

# **School of Electronics Engineering**

## M. Tech. – Embedded Systems

Curriculum and Syllabus 2023-24

#### VISION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

Transforming life through excellence in education and research.

#### MISSION STATEMENT OF VELLORE INSTITUTE OFTECHNOLOGY

World class Education: Excellence in education, grounded in ethics and critical thinking, for improvement of life.

**Cutting edge Research**: An innovation ecosystem to extend knowledge and solve critical problems.

Impactful People: Happy, accountable, caring and effective workforce and students.

Rewarding Co-creations: Active collaboration with national & international industries & universities for productivity and economic development.

Service to Society: Service to the region and world through knowledge and compassion.

#### VISION STATEMENT OF THE SCHOOL OF ELECTRONICS ENGINEERING

To be a leader by imparting in-depth knowledge in Electronics Engineering, nurturing engineers, technologists and researchers of highest competence, who would engage in sustainable development to cater the global needs of industry and society.

#### MISSION STATEMENT OF THE SCHOOL OF ELECTRONICS ENGINEERING

.

- Create and maintain an environment to excel in teaching, learning and applied research in the fields of electronics, communication engineering and allied disciplines which pioneer for sustainable growth.
- Equip our students with necessary knowledge and skills which enable themto be lifelong learners to solve practical problems and to improve the quality of human life

## **PROGRAMME EDUCATIONAL OBJECTIVES (PEOs)**

#### The graduates of the programme will be able to

1. Graduates will be engineering practitioners and leaders, who would help solve industry's technological problems

2. Graduates will be engineering professionals, innovators or entrepreneurs engaged in technology development, technology deployment, or engineering system implementation in industry

3. Graduates will function in their profession with social awareness and responsibility

4. Graduates will interact with their peers in other disciplines in industry and society and contribute to the economic growth of the country

- 5. Graduates will be successful in pursuing higher studies in engineering or management
- 6. Graduates will pursue career paths in teaching or research

## **PROGRAMME OUTCOMES (POs)**

On completion of the Programme the students will have the

PO\_01: Having an ability to apply mathematics and science in engineering applications.

PO\_02: Having an ability to design a component or a product applying all the relevant standards and with realistic constraints, including public health, safety, culture, society and environment

PO\_03: Having an ability to design and conduct experiments, as well as to analyse and interpret data, and synthesis of information

PO\_04: Having an ability to use techniques, skills, resources and modern engineering and IT tools necessary for engineering practice

PO\_05: Having problem solving ability- to assess social issues (societal, health, safety, legal and cultural) and engineering problems

PO\_06: Having adaptive thinking and adaptability in relation to environmental context and sustainable development

PO\_07: Having a clear understanding of professional and ethical responsibility

PO\_08: Having a good cognitive load management skills related to project management and finance

### **Programme Specific Outcomes (PSOs)**

On completion of M. Tech. Embedded Systems, graduates will be able to

PSO1. Apply the advanced concepts of Embedded System Design with realtime constraints using advanced Microcontrollers and FPGA based systems.

PSO2. Use the cutting-edge technologies in both hardware and software, to solve real- world multi-disciplinary problems and arrive at a viable solution.

PSO3. Independently carry out research on diverse Embedded System strategies to address practical problems and present a substantial technical report.

	CREDIT INFO	
S.no	Catagory	Credits
1	Discipline Core	24
2	Discipline Elective	12
3	Projects and Internship	26
4	Open Elective	3
5	Skill Enhancement	5
	Total Credits	70

		Discipline Core							
sl.no	Course Code	Course Title	Course Type	Ver sio n	L	т	Ρ	J	Credits
1	MEDS501L	Embedded System Design	Theory Only	1.0	3	0	0	0	3.0
2	MEDS502L	Microcontroller Architecture and Organization	Theory Only	1.0	3	0	0	0	3.0
3	MEDS502P	Microcontroller Architecture and Organization Lab	Lab Only	1.0	0	0	2	0	1.0
4	MEDS503L	Embedded Programming	Theory Only	1.0	3	0	0	0	3.0
5	MEDS503P	Embedded Programming Lab	Lab Only	1.0	0	0	2	0	1.0
6	MEDS504L	In Vehicle Networking	Theory Only	1.0	3	0	0	0	3.0
7	MEDS505L	Real Time Operating System	Theory Only	1.0	3	0	0	0	3.0
8	MEDS505P	Real Time Operating System Lab	Lab Only	1.0	0	0	2	0	1.0
9	MEDS506L	Wireless and Mobile Communication	Theory Only	1.0	3	0	0	0	3.0
10	MEDS507L	Electronic Hardware System Design	Theory Only	1.0	2	0	0	0	2.0
11	MEDS507P	Electronic Hardware System Design Lab	Lab Only	1.0	0	0	2	0	1.0

		Discipline Elective							
sl.no	Course Code	Course Title	Course Type	Ver sio n	L	т	Р	J	Credits
1	MEDS601L	Electromagnetic Interference and Compatibility	Theory Only	2.0	3	0	0	0	3.0
2	MEDS602L	Advanced Digital Image Processing	Theory Only	1.0	3	0	0	0	3.0
3	MEDS603L	Design and Analysis of Algorithms	Theory Only	1.0	3	0	0	0	3.0
4	MEDS605L	Hardware Software Co-design	Theory Only	1.0	2	0	0	0	2.0
5	MEDS606L	Modern Automotive Electronics Systems	Theory Only	1.0	3	0	0	0	3.0
6	MEDS608L	Intelligent IoT System Design and Architecture	Theory Only	1.0	2	0	0	0	2.0
7	MEDS608P	Intelligent IoT System Design and Architecture Lab	Lab Only	1.0	0	0	2	0	1.0
8	MEDS609L	Fault Tolerance and Dependable Systems	Theory Only	1.0	3	0	0	0	3.0
9	MEDS611L	Parallel Processing and Computing	Theory Only	1.0	3	0	0	0	3.0
10	MEDS613L	Cloud computing	Theory Only	1.0	3	0	0	0	3.0
11	MEDS614L	Cyber Physical Systems	Theory Only	1.0	3	0	0	0	3.0
12	MEDS614P	Cyber Physical Systems Lab	Lab Only	1.0	0	0	2	0	1.0
13	MEDS615L	5G and Future Generation Communication Systems	Theory Only	1.0	3	0	0	0	3.0
14	MEDS616L	Machine Learning and Deep Learning	Theory Only	1.0	3	0	0	0	3.0

		Discipline Elective							
15	MVLD611L	Advanced Computer Architecture	Theory Only	1.0	3	0	0	0	3.0
16	MVLD613L	System Design with FPGA	Theory Only	1.0	3	0	0	0	3.0
17	MVLD616L	Scripting Language for Electronic Design Automation	Theory Only	1.0	3	0	0	0	3.0

	Projects and Internship											
sl.no	Course Code	Course Title	Course Type	Ver sio	L	т	Ρ	J	Credits			
				n								
1	MEDS696J	Study Oriented Project	Project	1.0	0	0	0	0	2.0			
2	MEDS697J	Design Project	Project	1.0	0	0	0	0	2.0			
3	MEDS698J	Internship I/ Dissertation I	Project	1.0	0	0	0	0	10.0			
4	MEDS699J	Internship II/ Dissertation II	Project	1.0	0	0	0	0	12.0			

		Open Elective							
sl.no	Course Code	Course Title	Course Type	Ver	L	т	Ρ	J	Credits
				sio n					
1	MFRE501L	Francais Fonctionnel	Theory Only	1.0	3	0	0	0	3.0
2	MGER501L	Deutsch fuer Anfaenger	Theory Only	1.0	3	0	0	0	3.0
3	MSTS601L	Advanced Competitive Coding	Soft Skill	1.0	3	0	0	0	3.0

		Skill Enhancement							
sl.no	Course Code	Course Title	Course Type	Ver	L	т	Р	J	Credits
				sio					
				n					
1	MENG501P	Technical Report Writing	Lab Only	1.0	0	0	4	0	2.0
2	MSTS501P	Qualitative Skills Practice	Soft Skill	1.0	0	0	3	0	1.5
3	MSTS502P	Quantitative Skills Practice	Soft Skill	1.0	0	0	3	0	1.5

Course Code	Course Title		L   1	P	С
MEDS501L	Embedded System Desi	gn	3 (	0	3
Pre-requisite	NIL		/llabus	vers	ion
·			1.		
Course Objectiv	es			-	
The course aimed					
	inderstand comprehensively the technolog	aies and techniqu	les und	erlvin	a in
	n embedded solution to a wearable, mobile				9
	ML diagrams and advanced Modelling sch			ases.	_
	d the building process of embedded syste				-
01 01.001010					
Course Outcome	<u>-</u>				
The students will					
	embedded system and compare with gene	eral purpose syst	em.		
	e the methods adapted for the development			syste	-m
	uced to RTOS and related mechanisms.	it of a typical offic	Joadoa	0,010	
	pes of processors and memory architectur	'e			
	te the features of components and networ		systems	\$	
	real-time working prototypes of different				cale
•	d Systems.	ornan ocalo an			oulo
	d the various concepts in Multi-Tasking				
Module:1 Intro	duction to Embedded System			5 hc	ours
	m processor, hardware unit, software emb	edded into a svs	tem. Ex		
	stem, Embedded Design life cycle, Layers			ampi	0 01
	edded System Design Methodologies			5 hc	ours
	em modelling [FSM, SysML, MARTE], UN	II as Design too	L UMI		
	lysis and Use case Modelling, Design Exa		, OME	nota	
	ling Process For Embedded Systems			4 hc	ours
	Compiling, Cross Compiling, Linking, Locat	ing Compiler Dr	iver Liu		
	ots and scatter loading, Loading on the tar				Παρ
	em design using general purpose	jet, Embedded i		7 hc	ours
	essor				, and
Microcontroller a		Memory Strate	aic sel	ection	n of
	nemory, Memory Devices and their Cha				
	techniques, DMA.			,	ana
	ponent Interfacing & Networks			9 hc	ours
	ng, I/O Device Interfacing, Interrupt Con	trollers Networks	s for E		
	CI,PCI Express, UART, SPI, I2C, CAN, V				
	WPAN, Evolution of Internet of things (Io	• •	0110 2	10.010	
Module:6 Oper		• /•		7 hc	ours
	perating Systems, Basic Features & Fur	nctions of an Op	erating		
	atures [polled loop system, interrupt driv				
	and its states, Process/Task Control Block,				
Module:7 Multi				6 hc	
	ng , Scheduling and various Sched	uling algorithms	Inte		
	Shared Memory, Mail Box, Message Que			•	
	tex), Dead Lock, Priority Inversion (bot				
	Priority Inheritance Protocol		unu <del>c</del> u)	,	onty
<u> </u>	emporary Issues			2 hc	lire
				2 110	-ui 3
	Total Locture hours:			15 ha	lire
	Total Lecture hours:			45 hc	ours

Tex	xt Book(s)	
1.	Raj Kamal, "Embedded systems Architecture, Programming and Design", Tata McGraw-Hill, 2016.	
2.	Wayne Wolf "Computers as components: Principles of Embedded Computing System Design", The Morgan Kaufmann Series in Computer Architecture and Design, 2013.	
Ref	ference Books	
1.	Lyla B. Das," Embedded Systems an Integrated Approach", Pearson Education, 2013.	
2.	Shibu K V," Introduction to Embedded Systems", McGraw Hill Education(India) Private Limited, 2014	
3.	Sriram V Iyer, Pankaj Gupta " Embedded Real Time Systems Programming Tata McGraw- Hill, 2012	<b>;</b> ",
4.	Steve Heath, "Embedded Systems Design", EDN Series, 2013.	
Мо	de of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final	
Ass	sessment Test	
Ree	commended by Board of Studies 28-07-2022	
Арр	proved by Academic Council No. 67 Date 08-08-2022	

Course Code	Course Title			L 1	- P	С
MEDS502L	Microcontroller Architecture and Or	ganization		3 0	0	3
Pre-requisite	NIL		Syll	abus	vers	sion
				1.	0	
Course Objectiv						
The course aimed						
	the architecture of 8051 microcontroller and					
	the instruction set of 8051 and ARM microco					
	system in block level using microcontrolle	r, memory c	levice	es, bi	lses	and
	oheral devices					
4. Solving re	al life problem using microcontroller-based s	systems				
Course Outcome						
	course, the students will be able to					
	he architectures of processors	mothomotio		~ 00	51	
	ssembly program applying Digital logic and ssembly Language Program for ARM	mainematic	s usii	iy ou:	51	
	LP with minimum instructions and memory.					
	nd evaluate the given program in terms o	f code size	and	comr	utati	onol
time	The evaluate the given program in terms 0	0000 3120	anu	Sout	Juidi	Jiai
	crocontroller based system within realistic c	onstraint like	usei	spe	cifica	tion
	of components etc			opo	linea	,
	life problem and construct a complete syste	em as a solut	ion			
Module:1 Intro	duction to Microcontrollers				5 ho	ours
Microprocessors	Vs Microcontrollers; Classification - bits, n	nemory arch	itectu	ure, I	SA; I	_ittle
Endian Vs Big En		,				
Module:2 8051	Microcontroller				6 ho	ours
Architecture - T	imers, Interrupts, Register Architecture (b	anks), PSW	regi	ister,	Mer	nory
architecture; Instr			Ũ			
Module:3 8051	Programming and Interfaces				8 ho	ours
	& Assembly for – Interrupts, Timers and In	terfaces – P	ORT	5, LE	D, Al	DC,
SENSORS, LCD,	DAC, Serial Communication					
Module:4 ARM	Architecture				4 ho	ours
ARM Design Phile	osophy; Overview of ARM architecture; State	es [ARM, Th	umb,	Jaze	lle];	
Registers, Modes	; Conditional Execution; Pipelining; Vector T	ables; Exce	otion	hand	ling.	
Module:5 ARM	Instruction Set				6 ho	ours
	data processing instructions, branch instru					ons,
	oading instructions, conditional Execution, A	Assembly Pro	ogran	nming		
	nb Instruction Set				6 ho	
	n-Thumb Registers, ARM Thumb interwo					
	uction, single/multiple load store instruc	ction, Stack	ins	tructi	on,	SWI
	nbly Programming.					
	Core based Microcontroller				8 ho	
	C214X, Memory Addressing, IO ports, Time		/Vatcl	n Dog	g Tim	er,
	UART, Interrupts, Displays, C programming	J.				
Module:8   Cont	emporary Issues				2 ho	ours
	Total Lecture hours:			4	45 ho	ours
Text Book(s)		<u> </u>			0015	
	oss, Dominic Symes, Chris Wright, ARM	Developer's	s Gu	ide, 1	2010	, 1 <sup>s</sup>
Edition, Else	vier, United States					

2.	Kenneth Ayala, The 8051 Microco	ontroller & Embe	edded Sy	stems Using Assembly and
	C, 2010, 1st edition, Cengage Lea	arning, United S	states	
Ref	ference Books			
1.	Steve Furber ARM System on C	Chip Architectur	e, 2010,	2 <sup>nd</sup> Edition, Addison Wesley,
	United States			
2.	Technical Reference Manual COF	RTEX M-3, ARN	1, 2010, L	Jnited States
Мо	de of Evaluation: Continuous Asse	ssment, Digital	Assignme	ent, Quiz and Final
Ass	sessment Test			
Ree	commended by Board of Studies	28-07-2022		
Арр	proved by Academic Council	No. 67	Date	08-08-2022
	•	•		•

С	ourse Code		Course Title			L	Т	Ρ	С
Μ	EDS502P	Microcontroller	Architecture and Organ	izatior	n Lab	0	0	2	1
Pr	e-requisite	NIL			Syllab		/ers	sion	
_						1.0			
	ourse Objectiv								
١r	ne course is aim		151 microcontrollar and A	DM nr	ococcor				
	2. Teaching	he instruction set of 8	51 microcontroller and A 051 and ARM microcontro	oller to	efficient				
		bheral devices	I using microcontroller, n	nemor	y devices	5, DL	lses	s an	na
			nicrocontroller-based syst	ems					
С	ourse Outcome	¥¥							
At	the end of the	course the students wi	Il be able to						
			lying Digital logic and ma			805	51		
			ogram for ARM and ARM	1 perip	herals				
		LP with minimum inst	n program in terms of co	oda si	ze and c	omn	etu	tion	اد
	time	nu evaluate the giver	r program in terms of or			omp	ula	lion	a
In	dicative Exper	ments							
1	Task-1: Calcu	lator Application				7 h	our	S	
	Sub ta	sk 1: Make the LCD ir	terfaced to 8051						
	Sub ta	sk 2: Get input from s	witch which is interfaced t	to 805 <sup>-</sup>	1 and				
		display it on LCD							
	Sub ta	sk 3: Based on switch	input, perform basic ope	ration	of a				
	Calcul								
2	Task-2: Speed	d control of motor				7 h	our	S	
	-		enerate an exact time del	av for	T <sub>ON</sub> and				
	TOFF			.,					
	Sub ta	sk-2: Use timer interru	pt in generating the wave	eform					
			d of a DC motor using Tin						
3		controller based applic		-		8 h	our	s	
		sk-1: Interface Zigbee							
		ask-2: Interface keypa							
		ask-3: Interface GSM							
			ressed in keypad, transm	nit the l	key info				
		•	r to rotate, which is interf		•				
			status of motor[run/stop]						
4	Task-4: Senso	or interfacing with ARM	1 LPC2148			8 h	our	S	
		ask-1: Interface IR with							
			rature sensor with LPC21	148					
		ask-3: Interface Blueto		0					
			detail and sensor data to	o anoth	ner				
	LPC2	148 via Bluetooth.							
			Total Labo			30	ho	urs	
			ssment and Final Assess	ment	lest				
			8-07-2022 lo. 67 Date	08-0	8-2022				
	oproved by Aca			00-0	0-2022				

