: An Introdu Engineersand Scientists", Wiley, 2nd Ed., 2011. ISBN: 0470126841	uction for
	uction for
Engineersand Scientists", Wiley, 2nd Ed., 2011. ISBN: 0470126841	
Engineersand Scientists", Wiley, 2nd Ed., 2011. ISBN: 0470126841 Reference Book(s) 1. Zujie Fang & et. al., "Fundamentals of Optical Fiber Sensors" Wiley	, 1 st Ed.,
Engineersand Scientists", Wiley, 2nd Ed., 2011. ISBN: 0470126841 Reference Book(s) 1. Zujie Fang & et. al., "Fundamentals of Optical Fiber Sensors" Wiley 2012.ISBN:0470575409 2. Shizhuo Yin, Paul B. Ruffin, and Francis T.S. Yu, "Fiber Optic Sensors"	, 1 st Ed., ors",CRC
Engineersand Scientists", Wiley, 2nd Ed., 2011. ISBN: 0470126841 Reference Book(s) 1. Zujie Fang & et. al., "Fundamentals of Optical Fiber Sensors" Wiley 2012.ISBN:0470575409 2. Shizhuo Yin, Paul B. Ruffin, and Francis T.S. Yu, "Fiber Optic Sensor Press, 2 Ed,2017. ASIN: B078JN75QW 3. F.Baldini&et.al., "Optical Chemical Sensors", NATO Science Series	, 1 st Ed., ors",CRC
Engineersand Scientists", Wiley, 2nd Ed., 2011. ISBN: 0470126841 Reference Book(s) 1. Zujie Fang & et. al., "Fundamentals of Optical Fiber Sensors" Wiley 2012.ISBN:0470575409 2. Shizhuo Yin, Paul B. Ruffin, and Francis T.S. Yu, "Fiber Optic Sensor Press, 2 Ed,2017. ASIN: B078JN75QW 3. F.Baldini&et.al., "Optical Chemical Sensors", NATO Science Series Mathematics, Physics and Chemistry, Springer, 2008. ISBN: 1402046	, 1 st Ed., ors",CRC

Course Code	Course Title	L	T	Р	С
MITS614L	Deep Learning	3	0	0	3
Prerequisite:	NIL	Sy	llabus	s Vers	sion
			1.	0	

- 1. To introduce the fundamental theory and concepts of machine learning and artificial intelligence
- 2. To provide a comprehensive foundation to artificial neural networks, neuro-modeling, and their applications to pattern recognition.
- 3. To explore the learning paradigms of supervised and unsupervised shallow/deep neural networks.
- 4. To provide exposure to the recent advances in the field of and facilitate in depth discussions on chosen topic
- 5. To impart adequate knowledge on deep learning frameworks and their applications to solving engineering problems

Course Outcomes

- 1. Gain knowledge about basic concepts of machine learning algorithms and identify machinelearning techniques suitable for the given problem.
- 2. Understand the differences between shallow neural networks and deep neural networks forsupervised and unsupervised learning.
- 3. Develop and train neural networks for classification, regression and clustering.
- 4. Understand the foundations of neural networks, how to build neural networks and learn how to leadsuccessful machine learning projects
- 5. Identify the deep feed forward, convolution and recurrent neural networks which are moreappropriate for various types of learning tasks in various domains
- 6. Implement deep learning algorithm and solve real world problems

Module:1 Foundations of Machine Learning-I

hour

Supervised and unsupervised learning, parametric vs non-parametric models, parametric models for classification and regression- Linear Regression, Logistic Regression, Naïve Bayes classifier, simple non-parametric classifier-K-nearest neighbour, support vector machines.

Module:2 Foundations of Machine Learning-II

5 hours

Clustering- distance based- K-means, density based, association rule mining, validation techniques- cross validations, feature selection and dimensionality reduction, principal component analysis-Eigenvalues, Eigen vectors, Orthogonality-challenges motivating deep learning

Module:3 Neural Networks for Classification and Regression

6 hours

ANN as a technique for regression and classification, structure of an artificial neuron, activation functions- linear activation, sigmoid and softmax. Feedforward neural networks- shallow model-single layer perceptron, multi-layer perceptron as complex decision classifier- learning XOR-Gradient based learning, Backpropagation algorithm, risk minimization, loss function, regularization, heuristicsfor faster training and avoiding local minima.

