

SCHOOL OF ELECTRONICS ENGINEERING

M. Tech Internet of Things & Sensor Systems

(M.Tech MTS)

Curriculum

(2020-2021 admitted students)

VISION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

Transforming life through excellence in education and research.

MISSION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

World class Education: Excellence in education, grounded in ethics and critical thinking, for improvement of life.

Cutting edge Research: An innovation ecosystem to extend knowledge and solve critical problems.

Impactful People: Happy, accountable, caring and effective workforce and students.

Rewarding Co-creations: Active collaboration with national & international, industries & universities for productivity and economic development.

Service to Society: Service to the region and world through knowledge and compassion.

VISION STATEMENT OF THE SCHOOL OF ELECTRONICS ENGINEERING

To be a leader by imparting in-depth knowledge in Electronics Engineering, nurturing engineers, technologists and researchers of highest competence, who would engage in sustainable development to cater the global needs of industry and society.

MISSION STATEMENT OF THE SCHOOL OF ELECTRONICS ENGINEERING

- Create and maintain an environment to excel in teaching, learning and applied research in the fields of electronics, communication engineering and allied disciplines which pioneer for sustainable growth.
- Equip our students with necessary knowledge and skills which enable them to be lifelong learners to solve practical problems and to improve the quality of human life.

PROGRAMME EDUCATIONAL OBJECTIVES (PEOs)

- 1. Graduates will be engineering practitioners and leaders, who would help solve industry's technological problems
- 2. Graduates will be engineering professionals, innovators or entrepreneurs engaged in technology development, technology deployment, or engineering system implementation in industry
- 3. Graduates will function in their profession with social awareness and responsibility
- 4. Graduates will interact with their peers in other disciplines in industry and society and contribute to the economic growth of the country
- 5. Graduates will be successful in pursuing higher studies in engineering or management
- 6. Graduates will pursue career paths in teaching or research

PROGRAMME OUTCOMES (POs)

- PO_01: Having an ability to apply mathematics and science in engineering applications.
- PO_02: Having an ability to design a component or a product applying all the relevant standards and with realistic constraints, including public health, safety, culture, society and environment
- PO_03: Having an ability to design and conduct experiments, as well as to analyse and interpret data, and synthesis of information
- PO_04: Having an ability to use techniques, skills, resources and modern engineering and IT tools necessary for engineering practice
- PO_05: Having problem solving ability- to assess social issues (societal, health, safety, legal and cultural) and engineering problems
- PO_06: Having adaptive thinking and adaptability in relation to environmental context and sustainable development
- PO_07: Having a clear understanding of professional and ethical responsibility
- PO_08: Having a good cognitive load management skills related to project management and finance

PROGRAMME SPECIFIC OUTCOMES (PSOs)

On completion of M. Tech. (Internet of Things & Sensor Systems) programme, graduates will be able to

- PSO1: Competent, and innovative with a strong cognizance in the area of sensors, IoT, data science, controllers and signal processing through the application of acquired knowledge and skills
- PSO2: Apply advanced techniques and tools of sensing and computation to solve multi-disciplinary challenges in industry and society.
- PSO3: To exhibit independent and collaborative research with strategic planning, while demonstrating the professional and ethical responsibilities of the engineering profession.

CREDIT STRUCTURE

Category-wise Credit distribution

| Category | Credits |
|--------------------------|---------|
| University core (UC) | 27 |
| Programme core (PC) | 21 |
| Programme elective (PE) | 16 |
| University elective (UE) | 06 |
| Total credits | 70 |

DETAILED CURRICULUM

University Core - 27

| S. No | Course Code | Course Title | L | T | P | J | C |
|-------|-------------|--------------------------------------|----|---|---|----|----|
| 1 | MAT6001 | Advanced Statistical Methods | 2 | 0 | 2 | 0 | 3 |
| 2 | ENG5001 | Fundamentals of Communication Skills | 0 | 0 | 2 | 0 | 2 |
| | ENG5001 and | Technical English I and | {0 | 0 | 2 | 0 | |
| 3 | ENG5002 or | Technical English II (or) | 0 | 0 | 2 | 0} | 2 |
| | GER5001 | Deutsch fuer Anfaeger | 2 | 0 | 0 | 0 | |
| 4 | STS5001 & | Soft Skills | 0 | 0 | 0 | 0 | 2 |
| 4 | STS5002 | | | | | | |
| 5 | SET5001 | SET Project-I | 0 | 0 | 0 | 0 | 2 |
| 6 | SET5002 | SET Project-II | 0 | 0 | 0 | 0 | 2 |
| 7 | ECE6099 | Master's Thesis | 0 | 0 | 0 | 0 | 16 |