Course Code	Course Title			L	Τ	Ρ	С
MEDS503L	Embedded Programming			3	0	0	3
Pre-requisite	NIL		Syl	labu		ersio	on
				1	0.		
Course Objective	es						
The course is aim							
	nt students with fundamentals of C						
	ize the students with data structures						
	ce the students with SHELL programming and						
4. To Implem	ent the Device drivers in LINUX environment						
Course Outcome							
	course the students will be able to						
	nd the fundamentals of C						
	nd the Data structures						
	nd the basics of Linux						
	the skill, knowledge and ability of SHELL pro	0	g.				
	working knowledge of basic Embedded Linu						
	nd the concepts of Kernel module Programm	ing					
	ce driver programs	ro and ac	ftwor	o too			
	ds on experience in using state-of- art hardwa	re and so	ntwar	e 100	15		
Module:1 C La	nguage				7	ho	ire
	f C, Embedded C Vs C, Embedded program	mina asi	nante	with			
	Functions, Arrays, pointers, structures and In			vvitii	103	pec	1 10
	structures of kernel programming	ouio/Ouip	/013.		6	ho	irs
	linked list, Double linked list and Queues.						
Module:3 Linux					6	ho	urs
	t, X windows basics, Navigating file system	n finding	n files	s. wo			
	iles text editing in Linux, Compression and						
	lanagement, I/O Handling, File Locking.		.g .c.	, _			
Module:4 Shell					7	ho	urs
	more than one command at a time, prior	ritizing ar	nd kill	ing i	oroc	ess	es.
	mands, pipes and redirection, regular ex						
-	while, if and other commands.	•	, I				07
	edded Linux				6	ho	urs
Linux Basics, Bo	oting process, make files , using SD card and	d reader t	o trar	nsfer	pro	grar	ns,
	NUX system calls, API's, device drivers, con				•	•	
driver.	-				-		
	el Module Programming					ho	
Compiling kernel,	Configuring Kernel and compilation, Kernel	code, bro	wsers	sSta	atic	linki	ng,
dynamic linking o	f modules, User space, kernel space concer	ots, Writir	ng sim	nple	mod	dule	s –
Writing, Make-file	s for modules.						
	e Driver concepts					ho	
	Block & character driver distinction, Low I	evel drive	ers, C	DS d	lrive	rs e	etc,
	drivers, Device major, minor number.						
Module:8 Cont	emporary Issues				2	ho	urs
	Total Lecture hours:				45	ho	urs
Text Book(s)							
	Richard stones, Beginning Linux Programmir	ng, 2012 i	reprin	t, Wr	ox -	– Wi	iley
Publishing, U	SA						

 2. Eric Foster Johnson, John C. Welch, Micah Anderson, Beginning shell scripting, 2012, reprint, Wrox – Wiley Publishing, USA
 Reference Books

 Derek Molloy, Exploring Beagle Bone: Tools and Techniques for Building with Embedded Linux, 2015, 1<sup>st</sup> Edition, Wiley Publications, USA

 Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final Assessment Test
 Recommended by Board of Studies 28-07-2022
 Approved by Academic Council No. 67 Date 08-08-2022

Cou	Irse Code	Course Ti	tle		LT	Ρ	С
ME	DS503P	Embedded Progra	mming Lab		0 0	2	1
Pre-	requisite	NIL		Sylla	abus v	vers	ion
					1.0	)	
	rse Objectiv						
	course is aim						
		t students with fundamentals of C					
		ze the students with data structur					
		ce the students with SHELL progra					
4	4. To Implem	ent the Device drivers in LINUX e	nvironment				
Cau							
	Irse Outcome	ourse the students will be able to					
		nd the fundamentals of C nd the Data structures					
	•	nd the basics of Linux					
		the skill, knowledge and ability of	SHELL programming				
		working knowledge of basic Emb		•			
		nd the concepts of Kernel module					
		ce driver programs	riogrammig				
		s on experience in using state-of-	art hardware and soft	tware	tools		
Indi	cative Experi	ments					
1.	Task1: C pro			6	6 hours		
	<ul> <li>Imple</li> </ul>	ment a binary tree sorting					
	<ul> <li>Imple</li> </ul>	ment a dice throw game					
	Implement a	command line argument based a	plication of automatic	n			
2.		mentation of data structure for an		6	6 hour	s	
		dMerge() function that takes two					
		easing order, and merges the two					
		creasing order. SortedMerge() she					
		should be made by splicing togeth	er the nodes of the fir	st			
	two lists.						
3.		Programming	m uning Chall againt		6 hour	S	
		of inventory management system	en using Shell script	ing			
		wing features					
		may add/update/delete inventory.					
		may add/update inventory details.					
		s include cost, quantity and descr	•				
4.		ns for inventory inwards and outwan process for an embedded board	a1u5.	6	6 hour	<u> </u>	
4.		I for a Beagle Bone Black (BBB) b	oard and board bring		nour	Э	
		odule program on an embedded					
5.		e driver programming –Implemen		r F	3 hour	s	
0.			Total Laboratory Hou		30 hou		
Mod	le of Assessm	ent: Continuous Assessment and					
		Board of Studies 28-07-2022					
	roved by Acad		Date 08-08-20	22			
, .pp			Duit 00-00-20				

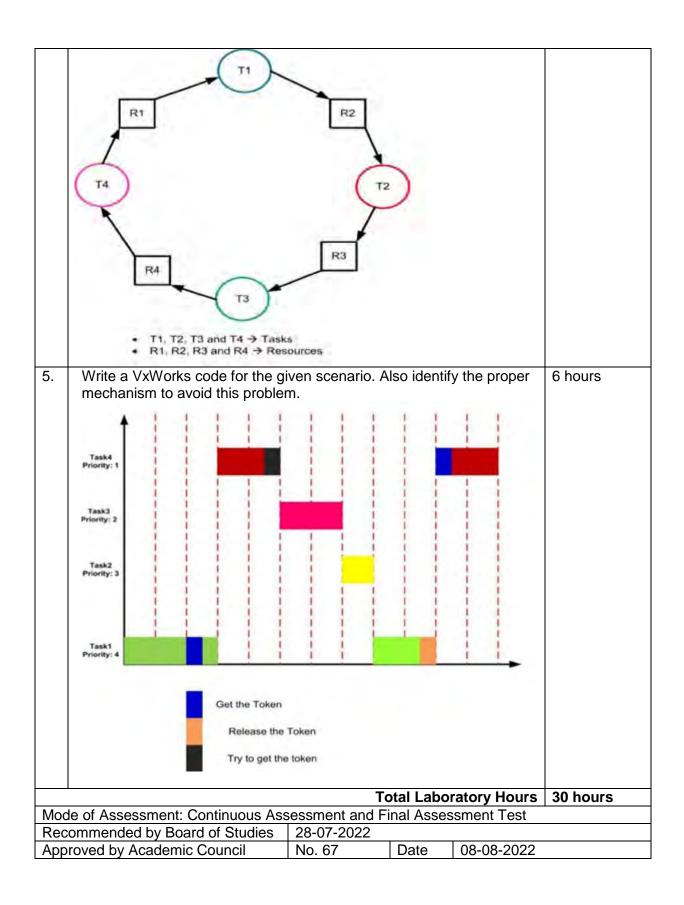
Course Code	Course Title	L	T	Р	С
MEDS504L	In Vehicle Networking	3	0	0	3
Pre-requisite	NIL	Sylla	bus \	/ersi	on
•			1.0		
Course Object	ives				
The course aim					
	g students, a working knowledge of in-vehicle ne				
	exposure to aspects of design, developmer			on a	and
	ance issues associated with in vehicle networkin				
	ng concepts of sensor data capture, storage and	excha	nge of	data	a to
access	emote services				
Course Outco	mes				
The students w					
	ne need for In Vehicle Networking and the	ie ba	sics (	of d	ata
	ication and networking concepts.				
	nend the general protocols, CAN and their u	sage i	n aut	omot	ive
sector.					
	overview of the CAN higher layer protocols like	e CAN	open,	Dev	vice
	CAN and SAE J1939.				
	and the working mechanism of LIN protocol.	tivo fo		ltime	dia
applicati	overview of MOST protocol used in automo	uve ic	or mu	ume	ula
	nend protocols like FlexRay used in automotiv	le for	fault	toler	ant
applicati			raun	torer	ant
Module:1 C	oncepts of In-vehicle networking			ours	
	ata communication and networking–need for In-				
	eference model-multiplexing and de-multiplexir	ig con	cepts-	-vehi	cle
buses.					
	eneral purpose protocols			ours	10
WiFi, Bluetooth	eneral-purpose networks and protocols –Ether	net, i (	CP, U	DP,	IP,
	etworks and protocols		8 hr	ours	
	principles of data exchange-real time data trar	nsmiss			ane
	bit encoding-bit-timing and synchronization-				0
	topology-bus access- physical layer standards				
	AN higher layer protocol		6 ho	ours	
Introduction to	CAN open –Device net–TTCAN–SAEJ1939–ove	erview	of CA	N op	ben
	s in transportation electronics–CAN open standa	ards.			
	N protocol			ours	
	overview – applications – LIN communication	conc	ept m	iessa	age
frame-develop			E ba		
I	OST		5 NC	ours	
	v-data rates-data types-topology -application a lexRay	11005.	6 br	ours	
	luction–network topology–ECU sand bus interfa	l lces_r			nst
	protocol operation controls-media access con				

	symbol processing–coding/decoding unit–Flex Ray scheduling–message processing– wakeup/startup–applications.										
		Contemporary Topics					2 hours				
Gu	est Lectu	res from Industry and, Re	search an	d Deve	lopmer	nt Org	anizations				
			Tot	al Lect	ure ho	urs:	45 hours				
Te	xt Book(	s)									
1.		ue Paret, Multiplexed No					ems CAN, LIN,				
	FlexRay, Safeby-Wire, 2014, 1 <sup>st</sup> edition, Wiley, United States.										
Re	ference										
1.	Chung Ming Huang, YuhShyan Chen, Telematics Communication Technologies										
		hicular Networks: Wirel				l App	plication, 2010,				
		n, Information Science Re									
2.		K Jurgen, Distributed Auto	motive Er	nbedde	ed Syste	ems, ä	2010, 4 <sup>th</sup> Edition,				
		ernational, United States.									
3.		Zurawski, Industrial Co		ion Te	chnolog	gy Ha	andbook, 2015,				
		on, CRC press, United Sta									
4.		Reif, Automotive Mechatro									
	Systems	s Electronics, 2015, 2 <sup>nd</sup> Ed	ition, Spriı	nger, U	nited St	tates.					
Mo	de of Ev	aluation: Continuous Asse	essment,	Digital	Assigni	ment,	Quiz and Final				
As	sessment	t Test	1								
		ded by Board of Studies	07-06-20	)23							
Ар	proved by	y Academic Council	No. 70	Date	24-0	6-202	23				

Course Code	Course Title		LTPC
MEDS505L	Real Time Operating Sys	tem	3 0 0 3
Pre-requisite	NIL		Syllabus version
			1.0
<b>Course Objectiv</b>	es		
The course is aim			
1. Introducin	g the students about Operating Systems	and acquaint	ting students to Real
	rating Systems		
	the students about Task Management and	l Enabling stu	udents to understand
RTOS Scl	5		
	g the students about interprocess	communica	tion and Memory
Managem	ent		
Course Outcom			
	course the will should be able to		
	and the basic components of an operating	system	
	ut the basics of real-time concepts	eyetem	
	nowledge about task management		
	with RTOS scheduling		
	ut IPC synchronization		
	ut IPC data exchange		
	nemory management in RTOS		
	knowledge for developing practical a	pplications of	of modern real-time
systems.			
Module:1 Intro	duction to Operating Systems		6 hours
	ing Systems, Operating Systems functions	Svetom Bo	
	- Monolithic and Microkernel	s, System Do	
	Time Operating Systems		7 hours
Tradeoffs for RT			1 110410
Module:3 Task			7 hours
Process and Three	ads, Process Control Block, Process Attri	butes, POSIX	(Threads
Module:4 RTO			7 hours
	neduling, Rate-Monotonic scheduling, Earl	iest Deadline	first scheduling,
Linux RT schedul			
	Synchronization		7 hours
IPC, Race condit	tions and critical sections, Signals, Atomic	c operations,	Semaphore, Mutex,
	Inversion and Priority ceiling.		7 hours
Module:6 IPC -	FIFO, Messages and Mailbox, Circular and	d owinging by	7 hours
	ory Management		2 hours
	nent, shared memory		2 nouis
	emporary Issues		2 hours
	Total Lecture hours:		45 hours
Text Book(s)			
1. Herma K., R	eal Time Systems, Design for distributed pringer, USA.	Embedded A	pplications, 2011,
	Andrew, Modern Operating Systems, 20	15, 4 <sup>th</sup> ed.,,	Pearson Prentice
Reference Book	S		
1. Ivan Cibrari	Bertolotti, Politecnico di Torino and ystems: Open-Source Operating Systems		
Press, USA			

2.	Lyla B. Das, E Education, India		Systems	an	Integrate	d Appı	roach,	2012,	1 <sup>st</sup> ed.,	Pearson	
	Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final Assessment Test										
Re	commended by Be	oard of Stu	dies	28-07-2022							
Ар	proved by Acaden	nic Council		No. 6	7	Date	-80	08-2022			

Cou	rse Code	Course Title		L	Т	Ρ	С
MED	DS505P	Real Time Operating System Lab	(	0	0	2	1
Pre-	requisite		Sylla	bu	s v	ersi	on
	•		-		.0		
Cou	rse Objective	2S					
The	course is aim	ed at					
1.	Introducing	the students about Operating Systems and acquainting	stuc	dent	ts t	o R	eal
		ing Systems					
2.	Teaching the	e students about Task Management and Enabling stude	nts to	o u	nde	ersta	and
	<b>RTOS Sche</b>	duling					
3.	Introducing t	he students about interprocess communication and Memo	ory N	/lan	age	eme	ent
	rse Outcome						
		course the will should be able to					
		the basic components of an operating system					
		the basics of real-time concepts					
		wledge about task management					
		h RTOS scheduling					
		IPC synchronization					
		IPC data exchange					
		nory management in RTOS					
8.	Apply the kn	owledge for developing practical applications of modern r	eal-t	Ime	e sy	ster	ns.
lin alla							
	cative Experi			<u> </u>			
1.		ode for a simple calculator (+, -, *, /) using functional	0	6 ho	urs		
	•	rgument in a function					
	int add (int ) int sub (int )						
	intmul (int x	• •					
	int div (int x	• /					
	int (*mathop						
		(*mathop)(int , int), int x, int y)					
2.		gram to create multiple threads carrying out different	6	6 ho	urs		
	functions.						
		ccepting a string from the user.					
		isplay the string in upper case.					
		ount the number of vowels in the string					
		punt the number of special characters in the string.					
3.		ram to create three threads, which are implemented usin	g 6	6 ho	urs		
		nters. First thread is for getting a list of numbers from the	Ŭ				
		econd thread is helpful to extract the ODD and EVEN list					
	from the giv	en list, and the third one is used to arrange the ODD and					
	EVEN list of	numbers in an order. Use Mutex semaphore.					
	Note:						
	First Thread	l for getting input data from keyboard.					
	Second Thr	ead to identify the ODD and EVEN list					
	Third Threa	d to get descending ordered ODD list					
		ad to get ascending ordered EVEN list					
	Input data: 5	6, 23, 12, 64, 87, 02, 45, 88, 35, 67.					
	M/rito o M/v	Vorks code for the given scenario. Also identify the prope	r 6	6 ho	urs		
4.	ville a vx v	volke bode for the given boendhe. Also identify the prope		, 110	are		



Course Co	ode	Course Title		L	T	Ρ	С
MEDS506		Wireless and Mobile Communication		3	0	0	3
Pre-requis	site	NIL	S	Syllabi	us v	ersi	on
•				•	1.0		
Course Ob	ojective	es					
The course	e aimed	lat					
1. To kr	now abo	out wireless mobile communication system & relate	d issue	s, and			
2. To ke	ep abr	east of the future of mobile communication					
Course Ou							
The studer							
		ed Cellular Mobile Communication systems					
2. Unde theor		and solve telecommunication design issues usir	ng cellu	ular ar	nd ti	runk	ing
<ol><li>Analy</li></ol>	ze the	effect of multipath channels and suggest a suita	ible mo	del fo	r ind	door	or
		lications.					
		e the implications of multipath parameters in mobile	comm	unicat	ion.		
		Channel coding for Mobile Radio					
		Modulation techniques for Mobile Radio					
7. Get ir	ntroduc	ed to Advanced Communication Systems and Wire	eless St	andar	ds		
	0						
		lar Mobile Systems				ho	
		ommunication Evolution - Types of mobile wireless	s servic	es/sys	stem	is –	ΊG
		munication Technology lar Concept				' ho	uro
		<ul> <li>Frequency reuse – Channel assignment strateg</li> </ul>		landaf			
		system capacity – Trunking & Grade of service – I					
capacity in			mprovi		/era	ye a	JIIU
		e Radio Propagation			a	ho	ire
		pagation Model – Basic Propagation mechanisr	<u>т – Т</u>				
		ay) model – Outdoor Propagation Models: Okumu					
		n Model: Attenuation Factor Model.				nout	
		Scale Propagation models			4	ho	urs
		bile multipath channels – Types of small scale fadir	na – Fa	idina e			
		delay spread and Doppler spread					
		nation Theory and Coding			6	i ho	urs
		ntropy - Coding of memoryless sources: Shannon-	Fano /	Huffm	an c	odir	ng -
		nory: Markov model - Source Coding: Linear and					
		nannel Coding: Convolutional coding, Viterbi decod					
Module:6		plexing & Modulation Schemes				i ho	urs
	emory, I	FIFO, Messages and Mailbox, Circular and swingin	g buffe	rs, RP			
Module:7		nced Communication Systems and			7	' ho	urs
		ess Standards					
	d 5G a	nd beyond wireless standards – WLAN Architectu	re desi	gn and	l WI	IMA)	X –
VANETS		-					
Module:8	Conte	emporary Issues			2	ho	urs
	1						
		Total Lecture hours:			45	i ho	urs
Text Book	(s)						
		aupt, Wireless Communications Systems: An Ir	ntroduc	tion, \	Wile	y-IE	EE
•		ry 2020.	-	,		-	
		rt, Wireless Communication -Principle and Practice	,Prent	ice Ha	II, 20	010.	
Reference							