Module:4 Deep Feed Forward Neural Networks

6 hours

Feed forward neural networks- deep model- output units and hidden units, training deep models- hyper parameters and validation sets-cross validation, capacity, overfitting and under fitting, bias vs variance trade off, cross validation - vanishing

		m, new optimization m			
reg	ularization m	ethods (dropout, batch	n normaliza	tion, dataset a	augmentation), early
	oping.				
		Convolutional Neural			7 hours
		eration- kernel and fea			
		neter sharing, poolir			
con	volution and	d pooling as strong p	rior, convo	olution with s	tride, effect of zero
pad	lding, single	-channel and multi-cha	annel data	types used ir	n ConvNet, variants
		lution- locally connec			
		rable convolutions, fu			
		ayer sizing parameters		lies LeNet,	
		Recurrent Neural Net			6 hours
		ning with neural nets,			
		gh time (BPTT), vanis			
		ort term memory (LSTI			
		Deep Learning Tools			8 hours
		ow, Keras, PyTorch, C			
		CNN - YOLO, SSD. S		gnition with F	
IVIO	dule:8 (Contemporary Issues	5		2 hours
	al Hours				45 hours
Tex	t Book(s)				1
	tt Book(s) Bengio, Y 2015, MIT				lle. "Deep learning"
Tex	tt Book(s) Bengio, Y 2015, MIT Josh Pat	<u>Press</u> terson and Adam G	Gibson, "D		lle. "Deep learning"
1 2	tt Book(s) Bengio, Y 2015, MIT Josh Pat Approach	Press terson and Adam C 'O'Reilly Media Inc., 20	Gibson, "D		lle. "Deep learning"
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1 2 Ref	t Book(s) Bengio, Y 2015, MIT Josh Pat Approach' erence Book Bishop, C Rich E and Bengio, Y	Press terson and Adam C O'Reilly Media Inc., 20 Nks M., Pattern Recognit d Knight K, "Artificial In Toshua. "Learning de	Gibson, "D 017, USA. ion and Ma itelligence" ep archited	eep Learning chine Learnir , 2011, 2 nd ed	lle. "Deep learning" g- A Practitioner's ng, Springer, 2011 ., TMH, New Delhi,
1 2 Ref 1. 2 3	t Book(s) Bengio, Y 2015, MIT Josh Pat Approach' erence Book Bishop, C Rich E and Bengio, Y trends in N	Press terson and Adam C 'O'Reilly Media Inc., 20 ks .,M., Pattern Recognit d Knight K, "Artificial Ir oshua. "Learning de lachine Learning, 2(1)	Gibson, "D 017, USA. ion and Ma itelligence" ep archited - 2009	eep Learning chine Learnir , 2011, 2 nd ed ctures for Al	lle. "Deep learning" g- A Practitioner's ng, Springer, 2011 ., TMH, New Delhi, - Foundations and
1 2 Ref 1. 2	t Book(s) Bengio, Y 2015, MIT Josh Pat Approach' erence Book Bishop, C Rich E and Bengio, Y trends in N	Press terson and Adam C O'Reilly Media Inc., 20 Nks M., Pattern Recognit d Knight K, "Artificial In Toshua. "Learning de	Gibson, "D 017, USA. ion and Ma itelligence" ep archited - 2009	eep Learning chine Learnir , 2011, 2 nd ed ctures for Al	lle. "Deep learning" g- A Practitioner's ng, Springer, 2011 ., TMH, New Delhi, - Foundations and
1 2 Ref 1. 2 3	tt Book(s) Bengio, Y 2015, MIT Josh Pat Approach Ference Book Bishop, C Rich E and Bengio, Y trends in M Tom M. W 2013.	Press terson and Adam C 'O'Reilly Media Inc., 20 ks .,M., Pattern Recognit d Knight K, "Artificial Ir oshua. "Learning de lachine Learning, 2(1)	Gibson, "D 017, USA. ion and Ma itelligence" ep archited - 2009 ning", McG	eep Learning chine Learning , 2011, 2 nd ed ctures for Al raw-Hill Educ	Ile. "Deep learning" g- A Practitioner's ng, Springer, 2011 ., TMH, New Delhi, - Foundations and cation (India) Pvt Ltd,
1 2 Ref 1. 2 3 4 Mod	tt Book(s) Bengio, Y 2015, MIT Josh Pat Approach' erence Boo Bishop, C Rich E and Bengio, Y trends in M Tom M. W 2013. de of Evaluation	Teress terson and Adam Co 'O'Reilly Media Inc., 20 ks .,M., Pattern Recognited Knight K, "Artificial Infoshua. "Learning de lachine Learning, 2(1). litchell, "Machine Lear	Gibson, "D 017, USA. ion and Ma itelligence" ep archited - 2009 ning", McG	chine Learning chine Learning 2011, 2 nd ed ctures for Al raw-Hill Educ	Ile. "Deep learning" g- A Practitioner's ng, Springer, 2011 ., TMH, New Delhi, - Foundations and cation (India) Pvt Ltd,
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Course Code	Course Title	L	Т	Р	С
MITS615L	Web Design and Development	3	0	0	3
Pre-requisite	NIL	Sylla	bus	ver	sion
			1	.0	