Programme Core - 21

| S. No | Course Code | Course Title | L | T | P | J | C |
|-------|----------------|---|---|---|---|---|---|
| 1 | ECE5060 | Principles of Sensors and Signal Conditioning | 2 | 0 | 2 | 0 | 3 |
| 2 | ECE5061 | IoT Fundamentals and Architecture | 3 | 0 | 0 | 0 | 3 |
| 3 | ECE5062 | Data Acquisition | 0 | 0 | 4 | 0 | 2 |
| 4 | ECE5063 | Control Systems | 0 | 0 | 4 | 0 | 2 |
| 5 | ECE5064 | Programming and scripting languages | 0 | 0 | 4 | 0 | 2 |
| 6 | ECE5065 | Microcontrollers for IoT Prototyping | 2 | 0 | 2 | 0 | 3 |
| 7 | ECE6001 | Wireless Sensor Networks and IoT | 2 | 0 | 0 | 4 | 3 |
| 8 | ECE6030 | Signal Processing and Data Analytics | 2 | 0 | 2 | 0 | 3 |

Programme Electives - 16

| S.No | Course Code | Course Title | L | T | P | J | C |
|------|----------------|--|---|---|---|---|---|
| 1 | ECE5006 | Flexible and Wearable Sensors | 3 | 0 | 0 | 0 | 3 |
| 2 | ECE5008 | Micro and Nano Fluidics | 2 | 0 | 0 | 4 | 3 |
| 3 | ECE5066 | Chemical and Environmental Sensor | 2 | 0 | 2 | 0 | 3 |
| 4 | ECE5067 | Cloud and Fog Computing | 2 | 0 | 2 | 0 | 3 |
| 5 | ECE5068 | IoT Security and Trust | 2 | 0 | 0 | 4 | 3 |
| 6 | ECE5069 | IoT Applications and Web development | 2 | 0 | 0 | 4 | 3 |
| 7 | ECE6003 | Micro Systems & Hybrid Technology | 2 | 0 | 2 | 0 | 3 |
| 8 | ECE6004 | RF and Microwave Sensors | 3 | 0 | 0 | 0 | 3 |
| 9 | ECE6007 | Biomedical sensors | 2 | 0 | 2 | 0 | 3 |
| 10 | ECE6087 | Multi-disciplinary Product Development | 3 | 0 | 0 | 4 | 4 |
| 11 | ECE6088 | Deep Learning — An Approach to Artificial Intelligence | 3 | 0 | 0 | 0 | 3 |
| 12 | ECE6089 | Automotive Sensors & in-Vehicle Networking | 2 | 0 | 2 | 0 | 3 |
| 13 | ECE6090 | Fibre optic Sensors and Photonics | 3 | 0 | 0 | 0 | 3 |

| Course Code | Course Title | L | T | P | J | C |
|---------------|----------------------------------|------------------|---|-----|-----|---|
| ECE5060 | PRINCIPLES OF SENSORS AND SIGNAL | | 0 | 2 | 0 | 3 |
| | CONDITIONING | | | | | |
| Pre-requisite | Nil | Syllabus version | | | ion | |
| | | | | 1.0 | | |

- 1. To provide in depth knowledge in physical principles applied in sensing, measurement and a comprehensive understanding on how measurement systems are designed, calibrated, characterised, and analysed.
- 2. To introduce the students to sources and detectors of various Optical sensing mechanisms and provide in-depth understanding of the principle of measurement, and theory of instruments and sensors for measuring velocity and acceleration
- 3. To give a fundamental knowledge on the basic laws and phenomena on which operation of sensor transformation of energy is based.
- 4. To impart a reasonable level of competence in the design, construction, and execution of mechanical measurements strain, force, torque and pressure

Expected Outcomes:

- 1. Use concepts in common methods for converting a physical parameter into an electrical quantity
- 2. Choose an appropriate sensor comparing different standards and guidelines to make sensitive measurements of physical parameters like pressure, flow, acceleration, etc.
- 3. Design and develop sensors using optical methods with desired properties
- 4. Evaluate performance characteristics of different types of sensors
- 5. Locate different types of sensors used in real life applications and paraphrase their importance
- 6. Create analytical design and development solutions for sensors.
- 7. Compete in the design, construction, and execution of systems for measuring physical quantities