1.	W.C.Y.Lee, Wireless and Cellular Communication, McGraw Hill, 2006									
2.	2. Schiller, Mobile Communications; Pearson Education Asia Ltd., 2008									
	de of Evaluation: Continuous Asses	sment, Digital	Assignme	ent, Quiz and Final						
Ass	sessment Test									
Re	commended by Board of Studies	28-07-2022								
Ap	Approved by Academic Council No. 67 Date 08-08-2022									

Course Code	Course Title		LTPC
MEDS507L	Electronic Hardware System	Desian	
Pre-requisite	NIL		Syllabus version
•			1.0
Course Objectiv	es	1	
The course is aim	ed at		
1. Emphasing	students the significant role of FPGA in Sy	ystem design a	and development.
	e students to develop program using Har		tive Language and
•	I logic combinational and sequential circui		
	e students acquire knowledge in Interfa	acing periphera	als, Board Design,
	PCB Design and Analysis		
4. Motivating s	tudents to solve real life problem using FF	GA based sys	items.
Course Outcome			
	≠ course the student will be able to		
	d the architecture of FPGA and design flo	AA7	
	Hardware Description Language	~~	
	develop combinational logic circuits using	Verilog and V	HDL program
	develop sequential logic circuits using Ver		
	ripherals with FPGA.	- 3	1 3 3
6. Design the I	•		
7. Design FPG	A based system		
8. Comprehen	d upcoming trends in FPGA.		
			-
-	rammable Logic Devices & FPGAs		4 hours
	PGAs, FPGA technologies, FPGA Arch		
	Design Flow Prototyping with Xilinx FPGA	As, FPGA base	
	ware Descriptive Language		3 hours
	l <b>og/VHDL)</b> - Frequency reuse - Channel assignme	nt atratagiaa	Handoff atratagioa
	system capacity – Trunking & Grade of s		
capacity in cellula		icivice impre	wing coverage and
	eling of Combinational logic circuits		3 hours
	pagation Model – Basic Propagation r	nechanism –	
•	Ray) model – Outdoor Propagation Model		2
Indoor Propagatio	on Model: Attenuation Factor Model.		
Module:4 Mode	eling of Sequential logic circuits		4 hours
	ation of Shift Register -Realization c		
•	BCD counter, Mealy and Moore State Mac		nce detector, FIFO,
	Serial Data Receiver, Serial to parallel dat	a converter.	
	acing peripherals and Board Design		5 hours
	segment display, Stepper Motor, ADO		
	straints –Logical –Electrical -Physical, Po	wer distribution	n for FPGAs, Clock
design, I/O buses		[	
	duction to Packaging &PCB Design	ul alastrania a	4 hours
	on of circuits, packages, boards and fu		
	nrough hole and SMDs) and packaging tre		
	tegrity - The PCB Design Process - Def necking - Working with Properties & Co		
	esign tips for Placement / Fan-out and Wi		
	Speed PCB design and Analysis		5 hours
•	ess Standards		5 110015
	design -EMI/EMC analysis - Thermal m	anagement of	electronic devices
	nermal interface material, Cooling mech		
	are for automotive applications -System		
			-

automotive electronics systems for reliability. Layout constraints for FPGAs, FPGA-basedPCB schematics.Module:8Contemporary Issues2 hours

	aule:8	Contemporary Issues	2 hour							
		т.	otal Lecture ho	ours:	30 hours					
Tex	kt Book	(s)		·						
1.		Monk, Make Your Own ed Boards, 2014, First Editi			rom Schematic Designs to on, India.					
2.	Wayne	e Wolf, FPGA-based Syster	m Design, 2011,	, Re-Prin	t, Prentice Hall, India					
Ret	ference	Books								
1.		Clyde Coombs, Printed Circuits Handbook, 2011, Sixth Edition, McGraw Hill Professional, USA								
2.	lan Gr UK.	out, Digital Systems, Desig	gn with FPGAs	and CPL	Ds, 2012, Re-Print, Newness,					
3.			•	-	vstems Design with Platform Morgan Kaufman Publishers,					
Мо	de of Ev	aluation: Continuous Asse	ssment, Digital	Assignm	ent, Quiz and Final					
	sessmei		-	-						
Re	commer	nded by Board of Studies	28-07-2022							
Ар	proved b	by Academic Council	No. 67	Date	08-08-2022					

	rse Code		Course Title				L			С
	S507P		Hardware Syste	em Desig	n Lab		0	-	-	1
Pre-	requisite	NIL				Syl	labus	s vei	rsio	n
							1	.0		
	rse Objectiv									
-	course is aim									
		students the significar								
2.		e students to develop			re Descr	iptive	Lang	guag	e a	nd
		I logic combinational					_			
3.		e students acquire k		nterfacing	periphe	rals,	Boar	dD	esig	зn,
4		PCB Design and Anal			h a a a d au		_			
4.	wotivating s	tudents to solve real I	ire problem usi	ng FPGA	based sy	/stem	s.			
Cou	rse Outcome									
		<del>z</del> course the student wil	l he able to							
		Hardware Description								
		develop combinationa		usina Ver	ilog and '	VHDI	proc	Iram	1.	
3.		develop sequential lo							-	
		ripherals with FPGA.	9	.9 9			9.5			
		Indic	ative Experim	nents						
1.		bination Logic:-					8 ho	urs		
		6-bit microprocessor	that is capab	le of per	orming I	ooth				
		arithmetic operation.								
2.		uential Logic:-				-	8 ho	urs		
		ntroller for vending m	achine which s	sells candy	/ bars to	r Rs				
0	5, 10 and 20						0 1			
3.		pheral Interfacing:-	ing the followi		onanta (/	$\rightarrow$ 7	8 ho	urs		
		ar speed monitor us splay (b) LEDs (c) S								
		e cars electronic sp								
		quency is proportion								
		of the design use								
	speedomete		function goin		provido					
4.	Task 4:PCB						6 ho	urs		
		CB for a circuit with a	a mixture of an	alog and	digital pa	arts.	20			
		ver planes, and a sing								
		ns that have a commo								
	tool.			-	-					
				tal Labor			30 h	our	s	
		nent: Continuous Asse		nal Asses	sment Te	est				
		y Board of Studies	28-07-2022	r						
	oved by Aca	demic Council	No. 67	Date	08-08-2	022				

Course Code	Course Title	L	Т	Р	С	
MEDS601L	Electromagnetic Interference and	3 0 0			3	
	Čompatibility					
Pre-requisite	NIL	Syllabus version				
•				.0		
Course Objecti	ves					
The course is ai	med at:					
	knowledge about EMI environment					
2. Teaching EMI coupling principles, EMI control techniques and design of						
PCBs for	-					
3. Giving ex	posure to EMI Standards, Regulations and Me	asure	ment	S		
Course Outcon						
	e course, the student will be able to					
1. Understa	nd terminologies of EMI and EMC					
	and understand various EMI coupling mechanis	SINS				
	us EMI Test and Measurement methods					
	various techniques needed to suppress EMI					
	different EMC regulations followed worldwide	c				
	design an Electromagnetic Compatible system and comprehend different techniques neede		Siana	Intoc	rity	
	y to understand various models for EMI/EMC		Siyiia	rinteg	inty	
Module:1 EM	l Environment		4 h	ours		
	nitions and units of Parameters, Sources of E	EML c			and	
radiated EMI, T						
Module:2 EM	I Coupling Mechanisms		6 ha	ours		
Conducted, Ra	diated and Transient Coupling, Common	Imped	dance	Grou	und	
Coupling, Radi	ated Common Mode and Ground Loop	Coup	ling,	Radia	ted	
<b>Differential Mod</b>	e Coupling, Near Field Cable to Cable Couplir	ig, Po	wer N	lains a	and	
Power Supply C						
Module:3 EM	Test and Measurements		8 ha	ours		
	on / Standards / Limits: Units of specifications					
Military standar	ds. EMI Test Instruments / Systems, EMI					
Chamber, Op						
	s/Couplers. EMI Measurement Methods: Milita	ary Te	est Me	ethod a	and	
	Procedures, Calibration Procedures, Modeling interferences					
	Control Techniques			ours		
	ring, Grounding, Bonding, Isolation Tran					
	Cable Routing, Signal Control, Compon	ent S	Select	tion a	and	
	rostatic discharge protection schemes		<b>5</b> la 1			
	MC Standards and Regulations					
	tentional standardizing organizations- FCC, (					
	FCC CE and RE standards, CISPR, CE and RE					
conversation.	CS standards, SAE Automotive EMC standard, Frequency assignment - spectrum					
	stem Design for EMC		8 h/	ours		
· · · · · · · · · · · · · · · · · · ·	ross Talk, Impedance Control, Power Distr	 ihutio			na	
	board Designs and Propagation Delay Pe					
	board bosigns and i ropagation beidy re			wou	,0,	

System Enclosures, Power line filter placement, Interconnection and Number of Printed Circuit Boards, PCB and subsystem decoupling						
	Module:7 Signal Integrity and EMI/EMC Models 5 hours					
	Effect of terminations on line wave forms, Matching schemes for Signal Integrity,					
Effects of	ine discontinuities, Statistica	al EMI/EN	IC mode	ls.		
Module:8	Contemporary Issues				2 hours	
Guest Lec	tures from Industry and, Res	search ar	nd Develo	opment	Organizations	
		Total I	_ecture	hours:	30 hours	
Text Book	(s)					
	n R. Paul,Introduction		magneti	ссотра	ntibility,2010, 2	
Reference	Books					
	W.ott, Electromagnetic Co and Sons, NewJersey.	mpatibility	y Engine	eering,	2011, 1sted. John	
2. Patricl	G. André and Kenneth					
Produ	ct Designers 2014, 1st ed., 5	SciTech F	Publishin	g, New .	Jersey	
Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final						
Assessment Test						
Recomme	nded by Board of Studies	07-06-20	)23			
Approved	by Academic Council	No. 70	Date	24-06-	2023	

	Course Title		L	Т	Ρ	С
MEDS602L	Advanced Digital Image Proces	ssing	3	0	0	3
Pre-requisite	NIL	Syll	abu	s ve	ersi	on
				1.0		
Course Objectiv	es					
The course is aim						
1. Revising t	he basics of digital image processing namel	y; image acquis	ition	, dig	gitizi	ng,
	images in spatial domain, image transfor					
frequency	domain.		-		-	
2. Enabling	the students to acquire knowledge in	n image resto	ratio	on,	ima	age
	ion, image segmentation and object recognit					
3. Motivating the students to apply image processing and classification algorithms for						
solving real life problems and introducing students to upcoming trends in Computer						
Vision.						
Course Outcome	-					
	course, the student will be able to		اما	la	- i	
	end the image acquisition, digitization, and pr					
	nd algorithms and programs for processing an		orm	aoi	nair	1
	with the image enhancement and restoration t different compression techniques to compre					
	ferent segmentation and image represer			for	ima	ana
processing			103	101	IIIIC	aye
	d the pattern recognition approaches for imp	lementing the vi	sual	sve	stem	1.
	omputer vision techniques in various real-time		ouu	, oyc		
Module:1 Imag	e Processing in Spatial Domain			7	' ho	urs
Fundamental ste	one in DIP - Elements of visual percer	tion - Image	Sam	nlir	na a	and
	eps in DIP – Elements of visual percep asic relationship between pixels. Image en					
Quantization - Ba	asic relationship between pixels. Image en	hancement - S	patia	al D	oma	ain:
Quantization - Basic Grey level	asic relationship between pixels. Image en I Transformations – Histogram Processing	hancement - S	patia	al D	oma	ain:
Quantization - Ba Basic Grey leve Sharpening spatia	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters.	hancement - S	patia	al D	oma	ain:
Quantization - Ba Basic Grey leve Sharpening spatia	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Icessing: Models, Transformation	hancement - S	patia	al D atial	oma	ain: ers-
Quantization - Basic Grey leveSharpening spatiaColour image ProModule:2Image	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Incessing: Models, Transformation <b>e Transforms</b>	hancement - S g – Smoothing	patia spa	al D atial 6	filte	ain: ers- urs
Quantization - BaBasic Grey leveSharpening spatiaColour image ProModule:2Image Transform	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. cessing: Models, Transformation e Transforms s: Two dimensional Fourier Transform- Dis	hancement - S g – Smoothing crete cosine tra	patia spa	al D atial 6 rm	filte	ain: ers- <b>urs</b> ulti-
Quantization - BaBasic Grey leveSharpening spatiaColour image ProModule:2Image Transformresolution analys	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. cessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis is – Haar Transform- Discrete Wavelet T	hancement - S g – Smoothing crete cosine tra	patia spa	al D atial 6 rm	filte	ain: ers- <b>urs</b> ulti-
Quantization - BaBasic Grey leveSharpening spatiaColour image ProModule:2Image Transformresolution analystransform. and SV	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. cessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis sis – Haar Transform- Discrete Wavelet T /D	hancement - S g – Smoothing crete cosine tra	patia spa	al D atial 6 rm n –	ilte filte	ain: ers- urs ulti- eve
Quantization - Basic Grey leveBasic Grey leveSharpening spatiaColour image ProModule:2Image Transformresolution analystransform. and SVModule:3Frequencies	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. cessing: Models, Transformation e Transforms s: Two dimensional Fourier Transform- Dis is – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image	hancement - S g – Smoothing crete cosine tra	patia spa	al D atial 6 rm n –	filte	ain: ers- urs ulti- eve
Quantization - BaBasic Grey leveSharpening spatiaColour image ProModule:2Image Transformresolution analystransform. and SVModule:3FrequeRestered	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. cessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis is – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration	hancement - S g – Smoothing crete cosine tra ransform. Karh	patia spa nsfo uner	al D atial rm n – 6	ilte	ain: ers- urs ulti- eve urs
Quantization - BaBasic Grey leveSharpening spatiaColour image ProModule:2Image Transformresolution analystransform. and SVModule:3FrequenceSmoothing frequence	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. cessing: Models, Transformation e Transforms s: Two dimensional Fourier Transform- Dis is – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image	hancement - S g – Smoothing crete cosine tra ransform. Karh	patia spa nsfo uner	al D atial rm n – 6	ilte	ain: ers- urs ulti- eve urs
Quantization - Ba Basic Grey leve Sharpening spatia Colour image Pro Module:2 Imag Image Transform resolution analys transform. and SV Module:3 Frequence Rester Smoothing frequence	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Decessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis bis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency	hancement - S g – Smoothing crete cosine trai ransform. Karh	patia spa nsfo uner Hor	rm 6 mon	ooma filte filte hore ooma filte filte filte filte filte filte	ain: ers- urs ulti- eve urs
Quantization - Ba Basic Grey leve Sharpening spatia Colour image Pro Module:2 Imag Image Transform resolution analys transform. and SV Module:3 Frequence Restor Smoothing frequence filtering. Image Restorati	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Incessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis sis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric	hancement - S g – Smoothing crete cosine transform. Karh domain filters- transformations	patia spa nsfo uner Hor	final D titial 6 rm n – 6 mon Rest	i ho i ho i ho i ho i corat	ain: ers- urs ulti- eve urs ohic .ion
Quantization - Ba Basic Grey leve Sharpening spatia Colour image Pro Module:2 Imag Image Transform resolution analys transform. and SV Module:3 Freque Restor Smoothing freque filtering. Image Restorati techniques, Noise	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Decessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis is – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of	hancement - S g – Smoothing crete cosine transform. Karh domain filters- transformations	patia spa nsfo uner Hor	ntial D ntial 6 rm n – 6 6 Rest	i hou	ain: ers- urs ulti- eve urs uhic s.
Quantization - Ba Basic Grey leve Sharpening spatia Colour image Pro Module:2 Imag Image Transform resolution analys transform. and SV Module:3 Frequence Restor Smoothing frequence filtering. Image Restorati	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Decessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis is – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of	hancement - S g – Smoothing crete cosine transform. Karh domain filters- transformations	patia spa nsfo uner Hor	ntial D ntial 6 rm n – 6 6 Rest	i ho i ho i ho i ho i corat	ain: ers- urs ulti- eve urs uhic s.
Quantization - BaBasic Grey leveSharpening spatiaColour image ProModule:2ImageImage Transformresolution analystransform. and SVModule:3FrequeRestoredSmoothing frequefiltering.Image Restoratitechniques, NoiseModule:4Image	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Decessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis sis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of e Compression	hancement - S g – Smoothing crete cosine trai ransform. Karh domain filters- transformations degradations, Ac	nsfo uner Hor	al D ttial 6 rm n – 6 mon Rest 8	i hou	ain: ers- urs ulti- eve urs whic s. urs
Quantization - BaBasic Grey leveSharpening spatiaColour image ProModule:2ImageImage Transformresolution analystransform. and SVModule:3FrequeRestoredSmoothing frequefiltering.Image Restoratitechniques, NoiseModule:4Image	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Decessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis bis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of e Compression	hancement - S g – Smoothing crete cosine trai ransform. Karh domain filters- transformations degradations, Ac	nsfo uner Hor	al D ttial 6 rm n – 6 mon Rest 8	i hou	ain: ers- urs ulti- eve urs whic s. urs
Quantization - Ba Basic Grey leve Sharpening spatia Colour image Pro Module:2 Imag Image Transform resolution analys transform. and SV Module:3 Freque filtering. Image Restorati techniques, Noise Module:4 Imag Image Compress JPEG and MPEG	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Decessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis bis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of e Compression sion Techniques - Lossy and Lossless cor standards	hancement - S g – Smoothing crete cosine trai ransform. Karh domain filters- transformations degradations, Ac	nsfo uner Hor	ai D ttial 6 7 7 7 7 6 6 6 6 6	i hou	ain: ers- urs ulti- eve urs whic cion s. urs ng-
Quantization - Ba         Basic Grey leve         Sharpening spatia         Colour image Pro         Module:2       Image         Image Transform         resolution analystransform. and SV         Module:3       Freque         Restor         Smoothing freque         filtering.         Image Restorati         techniques, Noise         Module:4         Image Compress         JPEG and MPEG         Module:5       Image	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. Decessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis bis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of e Compression sion Techniques - Lossy and Lossless cor standards	hancement - S g – Smoothing crete cosine transform. Karh domain filters- transformations degradations, Ac	patia spa nsfo uner Hor s, F lapti	ai D attial 6 rm n - 6 Rest ve f 6 End 7	inorp	ain: ers- urs ulti- eve urs whic ion s. urs ng- urs
Quantization - Ba         Basic Grey leve         Sharpening spatia         Colour image Pro         Module:2       Image         Image Transform         resolution analyst         transform. and SV         Module:3       Frequeries         Smoothing frequeries         filtering.         Image Restorati         techniques, Noise         Module:4         Image Compress         JPEG and MPEG         Module:5       Image	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. becessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis bis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image pration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of e Compression sion Techniques - Lossy and Lossless cor standards e Segmentation	hancement - S g – Smoothing crete cosine trai ransform. Karh domain filters- transformations degradations, Ac mpression- Entre	patia spa nsfo uner Hor s, F lapti opy	al D ttial 6 rm n - 6 Rest Ve f 6 End Z Zdge	inorp codi boma filte boma codi bas	ain: ers- urs ulti- eve urs whic ion s. urs ng- urs sed
Quantization - Ba         Basic Grey leve         Sharpening spatia         Colour image Pro         Module:2       Image         Image Transform         resolution analysis         transform. and SV         Module:3       Frequeries         Module:3       Frequeries         Smoothing frequeries         filtering.         Image Restorati         techniques, Noise         Module:4         Image Compression         JPEG and MPEG         Module:5         Image         Detection of disc         segmentation-reg	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. accessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis- sis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of e Compression sion Techniques - Lossy and Lossless correstandards <b>e Segmentation</b> continuities – point, corner, edge detection ion based segmentation- morphological	hancement - S g – Smoothing crete cosine transform. Karh domain filters- transformations degradations, Ac mpression- Entra	patia spa nsfo uner Hor s, F lapti opy -ec -	al D ttial 6 7 7 6 7 6 7 7 9 9 9 9 9 9 9 9 9 9 9 9	Final Stress of the second	ain: ers- urs ulti- eve urs whic s. urs ng- urs sed ned
Quantization - Ba         Basic Grey leve         Sharpening spatia         Colour image Pro         Module:2       Image         Image Transform         resolution analysis         transform. and SV         Module:3       Frequeries         Module:3       Frequeries         Smoothing frequeries         filtering.         Image Restorati         techniques, Noise         Module:4         Image Compression         JPEG and MPEG         Module:5         Image         Detection of disc         segmentation-reg	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. acessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis is – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of e Compression sion Techniques - Lossy and Lossless cor standards <b>e Segmentation</b> continuities – point, corner, edge detection	hancement - S g – Smoothing crete cosine transform. Karh domain filters- transformations degradations, Ac mpression- Entra	patia spa nsfo uner Hor s, F lapti opy -ec -	al D ttial 6 7 7 6 7 6 7 7 9 9 9 9 9 9 9 9 9 9 9 9	Final Stress of the second	ain: ers- urs ulti- eve urs whic s. urs ng- urs sed ned
Quantization - Ba         Basic Grey leve         Sharpening spatia         Colour image Pro         Module:2       Image         Image Transform         resolution analystransform. and SV         Module:3       Freque         Restor         Smoothing freque         filtering.         Image Restorati         techniques, Noise         Module:4         Image Compress         JPEG and MPEG         Module:5       Imag         Detection of disc         segmentation-reg         algorithm Descrit         RANSAC.	asic relationship between pixels. Image en I Transformations – Histogram Processing al filters. accessing: Models, Transformation <b>e Transforms</b> s: Two dimensional Fourier Transform- Dis- sis – Haar Transform- Discrete Wavelet T /D uency domain filtering and Image oration ency domain filters- sharpening frequency on: Image deformation and geometric e characterization, Linear, Position invariant of e Compression sion Techniques - Lossy and Lossless correstandards <b>e Segmentation</b> continuities – point, corner, edge detection ion based segmentation- morphological	hancement - S g – Smoothing crete cosine transform. Karh domain filters- transformations degradations, Ac mpression- Entra	patia spa nsfo uner Hor s, F lapti opy -ec -	al D ttial 6 rm n – 6 6 6 6 7 0 dge wat desc	Final Stress of the second	ain: ers- urs ulti- eve urs ohic ion s. urs ng- urs sed brs,