- 1. To acquire specific scripting knowledge to develop interactive applications.
- 2. To understand the basics of android application development.
- 3. To apply the programming skills in developing application pertaining to Industrial, medical, agricultural, etc.

Course Outcomes:

- 1. Design dynamic web forms to acquire and process user & sensor data
- 2. Interactive forms using Java Script with a focus on internet of things
- 3. Implement mobile application using android SDK
- 4. Solve the need for smart systems in a distributed environment
- 5. Understand the IoT architecture and building blocks for various domains
- 6. Devise multidisciplinary case to case modelling and execute wide range of application

Module:1 Markup Language

7 hours

Introduction to Markup language, HTML document structure, HTML forms, Style (CSS), Multiple CSS stylesheets, DHTML, Tools for image creation and manipulation, User experience design, IoT development using charts

Module:2 Scripting Language

6 hours

Introduction to JavaScript, Functions, DOM, Forms, and Event Handlers, Object Handlers, Input validation, J2ME, application design using J2ME, IoT development using Real time rules, platforms, alerts

Module: 3 Android Programing Framework

6 hours

Mobile app development: Android Development environment, Simple UI Layouts and layout properties, GUI objects, Event Driven Programming, opening and closing a Database

Module:4 Industrial Internet Application

6 hours

IIoT Fundamentals and Components, Industrial Manufacturing, Monitoring, Control, Optimization and Autonomy, Introduction to Hadoop and big data analytics

Module:5 Applications in agriculture

6 hours

Smart Farming: Weather monitoring, Precision farming, Smart Greenhouse, Drones for pesticides.

Module:6 Applications in IoT enabled Smart Cities

6 hours

Energy Consumption Monitoring, Smart Energy Meters, Home automation, SmartGrid and Solar Energy Harvesting, Intelligent Parking, Data lake services scenarios.

Module:7 Healthcare applications

6 hours

Architecture of IoT for Healthcare, Multiple views coalescence, SBC-ADL to construct the system architecture. Use Cases: Wearable devices for Remote monitoring of

Physiologicalparameter, ECG, EEG, Diabetes and Blood Pressure.						
Module:8	Contemporary Issues	2 hours				
	Total Lecture hours:	45 hours				
Text Book	(s)					
1.	John Dean, Web Programming with HTML5, CSS and Ja					
	2018, Jonesand Bartlett Publishers Inc., ISBN-10: 97812840	91793				
2.	DiMarzio J. F., Beginning Android Programming with And	roid				
	Studio, 2016, 4 th ed., Wiley, ISBN-10: 9788126565580					
Reference						
1.	Fadi Al-Turjman, Intelligence in IoT- enabled Smart Cities	, 2019,				
	1 st edition, CRCPress,ISBN-10: 1138316849					
2.	Giacomo Veneri, and Antonio Capasso, Hands-on Industrial					
	of Things: Create a powerful industrial IoT infrastructure using	ng				
	Industry 4.0, 2018, Packt Publishing.					
3.	Subhas Chandra Mukhopadhyay, Smart Sensing Technolog					
	for Agriculture and Environmental Monitoring, 2012, Springer	,				
	ISBN-10: 3642276377					
	valuation: CAT / Assignment / Quiz / FAT					
	nded by Board of Studies 07-06-2023					
Approved b	by Academic Council No. 70 Date 24-06-2023					