- 1	tional and accentration along the		( l !			
structural and syntactic classifiers - Clustering techniques - similarity measures -						
hierarchical methods – K-Means algorithm – Cluster evaluation methods. Convolution neural						
	networks, Region-based CNN, fully convolution networks, Multi-modal networks, Hybrid					
	learning methods.					
Mod	ule:7 Computer Vision Appli	cations		4 hours		
Face	e recognition application: persona	I photo collection	ns – Inst	ance recognition application :		
Loca	ation recognition – Machine lear	ning applicatior	is: Deep	voting, transfer learning and		
	ctured regression for image analys	sis and categoriz	zation.			
Mod	ule:8 Contemporary Issues			2 hours		
	T	otal Lecture ho	urs:	45 hours		
Text	Book(s)					
	Rafael C. Gonzalez & Richard E.	Woods "Digita	Ilmage	Processing" 4th Edition 2018		
	Pearson, USA	Woodd, Digita	mage			
	David A. Forsyth and Jean Ponce	e. "Computer Vi	sion <sup>.</sup> A I	Modern Approach", 2ndEdition		
	2012, Prentice Hall, Pearson Edu					
	erence Books					
1.	Richard Szeliski, "Computer vis	sion: Algorithm	and Ar	oplications". Springer- Verlag.		
	London, 2010.			· · · · · · · · · · · · · · · · · · ·		
	K. Jain, Fundamentals of Digi	tal Image Pro	cessing.	2015, 3rd Edition, Pearson		
	Education, USA.	0	0,	, , ,		
	K.P.Soman, K.I. Ramchandran,	N.G.Resmi, Ins	sights in	to Wavelets, From Theory to		
	Practice, 2013, 3rd Edition, PHI L	earning Private	Limited,	New Delhi, India.		
4.	Mark Nixon & Alberto Aguado, I	Feature Extract	on, and	Image Processing, 2013, 3rd		
	Edition, Elsevier's Science & Tecl	hnology Publica	tions, US	SA		
5.	William K. Pratt, Digital Image Pro	ocessing, 2013,	John Wi	ley & Sons, USA.		
Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final						
Assessment Test						
Reco	ommended by Board of Studies	28-07-2022				
	oved by Academic Council	No. 67	Date	08-08-2022		

Course Code	Course Title		L T P C
MEDS603L	Design and Analysis of Algo	orithms	3 0 0 3
Pre-requisite	NIL		Syllabus version
			1.0
Course Objectiv	ES		
This course is ain			
	he students to carry out analysis of vario	us algorithms f	or mainly time and
space con	· · ·	Ū	
2. Teaching	the students how to decide the appropriat	te data type an	d data structure for
a given pr	oblem.		
	the students how to select the best a		
	g various problem characteristics, such	n as the data	size, the type of
operations	s, etc.		
Course Outcome			
	course the student will be able to		
	roficiency in problem solving and programend Combinatorial Optimization	iming.	
	arious algorithms for mainly time and space	o comploxity	
	and Cryptographic Algorithms	complexity.	
	ometric Algorithms		
	arallel Algorithms		
	nd evaluate the given program in terms	of code size	and computational
time.			
8. Select the	e best algorithm to solve a problem	by considering	various problem
	stics, such as the data size, the type of op		
Module:1 Intro			7 hours
	ns in computing, Analysis of Algorithm		
	lem, Instance, RAM model, Principles		
	tion Sort & Complexity Analysis, Divide		
	stitution, Iteration, Recursion tree, Chang	ing variable and	
	binatorial Optimization		5 hours
	namic programming; Greedy Technique ;	Branch & Bou	
	nced Algorithmic Analysis ysis; Online and offline algorith	ms; Random	5 hours nized algorithms,
NP Completeness			lizeu algoninins,
	tographic Algorithms		9 hours
	ew of cryptography; Private-key cryptography	ography and	
	key cryptography; Digital signatures; Sec		
	, authentication etc.		
Module:5 Geor	netric Algorithms		7 hours
U .	properties, intersections; convex hull find	ing algorithms,	Voronoi Diagram,
Delaunay Triangu		1	
Module:6 Paral		L	5 hours
	cclusive versus concurrent reads and	writes; Pointer	r jumping; Brent's
theorem and wor		[	<b>F</b> 1
	s, Auto encoders and GANs	Den Ctakili(	5 hours
	lection; Termination detection; Fault tolera	ance; Stabilizat	
	emporary Issues	I	2 hours
	Total Lecture hours:		45 hours
Text Book(s)			

1.	Anany Levitin, "Introduction to t edition.,2011, Addison Wesley, 20	Ų	nd Analys	sis of Algorithms". 3rd		
2.	Cormen, Leiserson, Rivest and Stein, "Introduction to Algorithms", 3rd edition,					
	McGraw-Hill, 2009					
Ref	ference Books					
1.	1. Ellis Horowitz, "Fundamentals of Computer Algorithms", 2nd Edition, Universities Press, 2008					
2.	M. J. Quinn, Parallel computing – theory and practice, McGraw Hill, 2002					
3.	Sukumar Ghosh, "Distributed Syst					
	& Hall/CRC Computer & Informatic	on Science Ser	ies, 2006			
4.	William Stallings, "Cryptography &	Network Secu	rity", 4th E	Edition, Prentice Hall, 2005		
Mo	Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final					
Ass	Assessment Test					
Ree	commended by Board of Studies	28-07-2022				
App	Approved by Academic Council No. 67 Date 08-08-2022					

Course Code	Course T	itle	L	Т	Р	С
MEDS605L	Hardware Softwar		2	0	0	2
Pre-requisite	NIL	<b>- -</b>		Sylla	ibus v	ersion
					1.0	
Course Objectiv	/es					
The course is air						
1. Providing	adequate knowledge in the n	nodeling of heteroger	eous	embec	lded s	vstems
	design constraint and provide					
	ng the importance of estimation					re and
software	parameters.					
	ng various co-synthesis and					sign of
embedde	d systems with better commu	nication between diffe	erent	module	s.	
Course Outcom		11.4				
	course, the Students will be a					
	erent MOCs based on system	<b>U</b>				
	an alternate design solution b		alysis	5.		
	ne partitioning solution based nd various co-synthesis appro					
	pre-estimate and estimate		etrics	for h	ardwa	re and
	based on cost analysis.		CINCO		arawa	
	ate the pre-estimate and es	stimate the performa	nce r	netrics	for so	oftware
	st analysis.					
	n proper co-simulation method	d based on system sp	ecific	ation.		
	- · · ·					
Module:1 Spe	cification of embedded				4	hours
	ems					
	Co-design - Comparison of c					
	tate oriented, Activity orien		ited,	Data o	oriente	ed and
	-Software CFSMs-Processor					houro
	SW partitioning straints & tradeoffs				4	hours
	Principle of hardware / softw	are manning - Real	timo	schadi	ling -	design
	onstraints on Embedded syste		unic	Schede	ining -	ucsign
	SW partitioning				4	hours
	hodologies				-	
	pes of partitioning - Partiti	ion in granularity –	Kerni	gan -L	in Alg	orithm-
Extended Partition	oning – Binary Partitioning: G0	CLP Algorithm			•	
Module:4 Co-s	synthesis	-			4	hours
	sis – Hardware Synthesis- In	terface Synthesis – C	Co-syr	nthesis	Appro	aches:
	, Cosmos, Polis and COOL.	1				
	mation: Hardware				4	hours
	execution timing and power, C	Case studies				
	mation: Software					hours
	y and execution timing, Worst	Case Execution Time	e, Cas	se stud		• • • •
	simulation & Co-				4	hours
	fication	Detailed Level Co.	Cim··	otion c		itionina
•	<ul> <li>simulation – Abstract Level;</li> <li>nulation using Ptolemy approx</li> </ul>					0
	temporary Issues	aon, virtuar r tututypin	iy, i\d			hours
		I			2	110013
	Total Lecture hours:				30	hours
1		1				

Те	Text Book(s)						
1	Soonhoi Ha, Jürgen Teich, "Ha	ndbook of Ha	rdware/Software	Co-design",			
	. Springer, 2017						
Re	eference Books						
1	Schaumont, Patrick, A," A Practic	al Introduction	to Hardware/Sof	tware Codesign",			
	2013, reprint, Springer, India.						
2	FeliceBalarin, Massimiliano Chiod	o, Paolo Giust	o, Harry Hsieh,	Attila Jurecska,			
	Luciano Lavagno, Claudio Passe	erone, Alberto	Sangiovanni -	Vincentelli, Ellen			
	Sentovich, Kei Suzuki, BassamTabl	bara, "Hardware	-Software Co-Des	sign of Embedded			
	Systems: The POLIS Approach", Sp	oringer, 2012.					
3	http://ptolemy.eecs.berkeley.edu/pto	plemyII/ptII10.0/p	otll10.0.1_201412	217/ptolemy/domai			
	ns/continuous/doc/index.htm						
M	Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final						
As	Assessment Test						
Re	ecommended by Board of Studies	28-07-2022					
Ap	proved by Academic Council	No. 67	Date	08-08-2022			

Course Code	Course Title				т	Р	С
MEDS606L	Modern Automotive Electronics	e Svetome		3	0	0	3
Pre-requisite	NIL	s Systems	Sylla	-			-
Fie-lequisite			Synd		<u>.0</u>	1 310	<i>/</i> //
Course Objective				- 1	.0		
The course is aim							
	fundamental understanding of variou	a outomotic	oontra		otor	~~ (	and
	rumentation involved in automobiles.		, contre	лэу	3101	115 0	JIIU
	various automobile condition measureme	nt and monit	torina n	noch	noni	eme	
	with advanced electronic elements a						
automobi					ispe	5013	
automobi							
Course Outcome	2						
	course the student will be able to						
	end engine management system.						
•	nd the various Ignition and Injection syste	ms					
	ne automotive control mechanisms.						
	different monitoring systems for automob	oiles					
	nd the typical sensors for transportation.						
	nowledge about upcoming trends in autor	notive electr	onics s	syste	ms		
	nowledge attained and develop appropria						
		-					
Module:1 Engir	ne management systems				8	ho	urs
	mponents for engine management syste	m - Open I	oop ar	nd c	lose	ed lo	oop
	Engine cranking and warm up control -A						
speed control.							
	tion and ignition systems				8	ho	urs
Feedback carbur	etor system-Throttle body injection and	multi point f	uel inje	ectio	n s	yste	m–
Injection system	controls -Advantage of electronic ignition	on systems-	-Types	of	soli	d st	ate
ignition systems a	and their principles of operation –Electro	nic spark tir	ning co	ontro	ol, E	Exha	ust
emission control e							
	motive control mechanism				-	ho	
	ement of chassis systems, Vehicle mo						
system, Tyre pre	essure monitoring system, Collision avo	idance syst	tem, T	racti	on	con	trol
system.							
	motive Electronics systems					ho	
	n system Keyless entry system and El						
	s - lighting design - Horn – Warning sy	vstems – Bra	ake act	uatio	on v	varn	ing
systems, Infotainr							
	toring of Automotive systems					ho	
	ystems, oil pressure warning system, eng				syst	em,	air
	system, safety devices-Wind shield wiper	and washer	r, vane	ΞT			
	ors for transportation - I					ho	
	angement-Types of sensors, Oxygen Sei	nsor –Crank	king Se	nsoi	r —F	Posit	ion
Sensors							
	ors for transportation - II					ho	
	vater temperature Sensor–Engine oil pr	essure Sen	sor–Fu	iel r	nete	ering	J –
	nsor and detonation sensor.						
Module:8 Conte	emporary Issues				2	ho	urs
1							
	Total Lecture hours:				45	ho	urs
Text Book(s)							
	, Automobile Electrical and Electronic S	Systems 20	12 4 <sup>th</sup>	Fd	iti∩r	า.	
		,, 20	·_, ·			-,	

	Butter Worth Heinemann, United States					
2.	Bosch Automotive Electrics and Automotive Electronics, 2014, 5 <sup>th</sup> Edition, Springer					
	Vieweg, United States					
3.	Beckwith, T.G, Roy D.Marangoni,	John H.Lien	hard, Me	chanical Measurements,		
	2011, 6 <sup>th</sup> Edition, Addison Wesley,	United States	·			
Ref	erence Books					
1.	Ernest O Doeblin, Measurement	Systems, A	oplication	and design, 2013, 5 <sup>th</sup>		
	Edition McGraw Hill Book Co., United		•	<b>3</b>		
2.	Holman, J.P, Experimental methods	s for Engineer	s McGra	w Hill Book Co. 2011 8 <sup>th</sup>		
۷.	Edition, United States		3, MCOTA	W Thin Dook Go., 2011, 0		
3.	Robert Bosch Gmph, Automotive H	and Book, 20	14, 9"' Edi	ition, Wiley, United States		
4	William, B. Ribbens, Understandir	ng Automotive	e Electror	nics, 2014, 8 <sup>th</sup> Edition Butter		
	Worth Heinemann, United States	5				
Mo	Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final					
-	sessment Test	<i>,</i> 0	0	, .		
Red	commended by Board of Studies	28-07-2022				
Approved by Academic Council No. 67 Date 08-08-2022						
<u> </u>						

Course Code	Course Title	LTP	С
MEDS608L	Intelligent IOT System Design and Architectu		2
Pre-requisite	NIL	Syllabus version	
<u>i io ioquiono</u>		1.0	
Course Objective	es		
The course is aim			
	the characteristics of the Internet of things and its de	esian	
	the students to get familiar with IoT architecture mod		
	nt the students with various security concepts and da		οT
system.			
	p and deploy an IoT enabled prototypes for real-life u	se cases.	
Course Outcome			
	course, the student will be able to		
	the technologies that enable IoT and to interpret the	e different componer	nts
in IoT arch			
	end the concepts of edge computing and edge enable	bled solutions for re-	al-
	trial applications.	protocol starle fra 1	4k ~
	he IoT communication architecture models and the	protocol stack for t	ιne
	tive design of IoT applications on different platforms. The security threats and to design a resilient IoT Archit	ooturo	
•	the data analytics tools and gain knowledge to de-		L
	the data analytics tools and gain knowledge to de	vise an intelligent i	101
system.	loud platform services to perform IoT data analytics	and make the syste	om
intelligent.		and make the syste	
	d develop smart IoT prototypes for use cases under o	discussion	
	d develop smart for prototypes for use cases under t		
Module:1 IoT E	ssentials	4 hou	urs
Evolution of IoT,	IoT characteristics, IoT enabling technologies, Planni	ing for an IoT solution	on,
	elopment - Need and goals, IoT Architecture refere		
	ommunication and security Model, Service oriented		
driven architectur	e, Applications and standards.		
Module:2 Edge		5 hou	Jrs
Introduction to E	dge/Fog computing, Edge nodes and gateway, No	de to edge interface	es,
Protocol and star	ndards for edge devices, IoT edge architecture, IoT	supported hardwar	re-
Raspberry pi, AR	M Cortex Processors, Software Platforms for IoT Ec	lge - Raspbian Pi O	)S,
RIOT, Python par	ckages for edge computing, Edge security, Real time	e applications of ed	lge
computing.			
	communication Architecture and	5 hou	Jrs
Proto			
	nodels for IoT, 6LoWPAN, IPv4/IPv6, IoT communication	tion protocols - MQT	ΓT,
	I, RTLS, RPL, Communication API's.		
	ecurity and Privacy	4 hou	
	curity challenges, IoT security architecture - A tru	-	<u> </u>
	hrough security groups- Specific user access control		
•	Iser Authentication/Authorization methods, Block cha	in for IoT security a	ind
privacy.			
	t Data Analytics	4 hou	
	nalytics, Data generation, Data pre-processing, Han		
	lues, Outliers, Intelligent IoT systems -Supervise	•	
•	algorithms, Deep learning for IoT- Predictive analy	rtics, Python functio	ons
	lata analytics, Big Data analytics and frameworks		
	Analytics in Cloud Concepts rchitecture for data analytics, Elasticity in cloud for	4 hou	

Dat	a base	d decisions, Cloud data la			ta analytics tools, AI Services- analysis, Open source cloud		
		nd services.					
		IoT Architecture for spec			2 hours		
	Roadmap for complete IoT solution, Open source IoT platforms, IoT solution to Health						
					Retail, Logistics and Farming,		
				istry app	lications, Smart city and other		
		s to cater the societal require	ements.				
Мо	dule:8	Contemporary Issues			2 hours		
		Tot	al Lecture ho	ours:	30 hours		
Tex	t Book	(s)					
1.		epBahga, Vijay Madisetti, "li	nternet of Thin	as – A h	ands-on approach",		
		sities Press, 2015.		0			
2.			Security: Four	dations	and Challenges", CRC Press,		
	2016.		2		<b>C</b>		
3.	Dey, H	assanien, Bhatt, Ashour and	Satapathy "Ir	ternet of	f Things and Big Data		
		cs towards Next-Generation	• •		•		
Ref	ference		<u> </u>		<i>.</i>		
1.	Adrian	McEwen & Hakim Cassimal	ly, "Designing	the Inter	rnet of Things", Wiley, 2013.		
2.	Ovidiu	Vermesan, Peter Friess, "Inte	ernet of Thing	s: Conve	erging Technologies for Smart		
	Enviro	nments and Integrated Ecos	ystems", River	Publish	ers, 2013.		
3.		Hersent, David Boswarthick					
		tions and Protocols", Wiley I			<b>3 3</b>		
Мо		aluation: Continuous Assess			ent, Quiz and Final		
	sessmer		<i>,</i> 0	0			
		ded by Board of Studies	28-07-2022				
		y Academic Council	No. 67	Date	08-08-2022		
		<b>,</b>			-		

Course Code		Course Title			L	Т	Ρ	С
MEDS608P	Intelligent IOT S		nd Architect	ture	0	0	2	1
Pre-requisite	NIL	Lab			Sv	labus	s ver	sion
					- ]		.0	
<b>Course Object</b>	ves							
The course is a	med at:							
	re the characteristics							
	le the students to get							
•	aint the students with	n various security	concepts ar	nd data	ana	lytics	in the	e lo l
system. 4. To deve	op and deploy an Io	Fenabled prototy	pes for real-l	life use	case	es.		
Course Outcor	ne							
	e course, the student	will be able to						
	te the technologies the		nd to interpre	et the di	ffere	nt co	mpor	nents
	chitecture.		·				•	
	nend the concepts o	f edge computing	g and edge	enabled	d sol	utions	s for	real-
	ustrial applications.							
	the IoT communica ctive design of IoT a				otoco	ol sta	CK TO	r the
cost-ene	CIVE DESIGN OF IOT A			2000				
					uro			
4. Interpret	the security threats a	and to design a re	esilient IoT A	rchitect		intel	liaen	t IoT
<ol> <li>Interpret</li> <li>Perceive</li> </ol>		and to design a re	esilient IoT A	rchitect		intel	ligen	t IoT
<ol> <li>Interpret</li> <li>Perceive system.</li> </ol>	the security threats a	and to design a re tools and gain k	esilient IoT A knowledge to	rchitect o devise	e an		•	
<ol> <li>Interpret</li> <li>Perceive system.</li> </ol>	the security threats a the data analytics cloud platform servio	and to design a re tools and gain k	esilient IoT A knowledge to	rchitect o devise	e an		•	
<ol> <li>Interpret</li> <li>Perceive system.</li> <li>Analyze intelliger</li> </ol>	the security threats a the data analytics cloud platform servio t.	and to design a re tools and gain k	esilient IoT A knowledge to	rchitect o devise	e an		•	
<ol> <li>Interpret</li> <li>Perceive system.</li> <li>Analyze intelliger</li> </ol> Indicative Expension	the security threats a the data analytics cloud platform servio t.	and to design a re tools and gain k	esilient IoT A knowledge to	rchitect o devise	e an	ake th	ne sy	stem
<ol> <li>Interpret</li> <li>Perceive system.</li> <li>Analyze intelliger</li> </ol> Indicative Expendent 1 Task-1	the security threats a the data analytics cloud platform servio nt. eriments	and to design a re tools and gain k ces to perform lo	esilient IoT A knowledge to oT data analy	rchitect o devise /tics and	e an d ma	ake th	•	stem
<ol> <li>Interpret</li> <li>Perceive system.</li> <li>Analyze intelliger</li> </ol> Indicative Expension <ol> <li>Task-1</li> <li>Program the</li> </ol>	the security threats a the data analytics cloud platform servic t. cloud platform servic eriments e gateways to interface	and to design a re tools and gain k ces to perform lo e the sensors an	esilient IoT A knowledge to oT data analy	vtics and	e an d ma	ake th	ne sy	stem
<ul> <li>4. Interpret</li> <li>5. Perceive system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expension 1 Task-1 Program the communication	the security threats a the data analytics cloud platform servio nt. eriments	and to design a re tools and gain k ces to perform lo e the sensors an	esilient IoT A knowledge to oT data analy	vtics and	e an d ma	ake th	hour	stem
<ul> <li>4. Interpret</li> <li>5. Perceive system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expension 1 Task-1 Program the communicat 2 Task -2	the security threats a the data analytics cloud platform servic at. eriments e gateways to interfact ion protocols to perfo	and to design a ro tools and gain b ces to perform lo ce the sensors an orm secured edge	esilient IoT A knowledge to oT data analy	rchitect devise ytics and tics and	e an d ma	ake th	ne sy	stem
<ul> <li>4. Interpret</li> <li>5. Perceive system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communication 2 Task -2 Explore the	the security threats a the data analytics cloud platform servic t. cloud platform servic eriments e gateways to interface	and to design a re tools and gain k ces to perform lo ce the sensors an orm secured edge forms to build da	esilient IoT A knowledge to oT data analy	rchitect devise ytics and tics and	e an d ma	ake th	hour	stem
<ul> <li>4. Interpret</li> <li>5. Perceive system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communication 2 Task -2 Explore the	the security threats a the data analytics cloud platform servic t. eriments e gateways to interfact ion protocols to perfo open source IoT plat	and to design a re tools and gain k ces to perform lo ce the sensors an orm secured edge forms to build da	esilient IoT A knowledge to oT data analy	rchitect devise ytics and tics and	e an d ma	ake th	hour	stem s
<ul> <li>4. Interpret</li> <li>5. Perceive system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending intelliger 1 Task-1 Program the communication of the co	the security threats a the data analytics cloud platform servic at. eriments e gateways to interfact ion protocols to perfo open source IoT plat applications using vi	and to design a re tools and gain k ces to perform lo e the sensors an orm secured edge forms to build da rtual things.	esilient IoT A knowledge to oT data analy d implement e computing. ta driven inte	rchitect devise ytics and tics and	e an d ma	ake th	hour	stem s
<ul> <li>4. Interpret</li> <li>5. Perceives system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communication 2 Task -2 Explore the Industry 4.0 3 Task-3: Build prototy Internet of M	the security threats a the data analytics cloud platform servic at. eriments e gateways to interfact ion protocols to perfo open source IoT plat applications using vi	and to design a re tools and gain k ces to perform lo e the sensors an orm secured edge forms to build da rtual things.	esilient IoT A knowledge to oT data analy d implement e computing. ta driven inte	rchitect devise ytics and tics and	e an d ma	ake th 8 8 7t	hours	stem s s
<ul> <li>4. Interpret</li> <li>5. Perceives system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communication 2 Task -2 Explore the Industry 4.0 3 Task-3: Build prototy Internet of M	the security threats a the data analytics cloud platform service t. eriments e gateways to interfact ion protocols to perfo open source IoT plat applications using vi /pes and explore UI/U fedical Applications.	and to design a re tools and gain k ces to perform lo to be the sensors and forms to build data forms to build data rtual things.	esilient IoT A knowledge to oT data analy d implement e computing. ta driven inte s tools for	vtics and vtics and various	e an d ma	ake th 8 8 7t	hour	stem s s
<ul> <li>4. Interpret</li> <li>5. Perceive system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communicat 2 Task -2 Explore the Industry 4.0 3 Task-3: Build prototy Internet of M 4 Task-4: Explore the of	the security threats a the data analytics cloud platform service t. eriments e gateways to interfact open source IoT plat applications using vi /pes and explore UI/I ledical Applications.	and to design a re tools and gain k ces to perform lo se the sensors an orm secured edge forms to build da rtual things. JX, data analytics	esilient IoT A knowledge to oT data analy d implement computing. ta driven inte s tools for n environme	vtics and vtics	e an d ma	ake th 8 8 7t	hours	stem s s
<ul> <li>4. Interpret</li> <li>5. Perceive system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communicat 2 Task -2 Explore the Industry 4.0 3 Task-3: Build prototy Internet of M 4 Task-4: Explore the of monitoring /	the security threats a the data analytics cloud platform service t. eriments e gateways to interfact open source loT plat applications using vi /pes and explore UI/L fedical Applications.	and to design a re tools and gain k ces to perform lo se the sensors an orm secured edge forms to build da rtual things. JX, data analytics	esilient IoT A knowledge to oT data analy d implement computing. ta driven inte s tools for n environme	vtics and vtics	e an d ma	ake th 8 8 7t	hours	stem s s
<ul> <li>4. Interpret</li> <li>5. Perceive system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communicat 2 Task -2 Explore the Industry 4.0 3 Task-3: Build prototy Internet of M 4 Task-4: Explore the of	the security threats a the data analytics cloud platform service t. eriments e gateways to interfact open source loT plat applications using vi /pes and explore UI/L fedical Applications.	and to design a re tools and gain k ces to perform lo ethe sensors an orm secured edge forms to build da rtual things. JX, data analytics	esilient IoT A knowledge to oT data analy d implement e computing. ta driven inte s tools for n environments and other in	rchitect devise /tics and : various elligent ntal	e an d ma s loT	ake th 8 8 71 71	hours	stem s s s
<ul> <li>4. Interpret</li> <li>5. Perceives system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communicat 2 Task -2 Explore the Industry 4.0 3 Task-3: Build prototy Internet of N 4 Task-4: Explore the of monitoring / intelligent loo	the security threats a the data analytics cloud platform service t. eriments e gateways to interfact ion protocols to perfo open source IoT plat applications using vi /pes and explore UI/L dedical Applications. open source cloud plat smart agriculture / in <u>F use cases.</u>	and to design a re tools and gain k ces to perform lo tools and gain k ces to perform lo to perform lo to perform secured edge forms to build da rtual things. JX, data analytics atforms to perform ternet of vehicles	esilient IoT A knowledge to oT data analy d implement e computing. ta driven inte s tools for n environments and other in <b>Total Labor</b>	rchitect devise /tics and : various elligent ntal novativ	e an d ma s loT	ake th 8 8 71 71	hours	stem s s s
<ul> <li>4. Interpret</li> <li>5. Perceives system.</li> <li>6. Analyze intelliger</li> </ul> Indicative Expending 1 Task-1 Program the communicat 2 Task -2 Explore the Industry 4.0 3 Task-3: Build prototy Internet of N 4 Task-4: Explore the of monitoring / intelligent lo Mode of Assess	the security threats a the data analytics cloud platform service t. eriments e gateways to interfact open source loT plat applications using vi /pes and explore UI/L fedical Applications.	and to design a re tools and gain k ces to perform lo tools and gain k ces to perform lo to perform lo to perform secured edge forms to build da rtual things. JX, data analytics atforms to perform ternet of vehicles	esilient IoT A knowledge to oT data analy d implement e computing. ta driven inte s tools for n environments and other in <b>Total Labor</b>	rchitect devise /tics and : various elligent ntal novativ	e an d ma s loT	ake th 8 8 71 71	hours	stem s s s

Course Code	Course Title			L	Т	Ρ	С
MEDS609L	Fault Tolerance and Dependabl	e Systems		3	0	0	3
Pre-requisite	NIL		Syll	-	-	-	-
			Oyn		1.0		011
Course Objectiv	/es				1.0		
The course is ain							
1. Providing	students with a working knowledge of	the potential	l fau	lts a	and	err	ors
	in an embedded system.	·					
	knowledge in concepts of fault detection a	and fault tolera	nce.				
	students dependability concepts						
	the fault tolerance strategies and design to	echniques.					
		•					
<b>Course Outcom</b>	e						
	course, the student will be able to						
	wledge in concepts involving fault detectior	ו					
	end dependability concepts						
	nd tolerance and correction mechanisms ir						
	nd develop dependable systems for missio		catior	ns.			
	nd Fault tolerance in interconnected syster	ns.					
	nd Fault tolerance in distributed systems.						
7. Apply Dep	pendability evaluation techniques and Tool	S					
Module:1 Faul	ts and Failures				4	ho	urs
Fault - error, failu	ire - faults and their manifestation - classifi	cation of faults	and	failı	ires		
	endability Concepts					ho	urs
Dependable syst	em - techniques for achieving dependabilit	y - dependabil	ity m	easi	ures	3	
	t Tolerance Strategies					ho	urs
Fault detection -	masking - containment - location - recon	figuration - rec	over	V			
	t tolerant design techniques	5		/	8	ho	urs
	ancy - software redundancy - time redund	ancy - informa	tion r	edu			
	t tolerance in Interconnects				6	ho	urs
	graphs - fault tolerant ATM switches					-	
	t Tolerance in Distributed Systems					ho	
	al problem - consensus protocols - chec		d rec	over	у –	sta	ble
<u> </u>	D architectures - data replication and resilie	ency					
tools	-				6	ho	urs
	kov chains - HIMAP tool						
Module:8 Cont	temporary Issues				2	ho	urs
1							
	Total Lecture hours:				45	ho	urs
Text Book(s)		L					
	, C. Mani Krishna, Fault-Tolerant System	s, 2011. Mora	an K	aufr	nan	n, S	San
Francisco.	,	, . , <b>.</b>				, -	
	va, Fault-Tolerant Design, 2013, Springer,	Sweden.					
Reference Book		·					

 D. P. Siewiorek and R. S. Swarz, Reliable Computer Systems: Design and Evaluation, 2014,3rded., Digital Press, Pennsylvania.
 Alessandro Birolini, Reliability Engineering: Theory and Practice, 2017, 8<sup>th</sup> ed., Springer-

Verlag Berlin Heidelberg, Spain. Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final Assessment Test

Assessment lest			
Recommended by Board of Studies	28-07-2022		
Approved by Academic Council	No. 67	Date	08-08-2022

Course Code	Course Title			L	Т	Ρ	С
MEDS611L	Parallel Processing and Computing			3	0	0	3
Pre-requisite	NIL		Sv	labı		_	-
i io ioquiono			- Cy		1.0		011
Course Objectiv	PS						
The course is aim							
	the students to understand the scope, design and	1 mor	പില്പ	nara	alloli	sm a	hne
	e parallel computing architecture	11100		purc	incii		
	students to do analytical modelling and performa	inco (	of nar	امالد	nro	aran	ne
0	students to solve a complex problem with messa		•		•	gran	13
0	ning with CUDA and analyse complex problem with messa	• •		•		nom	onv
programm	• • • •	115 W	nun e	mare	uı		Ory
programm	ling						
Course Outcom							
	course the student will be able to						
	d the fundamentals of parallel processing						
	he scheduling loops and process execution						
	e parallel system architecture with CUDA						
	and the kernel based parallel programming conce	nte					
	performance consideration for parallel processing						
	arious parallel computation patterns						
	pare matrix vector multiplications						
Module:1 Intro	duction to Parallel Processing				5	i ho	urs
	ng – Concepts and Terminology- Parallel Comput	er Me	mor	/ Arc	hite	cture	es -
	ning Models - Designing Parallel Programs- Perfo						
	ed Memory Programming			í		i ho	urs
	hreads - Scope of Variables - Reduction Clause	– Dir	ective	es –	Sch	edu	ling
	Cache coherence and False Sharing - Thread Sa						
sort, Odd- even tr	•	,		•			
Module:3 Para	lel Computing				6	6 ho	urs
Portability and S	calability- Introduction to CUDA, Data Parallelis	sm a	nd T	hrea	ds-N	Лет	ory
Allocation and D	ata Movement API- Kernel-Based SPMD Par	allel	Prog	amn	ning	-Ker	nel
	rogramming, Multidimensional Kernel Configura						
Multiplication							
Module:4 Kern	el-Based Parallel Programming				6	6 ho	urs
Thread Schedulin	g-Control Divergence- Memory Model and Localit	y - C	UDA	Men	norie	es-T	iled
	ns- Tiled Matrix Multiplication- Tiled Matrix Mult				el-H	and	ling
Boundary Conditi	ons in Tiling A Tiled Kernel for Arbitrary Matrix D	imen	sions	5			
	ormance Considerations					i ho	
Warps and Thre	ad execution - Global Memory Bandwidth - DR	AM E	3and\	vidth	1 - N	Лет	ory
	mic partition of execution resources						
	duction to Packaging &PCB Design					6 ho	
Convolution- Tile	ed Convolution- 2D Tiled Convolution Kerne	- Da	ata F	Reus	e ir	ד ו	iled
	action- A Basic Reduction Kernel- Scan (Prefix	Sum)	- A	Wor	k-In	effici	ent
	ork-Efficient Parallel Scan Kernel						
	Speed PCB design and Analysis				6	i ho	urs
Wire	ess Standards						
Parallel SpMV U	sing CSR-Padding and Transposition-Using Hy	/brid	to C	ontro	D P	addi	ng-
Sorting and Partit	ioning for Regularization					<u> </u>	-
Module:8 Cont	emporary Issues				2	? ho	urs
							_

		Tot	al Lecture ho	ours:	45 hours		
Tex	xt Book	(s)					
1.							
	Parallel Computing, 2011, Second Edition, Addison Wesley Professional, UK.						
2.	2. David B. Kirk and Wen-mei W. Hwu, Programming Massively Parallel Processors: A Hands-on Approach, 2016, Third Edition, Morgan Kaufmann Publishers, US.						
Re	ference	Books					
1.							
	Mode of Evaluation: Continuous Assessment, Digital Assignment, Quiz and Final Assessment Test						
Re	commer	nded by Board of Studies	28-07-2022				
Ар	proved b	by Academic Council	No. 67	Date	08-08-2022		

Course Code	Course Title		Т	Р	С
MEDS613L	Cloud Computing	3	0	0	3
Pre-requisite	NIL	-	abus	versi	on
		<b>_</b>	1.		
Course Object	ives	I		-	
	imed at making the students to				
	re the cloud computing concepts.				
2. To get fa	miliar with cloud orchestration to support elastic	city and	d edg	ge dev	/ice
availabili	J				
	t knowledge on cloud security and to develop la	rge sca	ale e	mbedo	bed
application	ons.				
Course Outoo					
Course Outcou	e course, the students will be able to				
	nend the basics of cloud computing, clou	d mo	عامل	and	ite
	vity to develop smart applications.	u mo	ucis	anu	11.5
	the virtualization techniques and Interpret a sui	table c	loud	mode	el to
	the business needs by interpreting different s				
	ent models.			2	
	the division of responsibility and managing	risks	in t	he clo	bud
environn					
	the system level security threats and to desi	gn a i	resilie	ent clo	oud
Architect	ure. te the OS security concepts and ability to des	ian o i	rocili	ont d	aud
architect	5 1 5	iyii a i	esiii		Juu
	and develop platform-specific tools and manage	aemen	it coi	nsoles	s to
	I-time embedded system applications.				
	oud Computing Fundamentals			hours	
Characteristics	of Cloud computing - Cloud Architecture- De	sign co	onsic	leratio	ns-
Edge device di	scovery, Cloud orchestration, Cloud connectivi	ty for (	edge	devic	æs,
	Cloud Services – IaaS, PaaS, SaaS, XaaS.		6	hour	•
	Load Balancing and fault tolerance, Sc	alabilit		hour: Elastic	
	Replication, Monitoring, Software defined No				
	zation, Mapreduce programming model.	CIWOIN	ing,	NCLW	OIK
	oud Computing Services		6	hour	s
	ces, Storage Services, Database services, A	pplicat			
Data Analytics	Services for predictive maintenance, Deployme	nt and	Mar	nagem	ent
Services, Identi	ty and Access management services.				
	oud Risk Analysis			hours	
	s in the Cloud. Retaining Information Secu				
55		egotiat	ing	Secu	irity
	vith Vendors, Service Level Agreement. cure Cloud Architecture		2	hour	6
	vork Access through Security Groups. Specific L	Isor A			
	Id Authentication/Authorization, Data Confidenti				
	n Motion and Data at Rest, Identifying Your Sec				
Management.					1
managomonti					

Program threats, System threats, Locking Down Cloud Servers. PatchirVulnerabilities, Filtering Traffic by Port Number, Operating System Security Policieand Procedures.Module:7Cloud Platforms7 hours					
and Procedures.     Module:7     Cloud Platforms     7 hours					
Module:7         Cloud Platforms         7 hours					
Google cloud, Microsoft Azure, Amazon Web services, Cloud application					
development using third party APIs, Resource pooling, Cloud service migration					
Federated cloud platform, Embedded systems applications on cloud.					
Module:8Contemporary Issues2 hours					
Total Lecture hours: 45 hours					
Text Book(s)					
1. Cloud Computing theory and Practice, 3rd Edition by Dan Marinescu, Elsevie					
2. Cloud computing: Methodology, Systems and Applications, Lizhe Wang, Raj					
Ranjan, Jinjun Chen, CRC Press, 2017.					
3. Cloud Computing Principles and Paradigms, Rajkumar Buyya, James Brober					
Andrzej Goscinski, John Wiley & Sons, Inc. 2011.					
Reference Books					
1. John R. Vacca, "Cloud Computing Security: Foundations and Challenges", CR					
Press, 2016.					
2. Pearson, Siani, Yee, George, "Privacy and Security for Cloud Computing					
Springer, 2013.					
3. Nick Antonopoulos, Lee Gillam, Cloud Computing: Principles, Systems ar					
Applications, Springer, 2015.					
4. Toby Velte, Anthony Velte, Robert Elsenpeter, Cloud Computing, A Practic					
Approach, McGraw Hill, 2010.					
Mode of Evaluation: Continuous Assessment Test, Digital Assignment, Quiz ar					
Final Assessment Test					
Recommended by Board of Studies 07-06-2023					
Approved by Academic Council No. 70 Date 24-06-2023					

Course Code	Course Title	L	Т	Р	С
MEDS614L	Cyber Physical Systems	3	0	0	3
Pre-requisite	NIL	-	-	versi	-
The requisite		<u> </u>	<u>ubus</u> 1.		011
Course Objectiv	les			•	
The course is ain					
	uce the fundamentals of modelling cyber-physical sectors and the sector of the sector	sical s	svster	ns (Cl	PS)
	g of both discrete and continuous dynamics		Jere		-,
	e an overview of design automation and verific	cation	prob	lems v	vith
a system	s perspective for designing, monitoring, and m	anag	ing la	rge so	ale
infrastruc		-	-	-	
	le exposure to practical applications of mode				
	ase studies and able to address real-world prob	olems	throu	igh Cy	ber
Physical	Systems.				
Course Outcom					
	course, the student will be able to			6.0	
	id the need and purpose of the different co	mpor	ients	of Cy	ber
Physical S					
	sign, and prototype eir own system with different applications				
	ems with mathematical modelling in various fi	u shla	with n	arame	tric
measures	ents with mathematical modeling in various in		mui p	arame	uic
	he performance of a Cyber Physical System				
	ds on experience in using state-of- art hardwar	e and	softw	<i>iare</i> to	ols
	sis and learning for cyber-physical system des				
	ety, privacy, and security for the designed cybe				
<ol><li>Deploy cy</li></ol>	ber physical systems in practical applications I	ike In	ternet	of thi	ngs
(loT), swa	rm systems, edge computing, and smart gatev	vays.			
		1			
Module:1 Cyl	per Physical Systems			ours	
	view, requirements, features and examples				
	n the real world; Key design drivers and qualit n confidence CPS, Interface between Physica				
	toSAR, IIOT implications, Building Automa				
Transportation, E		uon,	meun		5,
	S - Modelling Dynamic Behavior		7 h	ours	
	of design and validation of CPS, Relationship	betwe			beb
	PS, Design Process- Modeling, Design, A				
	rete Dynamics. Hybrid Systems - State Mac				
Models of Comp					
Module:3 CP	S- Design and Implementation		7 ho	ours	
	ating Systems. Networking Embedded Sys	tems.	Sen	sors a	and
	edded Processors - Memory Architecture -		t and	l Outp	out.
	heduling, CPS case study- design, implement	ation			
	S- Analysis and Verification			ours	
	Temporal Logic - Equivalence and Refiner				
norformonoo D	achability analysis Quantitative analysis	CDC	<u> </u>	· · · · ·	
Analysis, Verifica	eachability analysis - Quantitative analysis.	CP3	Cas	e Stu	ay-

Module:5 CPS- Network and Protocol	7 hours					
CPS Communications, CPS Network – Wireless Hart, CA						
Scheduling Real Time CPS tasks, data analysis, ar						
Hardware, CPS Models and Aspects, Internet of Things Architectures, Properties,						
and Security Requirements; CPS vs IoT; Network and						
Constrained Application Protocol: Application Layer Con						
Protocol for the Internet of Things; Datagram Transport I	Layer Security. Overview					
and Supporting Constrained Application Protocol.	C haven					
Module:6 CPS- Security Issues and Controls	<u> </u>					
Security Challenges – Quantifying Security & Risk –						
Readiness – Security Technologies. CPS Security Vulnera						
Attacks, Security Control and Solutions. Securing Ca						
Autonomous Vehicle, Networking Technologies, Wire						
Transportation, IPv6-Connected Internet of Thing	s, Machine-to-Machine					
Communications, Mobile Cloud Computing.						
Module:7 Machine Learning for Cyber Physical	6 hours					
Systems						
Introduction to Machine Learning. Mathematical Optin	nization - Planning and					
guidance. Basics of Neural Networks. Deep Learning	g. Supervised Learning,					
Unsupervised Learning, Ensemble Learning, Machine Lea						
Systems: Vehicular CPS, Smart Cities and the Internet of						
CPS.	5 5.					
Module:8 Contemporary Issues	2 hours					
Module:8 Contemporary Issues	2 hours					
Module:8 Contemporary Issues Total Lecture ho						
Total Lecture ho	ours: 45 hours					
Total Lecture ho	ours: 45 hours					
Total Lecture ho	ours: 45 hours					
Text Book(s)         1.       E.A.Lee and S A Shesia, (2018), Embedded system I Approach, Second Edition, MIT Press.	Durs: 45 hours Design: A Cyber-Physical					
Text Book(s)         1.       E.A.Lee and S A Shesia, (2018), Embedded system I Approach, Second Edition, MIT Press.         2.       Ragunathan (Raj) Rajkumar, Dionisio de Niz and M	Durs: 45 hours Design: A Cyber-Physical Iark Klein, (2017), Cyber					
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Course Code	Course Title	L	Т	Р	С
MEDS614P	Cyber Physical Systems Lab	0	0	2	1
Pre-requisite	NIL	Sylla		versio	'n
			1.0		
Course Object					
The course is a					
	duce the fundamentals of modeling cyber-phy og of both discrete and continuous dynamics	sical s	ystem	IS (CP	'5)
	de an overview of design automation and verif	ication	nrohle	ems w	<i>i</i> ith
	ns" perspective for designing, monitoring, and				
infrastru		5	5	5	
	de exposure to practical applications of mod				
	case studies and able to address real-world pro	blems	throu	gh Cyt	ber
Physical	Systems.				
Course Outco	mor				
	e course, the student will be able to				
	lesign, and prototype				
	heir own system with different applications				
	stems with mathematical modeling in various	fields v	vith pa	aramet	tric
measure					
4. Have ha	nds on experience in using state-of- art hardwa	re and	softwa	are too	)IS.
	and automotive electronics architecture and connectivity, control) design.	(senso	rs, a	clualo	rs,
	and highly dynamic networked systems (li	fetime	mana	aneme	nt
	vity, adaptation).		mane	igeine	
	and Security/safety for automotive systems.				
	and Integration of learning and optimizatio	n into	safet	ty-criti	cal
systems					
Indicative Exp	eriments				
	bedded C/C++ Programming for CPS		7	hours	
	task 1: Port Handling, Timer initialization			nours	
	task 2: Waveform Generation.				
	task 3: Serial Port Controller				
	task 4: Interrupt Generation				
	task 5: Motor Control using Embedded C				
	task 6: PLC Emulation using Embedded C				
	task 7: Pulse Width Modulation				
	Benchmark IoT for CPS		6	hours	;
Sub tas	k 1: Deployment of Sensors and IoT devices				
	sk 2: Control of sensors using Open APIs lik	e MQT	т,		
COAP					
	k 3: Addition of new sensors to CPS-IoT.				
	k 4: Control of Servo Motors using Embedded	Softwa			
	deling and Simulation of CPS using Ptolemy		9	hours	)
	task 1: Computation Models				
Sub	task 2: Process Networks				

	Sub task 3: Discrete Events	
	Sub task 4: Data Flow	
	Sub task 5: Rendezvous Based models	
	Sub task 6: Synchronous/Reactive	
	Sub task 7: 3D Visualization	
	Sub task 8: Continuous Time Model	
	Sub task 9: Hybrid Systems Modeling	
	Sub task 10: Sensor Network Design	
	Sub task 11: Scientific workflows	
	Sub task 12: Modeling and Simulation of Wireless Networks	
4	Task-4: Matlab toolboxes	8 hours
	Sub task 1: Simulink, Stateflow, Define embedded systems and	
	cyber-physical systems (CPS) and give examples	
	Sub task 2: Understand various modeling formalisms for CPS,	
	such as hybrid automata, state-space methods, etc.	
	Sub task 3: Understand CPS design, modeling, and analysis	
	Compare architectural design trade-offs in CPS	
	Sub task 4: Design CPS and analyze models of CPS to see if	
	they meet their specifications and requirements	
	Sub task 5: Understand methods for verification and validation	
	of CPS such as simulation, testing, model checking, etc.	
	Sub task 6: Understand and appreciate engineering design and	
F	analysis difficulties in CPS disciplines	
5	Additional Exercises	
	Matlab and Simulink	
	Robotic Control and Simulation	
	Drone Control	
	Automotive Systems	20 havea
	Total Laboratory Hours	
	ode of Assessment: Continuous Assessment and Final Assessment T	ยรเ
-	ecommended by Board of Studies 07-06-2023	
T Aľ	oproved by Academic Council No.70 Date 24-06-2023	

Course Code	Course Title	L 3	Т	Ρ	С	
MEDS615L	EDS615L 5G and Future Generation Communication Systems				3	
Pre-requisite	NIL	Svlla	abus	vers	ion	
		<u> </u>	1.0			
Course Object	tives					
	imed at making the students to					
	erstand standardization and the evolution of	neX	t Gei	herat	tior	
networks.						
	re the new terminologies and concepts relating to	NR.				
	de exposure to different 5G use cases and practic		plicat	ions.		
Course Outco	•		<b>I</b>			
	e course, the students will be able to					
	and the 3GPP 5G standards and spectrum.					
	hend the key concepts, terminologies and access	metho	ods of	5G [	١R	
	e the 5G Random Interface Architecture.				••••	
	the MIMO techniques for 5G NR.					
5. Evaluate	e different 5G use cases and applications.					
	the future Generation and private networks relating	na to a	applic	atior	IS.	
Module:1 5G			4 ho			
	reless Technologies (1G to 4G), What is 5G? Wh	v do			G	
5G Standardiz	ation - 3GPP and IMT2020 - Spectrum for 5G	. 5G	deplo	vme	nt	
Options, Challe				<i>.</i>		
	NR – Terminologies and Concepts		7 ho	urs		
5G Network Terminology and concepts - Channel Access methods - Comparison,						
Massive centra	erminology and concepts - Channel Access methalised RAN, Cognitive Radio, Vehicular comm					
Massive centra slicing.	alised RAN, Cognitive Radio, Vehicular comm		ion, I	Vetw		
Massive centra slicing. Module:3 5G	alised RAN, Cognitive Radio, Vehicular comm NR Radio Interface architecture	unicat	ion, 1 8 ho	Vetw urs	ork	
Massive centra slicing. Module:3 5G Overall system	alised RAN, Cognitive Radio, Vehicular comm <u>NR Radio Interface architecture</u> architecture - Radio Protocol Architecture, QoS ha	unicat	ion, T <b>8 ho</b> g, Use	Vetw urs er Pla	ork	
Massive centra slicing. Module:3 5G Overall system Protocols-Radio	alised RAN, Cognitive Radio, Vehicular comm <b>NR Radio Interface architecture</b> architecture - Radio Protocol Architecture, QoS ha o Link Control - Medium-Access Control – Physic	unicat	ion, T <b>8 ho</b> g, Use	Vetw urs er Pla	ork	
Massive centra slicing. Module:3 5G Overall system Protocols-Radio Control Plane F	Alised RAN, Cognitive Radio, Vehicular comm <b>NR Radio Interface architecture</b> architecture - Radio Protocol Architecture, QoS ha b Link Control - Medium-Access Control – Physic Protocols, Mobility.	unicat	ion, T <b>8 ho</b> g, Use	Vetw urs er Pla nctio	ork	
Massive centra slicing. Module:3 5G Overall system Protocols-Radia Control Plane F Module:4 Ad	Alised RAN, Cognitive Radio, Vehicular common <b>NR Radio Interface architecture</b> architecture - Radio Protocol Architecture, QoS has b Link Control - Medium-Access Control – Physic Protocols, Mobility. <b>vance Multiple access and MIMO techniques</b>	unicat andlin al Lay	ion, 1 8 ho g, Use er fur 8 ho	Vetw urs er Pla nction urs	ork ane	
Massive centra slicing. Module:3 5G Overall system Protocols-Radio Control Plane F Module:4 Ad Overview of Ma	Alised RAN, Cognitive Radio, Vehicular community <b>NR Radio Interface architecture</b> architecture - Radio Protocol Architecture, QoS ha b Link Control - Medium-Access Control – Physic Protocols, Mobility. <b>Vance Multiple access and MIMO techniques</b> ulti-Antenna Techniques in LTE, Moving to 5G (	unicat andlin al Lay Cellula	ion, 1 <b>8 ho</b> g, Use rer fur <b>8 ho</b> ar with	Vetw urs er Pla nction urs n Lar	ane ane	
Massive centra slicing. Module:3 5G Overall system Protocols-Radio Control Plane F Module:4 Ad Overview of Massale Antenna	NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS ha o Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G ( Arrays, Antenna-array Architectures for 5G Cellu	andlin al Lay	ion, 1 8 ho g, Use er fur 8 ho ar with assive	Vetw urs er Planction urs n Lar e Mll	ane ns ge MC	
Massive centra slicing. Module:3 5G Overall system Protocols-Radia Control Plane F Module:4 Ad Overview of Ma scale Antenna for Evolved LTE	Alised RAN, Cognitive Radio, Vehicular comm NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS ha b Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV	andlin andlin al Lay Cellula Iar, M Vave a	ion, 1 8 ho g, Use er fur 8 ho ar with assive	Vetw urs er Pla nction urs n Lar e MII mW	ork ane ns ge WC ave	
Massive centra slicing. Module:3 5G Overall system Protocols-Radia Control Plane F Module:4 Ad Overview of Ma scale Antenna for Evolved LTE	NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS ha o Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G ( Arrays, Antenna-array Architectures for 5G Cellu	andlin andlin al Lay Cellula Iar, M Vave a	ion, 1 8 ho g, Use er fur 8 ho ar with assive	Vetw urs er Pla nction urs n Lar e MII mW	ork ane ns ge VIC ave	
Massive centra slicing. Module:3 5G Overall system Protocols-Radio Control Plane F Module:4 Ad Overview of Mascale Antenna for Evolved LTE Systems (Above NOMA.	Alised RAN, Cognitive Radio, Vehicular communication <b>NR Radio Interface architecture</b> architecture - Radio Protocol Architecture, QoS has be Link Control - Medium-Access Control – Physice Protocols, Mobility. <b>Vance Multiple access and MIMO techniques</b> ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI	andlin andlin al Lay Cellula Iar, M Vave a	ion, T 8 ho g, Use er fur 8 ho r with assive and m Techn	Vetw urs er Planction urs urs n Lar e Mill mWa ique	ork ane ns ge VIC ave	
Massive centra slicing. <b>Module:3 5G</b> Overall system Protocols-Radia Control Plane F <b>Module:4 Ad</b> Overview of Ma scale Anterna for Evolved LTE Systems (Abov NOMA. <b>Module:5 5G</b>	Alised RAN, Cognitive Radio, Vehicular communication <b>NR Radio Interface architecture</b> architecture - Radio Protocol Architecture, QoS has b Link Control - Medium-Access Control – Physic Protocols, Mobility. <b>vance Multiple access and MIMO techniques</b> ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI <b>NR use-cases and applications</b>	unicat andlin al Lay Cellula lar, M Vave a IMO	ion, T 8 ho g, Use ver fur 8 ho ar with assive and m Techn 4 ho	Netw urs er Planction urs n Lar e Mil mWa ique urs	ork ane ns ge VC ave s	
Massive centra slicing. Module:3 5G Overall system Protocols-Radia Control Plane F Module:4 Ad Overview of Ma scale Antenna for Evolved LTE Systems (Abov NOMA. Module:5 5G SG NR Service	Alised RAN, Cognitive Radio, Vehicular common NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS had b Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI NR use-cases and applications Classes Overview: Enhanced Mobile Broadband	unicat andlin al Lay Lar, M Vave a MO	ion, f 8 ho g, Use er fur 8 ho ar with assive and m Techn BB), f	Vetw urs er Planction urs Lar mWa ique urs Mass	ork ane ns ge MC ave s	
Massivecentraslicing.5GModule:35GOverall systemProtocols-RadioControl PlaneModule:4AdOverview of Mascale Anternafor Evolved LTESystems(Above)NOMA.Module:55GSG NR ServiceMachine-Type	<ul> <li>Alised RAN, Cognitive Radio, Vehicular communications</li> <li>NR Radio Interface architecture</li> <li>architecture - Radio Protocol Architecture, QoS has be Link Control - Medium-Access Control – Physic Protocols, Mobility.</li> <li>vance Multiple access and MIMO techniques</li> <li>ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu</li> <li>Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI</li> <li>NR use-cases and applications</li> <li>Classes Overview: Enhanced Mobile Broadbane Communications (m-MTC), Ultra Reliable</li> </ul>	unicat andlin al Lay Cellula lar, M Vave a MO d (eM e Lo	ion, 1 8 ho g, Use er fur 8 ho ar with assive and m Techn BB), 1 ow	Vetw urs er Planction urs i Lar mWa iique urs Vass Late	ork ane ns ge MC ave s	
Massive centra slicing. <b>Module:3 5G</b> Overall system Protocols-Radio Control Plane F <b>Module:4 Ad</b> Overview of Mo scale Anterna for Evolved LTE Systems (Abov NOMA. <b>Module:5 5G</b> SG NR Service Machine-Type Communication	Alised RAN, Cognitive Radio, Vehicular common NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS had b Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI NR use-cases and applications Classes Overview: Enhanced Mobile Broadband	unicat andlin al Lay Cellula lar, M Vave a MO d (eM e Lo	ion, 1 8 ho g, Use er fur 8 ho ar with assive and m Techn BB), 1 ow	Netw urs er Planction urs n Lar e Mil mWa ique urs Mass Late e.	ork ane ns ge MC ave s	
Massivecentraslicing. <b>Module:35G</b> Overall systemProtocols-RadiaProtocols-RadiaControl Plane FModule:4AdOverview of Mascale Antennafor Evolved LTESystems(Abover)NOMA.Module:55GModule:55GSGSG NR ServiceMachine-TypeCommunicationModule:6M2	Alised RAN, Cognitive Radio, Vehicular communications NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS had b Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI NR use-cases and applications Classes Overview: Enhanced Mobile Broadband Communications (m-MTC), Ultra Reliable is (URLLC), Application of NFV and SDN to 5G In M Communications	unicat andlin al Lay Lar, M Vave a MO d (eM e Lo nfrasti	ion, f 8 ho g, Use er fur 8 ho ar with assive and m Techn 4 ho BB), f Sw cuctur 8 ho	Vetw urs er Pla nction urs n Lar e Mil mWa iique urs Late e. urs	ork ane ns ge- VIC ave s ive ncy	
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Massivecentraslicing. <b>Module:35G</b> Overall systemProtocols-RadiaProtocols-RadiaControl PlaneControl Plane <b>Module:4Ad</b> Overview of Mascale Anternafor Evolved LTESystems(Above)Module:5 <b>5G</b> SG NR ServiceMachine-TypeCommunicationModule:6 <b>M2</b> LTE evolution for the spectives for the spective set of t	Alised RAN, Cognitive Radio, Vehicular communications         NR Radio Interface architecture         architecture - Radio Protocol Architecture, QoS had be Link Control - Medium-Access Control – Physic Protocols, Mobility.         vance Multiple access and MIMO techniques         ulti-Antenna Techniques in LTE, Moving to 5G C         Arrays, Antenna-array Architectures for 5G Cellu         E Systems (Below 6 GHz), Massive MIMO for cmV         ve 6 GHz), Advanced Multiple-access and MI         NR use-cases and applications         Classes Overview: Enhanced Mobile Broadband Communications (m-MTC), Ultra Reliables (URLLC), Application of NFV and SDN to 5G In M Communications         for M2M, 5G for M2M communication, Low-later or Small-cell 5G Networks - New Radio-interface	unicat andlin al Lay Lar, M Vave a IMO d (eM e Lo nfrasti	ion, f 8 ho g, Use er fur 8 ho ar with assive and m Techn Techn BB), f bw ructur 8 ho adio-ii	Vetw urs Pr Planction urs Lars MW ique urs Vass Late e. urs nterfa	ork ane ns ge MC ave sive ncy ace	
Massivecentraslicing. <b>Module:35G</b> Overall systemProtocols-RadiaProtocols-RadiaControl PlaneControl Plane <b>Module:4Ad</b> OverviewMassiveMassiveModule:4AdOverviewMassivefor Evolved LTESystemsSystems(Above)NOMA. <b>Module:55G</b> Machine-TypeCommunicationModule:6 <b>M2</b> LTEevolutionPerspectivesforlatency5GWire	Alised RAN, Cognitive Radio, Vehicular communications NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS had b Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI NR use-cases and applications Classes Overview: Enhanced Mobile Broadband Communications (m-MTC), Ultra Reliable ns (URLLC), Application of NFV and SDN to 5G In M Communications for M2M, 5G for M2M communication, Low-later or Small-cell 5G Networks - New Radio-interface eless Access, Massive Internet of Things.	unicat andlin al Lay Lar, M Vave a IMO d (eM e Lo nfrasti	ion, f 8 ho g, Use ver fur 8 ho ar with assive and m Techn 4 ho BB), f cuctur 8 ho adio-ii sign f	Netw urs Pr Planction urs n Lar Pr Mil mWV ique urs Mass Late e. urs nterfa or Lo	ork ane ns ge VIC ave s ive ncy ace	
Massivecentraslicing.Module:35GOverall systemProtocols-RadiaProtocols-RadiaControl Plane FModule:4AdOverview of Mascale AntennaAdOverview of Kascale AntennaFSystems(Abover)Systems(Abover)NOMA.SGModule:55GSG NR ServiceMachine-TypeCommunicationModule:6Module:6M2LTE evolutionPerspectives forlatency 5GWirdModule:7Fut	Alised RAN, Cognitive Radio, Vehicular communications NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS had b Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI NR use-cases and applications Classes Overview: Enhanced Mobile Broadband Communications (m-MTC), Ultra Reliable ns (URLLC), Application of NFV and SDN to 5G In M Communications for M2M, 5G for M2M communication, Low-later or Small-cell 5G Networks - New Radio-interface eless Access, Massive Internet of Things. ture Generation networks	unicat andlin al Lay Lar, M Vave a MO d (eM e Lo nfrasti L ncy Ra se Des	ion, f 8 ho g, Use er fur 8 ho ar with assive and m Techn 4 ho BB), f ow ructur 8 ho adio-in sign f 4 ho	Vetw urs Pr Planction urs urs Nass Late e. urs nterfa or Lo	rork ane ns ge VC ave s ive ncy ace	
Massive centra slicing. Module:3 5G Overall system Protocols-Radia Control Plane F Module:4 Ad Overview of Ma scale Antenna for Evolved LTE Systems (Abov NOMA. Module:5 5G SG NR Service Machine-Type Communication Module:6 M2 LTE evolution for Perspectives for latency 5G Wire Module:7 Fut	Alised RAN, Cognitive Radio, Vehicular communications NR Radio Interface architecture architecture - Radio Protocol Architecture, QoS had b Link Control - Medium-Access Control – Physic Protocols, Mobility. vance Multiple access and MIMO techniques ulti-Antenna Techniques in LTE, Moving to 5G C Arrays, Antenna-array Architectures for 5G Cellu E Systems (Below 6 GHz), Massive MIMO for cmV ve 6 GHz), Advanced Multiple-access and MI NR use-cases and applications Classes Overview: Enhanced Mobile Broadband Communications (m-MTC), Ultra Reliable ns (URLLC), Application of NFV and SDN to 5G In M Communications for M2M, 5G for M2M communication, Low-later or Small-cell 5G Networks - New Radio-interface eless Access, Massive Internet of Things. ture Generation networks .6 GHz, IAB enhancements, NR – Broadcast /	unicat andlin al Lay Lar, M Vave a MO d (eM e Lo nfrasti L ncy Ra se Des	ion, f 8 ho g, Use er fur 8 ho ar with assive and m Techn 4 ho BB), f ow ructur 8 ho adio-in sign f 4 ho	Vetw urs Pr Planction urs urs Nass Late e. urs nterfa or Lo	orl ane ns ge VIC ave sive ncy ace ow	

Mo	dule:8	Contemporary Issues				2 hours
Ind	ustry ex	pert lecture on different 5G	use cases	6		
			Total	Lecture he	ours:	45 hours
Text Book(s)						
1.		ahlman, Stefan Parkvall, ss Access Technology", Ao				
2.	R. Var	nithamby and S. Talwar, " date Technologies", John V	Towards 5	G: Applicat	ions, F	Requirements and
3.		Z. Asif, "5G Mobile Comm 1 <sup>st</sup> Edition, 2019.	unications	Concepts a	and Te	echnologies, CRC
4.		an Rodriguez, "Fundamen tion, 2015.	tals 5G Mo	bile Networ	rks", Jo	ohn Wiley & Sons,
Ref	erence	Books				
1.		t W. Heath Jr., Angel Loza ridge University Press, 1st			AIMO (	Communication",
2.						
	Mode of Evaluation: Continuous Assessment Test, Digital Assignment, Quiz and Final Assessment Test					
Rec	commer	ded by Board of Studies	07-06-20	23		
Арр	proved b	y Academic Council	No. 70	Date	24-06	5-2023

MEDS616L	Course Title	L	Т	Ρ	С	
MED3010L	Machine Leaning and Deep Learning	3	0	0	3	
Pre-requisite	NIL	Sylla	bus y		on	
			1.0			
Course Objectiv						
The course is air						
1. Understanding about the fundamentals of machine learning and neural						
networks						
	he students to acquire knowledge about pattern					
	the students to apply deep learning algorithms	TOF SC	olving	rear	me	
problems						
Course Outcom						
	course the student will be able to					
	end the categorization of machine learning algorithms algorithms and the categorization of machine learning algorithms algorithms algorithms algorithms are also also also also also also also also	rithms				
	id the types of neural network architectures, act			tions		
	with the pattern association using neural networ		Tune			
	arious terminologies related with pattern recogn					
	erent feature selection and classification technic					
	nd the architectures of convolutional neur		etworl	ks a	nd	
Compreh	end advanced neural network architectures	s suc	h as	RN	IN,	
Autoenco	ders, and GANs.					
Module:1 Lear	ning Problems and Algorithms		4 hc			
	ms of learning problems, Supervised, Ser	ni-sup	perviso	ed a	nd	
Unsupervised al						
Module:2 Neu			<u>8 hc</u>			
	reen Biological and Artificial Neural Networks - T					
	on Functions, Multi-layer neural network, Linear	Sepa	radiiit	у, не	aa	
	Adaline, Standard Back propagation					
Module:3 Neural Network – II 8 hours						
		Dolta			aro	
Training Algorith	ms for Pattern Association - Hebb rule and		rule,	Hete		
Training Algorith associative, Auto	nms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E	xampl	rule, es of	Hete Feate	ıre	
Training Algorith associative, Auto Maps, Learning	ms for Pattern Association - Hebb rule and	xampl	rule, es of	Hete Feate	ıre	
Training Algorith associative, Auto Maps, Learning Learning	nms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Bo	xampl	rule, es of ann N	Hete Featu Aach	ıre	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac	nms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be hine Learning: Terminologies	xampl oltzma	rule, es of ann M <b>7 hc</b>	Hete Featu Aach	ure ine	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam	nms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Bo	xampl oltzma , Reca	rule, es of ann M <b>7 hc</b> all, F1	Hete Featu Aach ours - Sco	ure ine re,	
Training Algorith associative, Auto Maps, Learning Learning <b>Module:4</b> Mac Classifying Sam the curse of dime	nms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be hine Learning: Terminologies ples: The confusion matrix, Accuracy, Precision	xampl oltzma , Reca lidatic	rule, es of ann M 7 hc all, F1 on, ove	Hete Featu Aach ours - Sco	ure ine re,	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam the curse of dim- under-fitting the	hms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be hine Learning: Terminologies ples: The confusion matrix, Accuracy, Precision ensionality, training, testing, validation, cross va	xampl oltzma , Reca lidatic	rule, es of ann M 7 hc all, F1 on, ove	Hete Featu Aach ours - Sco erfitti	ure ine re,	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam the curse of dimu under-fitting the Module:5 Mac Class	<ul> <li>Imms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be</li> <li>Imme Learning: Terminologies</li> <li>Iples: The confusion matrix, Accuracy, Precision</li> <li>Imme Learning, testing, validation, cross va</li> <li>Imme Learning: Feature Selection and</li> <li>Isification</li> </ul>	xampl oltzma , Reca lidatic riance	rule, es of ann M 7 hc all, F1 on, ove 7 hc	Hete Featu Aach - Sco erfitti	ine re, ng,	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam the curse of dimu under-fitting the Module:5 Mac Class Feature Selection	ms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Bo hine Learning: Terminologies ples: The confusion matrix, Accuracy, Precision ensionality, training, testing, validation, cross va data, early stopping, regularization, bias and va hine Learning: Feature Selection and sification n, normalization, dimensionality reduction, Class	xampl oltzma , Reca lidatic riance	rule, es of ann M 7 hc all, F1 on, ove 7 hc	Hete Featu Aach Jach Sco erfittin	re, ng,	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam the curse of dime under-fitting the Module:5 Mac Class Feature Selection Decision trees,	<ul> <li>Imms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be</li> <li>Imme Learning: Terminologies</li> <li>Iples: The confusion matrix, Accuracy, Precision</li> <li>Imme Learning, testing, validation, cross va</li> <li>Imme Learning: Feature Selection and</li> <li>Isification</li> </ul>	xampl oltzma , Reca lidatic riance	rule, es of ann M 7 hc all, F1 on, ove 7 hc	Hete Featu Aach Jach Sco erfittin	re, ng,	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam the curse of dime under-fitting the Module:5 Mac Class Feature Selection Decision trees, clustering.	ms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be hine Learning: Terminologies ples: The confusion matrix, Accuracy, Precision ensionality, training, testing, validation, cross va data, early stopping, regularization, bias and va hine Learning: Feature Selection and sification n, normalization, dimensionality reduction, Clas Naïve Bayes, Binary classification, multi c	xampl oltzma , Reca lidatic riance	rule, es of ann M 7 hc all, F1 on, ove 7 hc 5: KNN classi	Hete Featu Aach - Sco erfittin ours	re, ng,	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam the curse of dim- under-fitting the Module:5 Mac Class Feature Selection Decision trees, clustering. Module:6 Con	<ul> <li>Imms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be hine Learning: Terminologies</li> <li>Indext place in the confusion matrix, Accuracy, Precision ensionality, training, testing, validation, cross vadata, early stopping, regularization, bias and va hine Learning: Feature Selection and sification</li> <li>Indext place in the confusion, dimensionality reduction, Class Naïve Bayes, Binary classification, multi context place in the confusion of the classification</li> </ul>	xampl oltzma , Reca lidatic riance sifiers lass	rule, es of ann M 7 hc all, F1 on, ove 7 hc 3: KNN classi 5 hc	Hete Featu Aach Jurs - Sco erfitti Jurs J, SV ficatio	re, ng, M, on,	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam the curse of dime under-fitting the Module:5 Mac Class Feature Selection Decision trees, clustering. Module:6 Con	Imms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be hine Learning: Terminologies ples: The confusion matrix, Accuracy, Precision ensionality, training, testing, validation, cross vadata, early stopping, regularization, bias and va hine Learning: Feature Selection and sification n, normalization, dimensionality reduction, Class Naïve Bayes, Binary classification, multi c volutional Neural Networks backpropagation i	xampl oltzma , Reca lidatic riance sifiers lass n CNI	rule, es of ann M 7 hc all, F1 on, ove 7 hc 3 hc 5 hc N, opt	Hete Featu Aach Ours - Sco erfitti Ours I, SV fication fication fication	re, ng, M, on, rs,	
Training Algorith associative, Auto Maps, Learning Learning Module:4 Mac Classifying Sam the curse of dime under-fitting the Module:5 Mac Class Feature Selection Decision trees, clustering. Module:6 Con	Imms for Pattern Association - Hebb rule and associative, Kohonen Self Organising Maps, E Vector Quantization, Gradient descent, Be hine Learning: Terminologies ples: The confusion matrix, Accuracy, Precision ensionality, training, testing, validation, cross vadata, early stopping, regularization, bias and va hine Learning: Feature Selection and sification n, normalization, dimensionality reduction, Class Naïve Bayes, Binary classification, multi c volutional Neural Networks backpropagation i tion, convolution layers, pooling layers, fully	xampl oltzma , Reca lidatic riance sifiers lass n CNI	rule, es of ann M 7 hc all, F1 on, ove 7 hc 3 hc 5 hc N, opt	Hete Featu Aach Ours - Sco erfitti Ours I, SV fication fication fication	re, ng, M, on, rs,	

Мо	dule:7	RNNs, Auto encoders an	d GANs			4 hours	
Sta	ate, Stru	cture of RNN Cell, LSTM ar	nd GRU, 1	Fime dist	ributed la	yers, Generating	
	Text, Auto encoders: Convolutional Auto encoders, De-noising auto encoders,						
		auto encoders, GANs: The	discrimina	ator, gen	erator, DC	CGANs	
Мо	dule:8	Contemporary Issues				2 hours	
Gu	est Lect	ures from Industry and, Res	earch and	d Develo	pment Or	ganizations	
			Tota	I Lecture	e hours:	45 hours	
Tex	kt Book	(s)					
1.	J. S. R	. Jang, C. T. Sun, E. Mizu	tani, Neu	ro Fuzz	y and Sc	oft Computing -	
	A Com	putational Approach to L	earning a	and Mac	chine Inte	elligence, 2012,	
	PHI le	arning	_			_	
2.	Deep	Learning, Ian Good fellow,	Yoshua	Bengio a	and Aaror	n Courville, MIT	
	Press,	ISBN: 9780262035613, 20 <sup>-</sup>	16.				
Ref	ference	Books					
1.	The E	lements of Statistical Lear	ning. Trev	vor Hast	ie, Rober	t Tibshirani and	
	Jerom	e Friedman. Second Edition	. 2009.				
2.	Unders	standing Machine Learning	. ShaiSha	lev-Shw	artz and	Shai Ben-David.	
	Cambr	idge University Press. 2017					
Mo	de of E\	aluation: Continuous Asses	sment, Di	gital Ass	signment,	Quiz and Final	
Ass	Assessment Test						
Ree	commer	ided by Board of Studies	07-06-20	)23			
Ар	proved b	y Academic Council	No. 70	Date	24-06-20	)23	

Course Code	Course Title	L	Т	Р	С	
MVLD611L						
Pre-requisite	NIL	Sylla	bus \	Jersi	 0n	
		Jyna	1.0			
Course Objectiv	/es		1.0			
The course is air						
1. Introduce advanced concepts of computer architecture.						
2. Acquire knowledge on various interconnect topology for multiprocessor						
	nd Different pipelining techniques.					
	nding different memory hierarchy for r	nultipro	cess	or a	and	
multicomp	outer systems.					
Course Outcom						
Course Outcom	course the student will be able to:					
		ultiproc	0220	rs a	and	
multicomp		unpioc	,03301	13 0	inu	
	e the required static or dynamic interconr	nect ne	etworl	k for	r a	
	essor system.					
3. Understar	nd the Data level parallelism in Vector architect	ture, SI	MD, (	GPU		
	erent pipelining techniques to reduce computat					
	ne various memory design for multiprocessor a			pute	r.	
6. Design sc	alable parallel architecture for multiprocessor	system				
Modulo 1 Doro	llal computer models			5 hoi		
The state of c	Ilel computer models computing - Conditions of parallelism - [	)ata a				
	Hardware and software parallelism - Progra					
	rain Size and latency Classification of particular					
	and Multicomputer					
	em Interconnect Architectures			7 hoi		
	ies and routing - Static interconnection N					
	Networks - Multiprocessor system Interconnec					
	sbar switch and multiport memory - Multist	age ar	nd co	mbin	ing	
network.	level Parallelism in Vector and GPU Archit	octuro	<u> </u>	7 hoi	urc	
	ure- RISC-V Vector extension- Vector comp					
	namic typing, loads and store, parallelism duri					
	extension for multimedia-Graphics Processi					
	oop-level parallelism	5			5	
Module:4 Pipe	lining			7 hoi	urs	
	rocessor - nonlinear pipeline processor - Instruc					
	r instruction pipelining - Dynamic instruction		ling -	Brar	nch	
Handling techniques - branch prediction - Arithmetic Pipeline Design.						
Module:5         Memory Hierarchy Design         6 hours						
	a cache performance - reducing miss rate					
hierarchies.	hierarchies - main memory organizations -	uesiyi		mem	υy	
	ed Memory Architectures			6 hoi	urs	
Jilai			'		ui 3	

Symmetric shared memory architectures – distributed shared memory architectures – cache coherence protocols – scalable cache coherence – directory protocols – memory-based directory protocols – cache-based directory protocols.

Module:7 Multiprocessor Architectures 5 hours

Computational models – An Argument for parallel Architectures – Scalability of Parallel Architectures – Benchmark Performances.

## Module:8 Contemporary Issues

2 hours

Guest lectures from Industries and R & D Organizations

				Total L	ecture hours:	45 hours	
Тех	kt Book	(s)					
1.	Kai Hwang, NareshJotwani, Advanced Computer Architecture: Parallelism,						
	Scalab	ility, Programmability, 2017,	Third ed	lition, Ta	ta McGraw Hill	Education,	
	India.						
2.		Patterson, Andrew Wate				An Open	
	Archite	ecture Atlas, 2017, First edition	on, Straw	berry Ca	inyon, USA.		
Ref	ference	Books					
1.	John L	Hennessy, David A. Patter	rson, Cor	nputer A	rchitecture: A C	antitative	
	Approa	ach, 2011, Fifth edition, Morg	jan Kaufr	nann.			
2.		Sima, Terence Fountain, Pet					
	Archite	ectures – A Design Space Ap	proach, 2	2014, Pe	arson Education	n, India.	
3.		n Grama, Anshul Gupta, Geo					
		duction to Parallel Computin	ıg, 2009,	Second	edition, Pearsor	ר	
	Educa	tion, India.					
Мо	de of E	valuation: Continuous Asses	ssment T	est, Dig	ital Assignment	, Quiz and	
Fin	al Asse	ssment Test.					
Re	commer	nded by Board of Studies	07-06-20	023			
Ар	proved b	by Academic Council	No. 70	Date	24-06-2023		

Course Code	Course Title		т	Ρ	С
MVLD613L	System Design with FPGA	3	0	0	3
	NIL		labus	-	L -
		<u>J</u>	1.0		
Course Objecti	ves :				
This course is a					
1. Provide a	in overview of FPGA architectures and expound	d on t	he soft	core	and
	e processors in association with hardware and s				
2. Understa	nd the specification and operation of Program	nming	, for p	eriph	eral
Interfaces and Interconnect Fabrics.					
3. Implemer	nt digital system and IP blocks for various DSP a	lgorith	ims.		
Course Outcon					
	of the course the student will be able to:				
	nd and get an idea about SoC and FPGA archite	ectures	5.		
	nd the NIOS II soft core processor architecture.	a			
	he working of hardware and software co-design				
	the usage of various peripheral interfaces for sys		iesign.		
	a system by choosing suitable interconnect fabric ne system using NIOS II soft core processor, r		the e	uctor	a hu
	block and design and develop embedded synthe				гру
using n i	sock and design and develop embedded synthe	515 US	nig i i	UA.	
Module:1 SoC	Architecture		F	6 hou	rs
	System on Design – FPGA SoC Architecture –	Case			
/ Intel FPGA		0400	etaaj	, , , , , , , , , , , , , , , , , , , ,	
	Core and Hard Core Processor		10	) hou	rs
	tecture and Configurability Features: Nios II Pro	cesso	r – Nio	S	
	ARM cortex A9 architecture				
	dware – Software Co-design Flow			2 hou	rs
	n Flow – Software Design Flow - EDA Tool Hard	dware	and		
Software design					
	ramming for peripheral Interfaces			5 hou	rs
	32, SDRAM, SRAM Controller, VGA, Audio and	Video	, PIO,		
External Bus br					
	rconnect Fabrics			<u>l hou</u>	
	Fabric Interconnect - Implementation and	Funct	ions-In	tegra	ted
Design Environr				)	
Module:6 Syste				<u>B hou</u>	
	roller, Real Time Clock - Interfacing using FPGA	: VGF		, Carr 3 hou	
	res based SoC design	SUD			IS.
	algorithm- Image edge detection in FPGA using ny Edge Detection Algorithm, Colour and Brightr				nt
	rast enhancement using RGB to HSV algorithm				
0	ition using Controllers	มนวัตนี		<u> </u>	
Y	emporary Issues		2	2 hou	rs
	om Industry and R & D Organizations				
	Total Lecture	hour	s: 1	5 hou	irs
Text Book(s)				5 1101	J J

1.	ZainalabedinNavabi, "Embedded Core Design with FPGAs", 2011, Tata McGraw Hill Ltd, India.					
2.	Pong P. Chu, Embedded SoPC Design with NIOS II Processor and VERILOG examples", 2012, Wiley, USA.					
	erence Books					
1	Donald G. Bailey," Design for Embedded Image Processing on FPGAs", 2012, Wiley, USA.					
2	Jivan S. Parab, Rajendra S Gad, G.M. Naik, "Hands-on Experience with Altera FPGA Development Boards", 2018, Springer, USA.					
3	Joseph Yu, System-on-Chip Design with Arm Cortex-M Processors, 2019, ARM Education Media					
Mode of Evaluation: Continuous Assessment Test, Digital Assignment, Quiz and Final Assessment Test.						
Red	commended by Board of Studies 07-06-2023					
App	Approved by Academic Council No. 70 Date 24-06-2023					

Course Code	Course Title	L	Τ	Ρ	С		
MVLD616L	Scripting Languages For Electronic Design Automation						
Pre-requisite	NIL	Svi	ahue	versi	on		
Fie-iequisite		J	<u>abus</u> 1.				
Course Objectiv	<i>1</i> 05'			U			
The course is air							
1. To write scripts in the LINUX environment.							
2. To study the principles of Scripting Languages like Perl, TCL and Python.							
	te the scripts for automation using the language						
Pythor		55 1110	, 1 011,	1020	and		
Course Outcom	165:						
	course the student will be able to						
	n and apply commands in LINUX environment						
	op and execute the Perl scripts.						
	e and Handle files, directories and manage p	roces	ses u	ısing F	Perl		
scripts	0 1			0			
4. Use T	CL scripts for automation.						
5. Build 7	CL scripts to Handle files, directories and mar	nage	oroce	SS.			
6. Develo	pp Python scripts to interpret files and directori	es.					
Module:1 LINU				5 ho			
	inux, File System of Linux, General usage of Lir						
	ux users and group, Permissions for file, c		ory ar	nd use	ers,		
	and directory, zipping and unzipping concepts.						
Module:2 PER				7 ho			
	ncepts of PERL - Scalar Data - Arrays and						
	hes - Basics I/O - Regular Expressions – Funct	ions -	Misce	ellane	ous		
control structures							
	anced Topics in PERL			6 ho			
Directory acces	s - File and Directory manipulation - Proc	ess I	Mana	gemer	nt -		
	Modules -Applications of PERL scripts to	Eleo	ctronic	: Des	sign		
Automation.							
Module:4 TCL				7 ho			
	CL and Tk -Tcl Language syntax – Variables -				ists		
	procedures - Errors and exceptions - String ma	nipuia	ations				
	anced Topics in TCL			<u>6 ho</u>	urs		
	Processes. Applications - Controlling Tools - E	sasics					
Module:6 Pyth		<b>t</b> .		6 ho			
	ython – Using Python interpreter – Brief tour	on sta	andaro	a iidra	ry -		
	ls – Data structures – Regular Expressions.			6 hc			
	anced Topics in Python	ulaa	 	6 ho			
	It – Errors and Exceptions – Classes – Modu	lies-	чрыс	auons	S UI		
	Electronic Design Automation.			2 60			
	temporary Issues:			2 ho	ui S		
Guest lectures fr	om Industry and R&D Organizations						
I	Tabel I a strong	harm	o. 4	5 karr			
	Total Lecture	nour	5: 4;	5 hou	15		

Text Book(s)						
1.	Larry Wall, Tom Christiansen, Jo	hn Orwa	ant, Prog	gramming PERL, 2012,		
	Fourth Edition, Oreilly Publications.					
2.	John K. Ousterhout, Ken Jones, Tc	l and the	Tk Toolk	it, 2010, Second Edition,		
	Pearson Education, India					
Ref	ference Books					
1.	Guido van Rossum Fred L. Drake	e, Jr., edit	tor, Pyth	on Tutorial Release 3.2.3,		
	2012, Python Software Foundation					
2.	Randal L. Schwartz, Brian D Fog	y, Tom F	Phoenix,	Learning Perl, 2021, 8th		
	Edition, O'Reilly Media, Inc.	-		-		
3.	Mark Lutz, Learning Python, 2013,	5th Editi	on, O'Re	illy Media, Inc.		
Mo	de of Evaluation: Continuous Asse	ssment T	est, Dig	ital Assignment, Quiz and		
Fin	al Assessment Test		-	-		
Red	commended by Board of Studies	07-06-2	023			
Арр	proved by Academic Council	No. 70	Date	24-06-2023		