| | I | | | | | | |
|--------------|--|-----------------|----------------------|--|--|--|--|
| Module:1 | Sensor fundamentals and characteristics | 2 hours | | | | | |
| Sensor Clas | sification, Performance and Types, Error Analysis | characteristics | | | | | |
| Module:2 | Optical Sources and Detectors | 4 hours | | | | | |
| Electronic | and Optical properties of semiconductor as sens | sors, LED, Se | miconductor lasers, | | | | |
| Fiber option | e sensors, Thermal detectors, Photo multipliers, | photoconductiv | ve detectors. Photo | | | | |
| _ | alanche photodiodes, CCDs. | 1 | , | | | | |
| Module:3 | Intensity Polarization and Interferometric | 4 hours | | | | | |
| | Sensors | | | | | | |
| Intensity s | ensor, Microbending concept, Interferometers, M | Iach Zehnder, | Michelson, Fabry- | | | | |
| Perot and S | Sagnac, Phase sensor: Phase detection, Polarization | maintaining fib | pers. | | | | |
| Module:4 | Strain, Force, Torque and Pressure sensors | 5 hours | | | | | |
| Strain gage | es, strain gage beam force sensor, piezoelectric for | ce sensor, load | cell, torque sensor, | | | | |
| Piezo-resis | tive and capacitive pressure sensor, optoelectronic | pressure senso | rs, vacuum sensors. | | | | |
| Design of | signal conditioning circuits for strain gauges, piez | o, capacitance | and optoelectronics | | | | |
| sensors | | | | | | | |
| Module:5 | Position, Direction, Displacement and Level | 4 hours | | | | | |
| | sensors | | | | | | |
| Potentiomet | ric and capacitive sensors, Inductive and magn | etic sensor, L | VDT, RVDT, eddv | | | | |

current, transverse inductive, Hall effect, magneto resistive, magnetostrictive sensors. Fiber optic liquid level sensing, Fabry Perot sensor, ultrasonic sensor, capacitive liquid level sensor. Signal condition circuits for reactive and self generating sensors.

Module:6 Velocity and Acceleration sensors

3 hours

Electromagnetic velocity sensor, Doppler with sound, light, Accelerometer characteristics, capacitive, piezo-resistive, piezoelectric accelerometer, thermal accelerometer, rotor, monolithic and optical gyroscopes.

Module:7 Flow, Temperature and Acoustic sensors 6 hours

Flow sensors: pressure gradient technique, thermal transport, ultrasonic, electromagnetic and Laser anemometer. microflow sensor, coriolis mass flow and drag flow sensor. Temperature sensors- thermoresistive, thermoelectric, semiconductor and optical. Piezoelectric temperature sensor. Acoustic sensors- microphones-resistive, capacitive, piezoelectric, fiber optic, solid state electrect microphone.

| Module:8 | Contemporary Issues | 2 hours | |
|----------|---------------------|----------|--|
| | Total Lecture: | 30 hours | |

Text Book(s)

- Jacob Fraden, "Hand Book of Modern Sensors: physics, Designs and Applications", 2015, 3rd edition, Springer, New York.
- Jon. S. Wilson, "Sensor Technology Hand Book", 2011, 1st edition, Elsevier, Netherland.

Reference Books

- GerdKeiser,"Optical Fiber Communications", 2017, 5th edition, McGraw-Hill Science, Delhi.
- John G Webster, "Measurement, Instrumentation and sensor Handbook", 2017, 2nd edition, 2. CRC Press, Florida.
- Eric Udd and W.B. Spillman, "Fiber optic sensors: An introduction for engineers and scientists", 2013, 2nd edition, Wiley, New Jersey.
- Bahaa E. A. Saleh and Malvin Carl Teich, "Fundamentals of photonics", 2012, 1st edition, John Wiley, New York.

Mode of Evaluation: CAT, Digital Assignments, Quiz, Online course, Paper publication, Projects, Hackathon/Makeathon and FAT.

List of Experiments: (Indicative)

1. Design of signal conditioning circuits for strain gauges- Strain, Force, pressure, and torque measurement

8 hours

- Strain measurement with Bridge Circuit i.
- Beam force sensor using Strain Gauge Bridge ii.
- Beam deflection sensing with Strain Gauge Bridge iii.
- Diaphragm pressure sensor using Strain Gauge Bridge iv.
- Shear strain and angle of shift measurement of hollow shaft

After completing the 1st set of characteristics. Design a weighing machine having a range of 0-5 Kg with a sensitivity of 5 mg. What modification he/she has to do to change the upper range to 100 Kg with a sensitivity of 100 mg.

2. Develop a displacement measurement system with the following sensors: Inductive transducer (LVDT) i.

4hours

- ii. Hall effect sensor
- 3. After studying the characteristics of temperature sensors listed below, develop a temperature measurement system for a particular application using the suitable sensor.

6hours

- i. Thermocouple principles
- Thermistor and linearization of NTC Thermistor

| iii. Resistance Temperature Detector | | | | | | |
|--|------------------------|--------------------|------------|---------|--|--|
| iv. Semiconductor Te | mperature sensor | OA79 | | | | |
| v. Current output abs | solute temperature | sensor | | | | |
| 4. Develop a sensor system for force mea | asurement using p | iezoelectric trans | sducer | 4hours | | |
| 5. Measurement of shear strain and angle twist using strain gauge is not suitable for 8hor | | | | | | |
| many applications. Based on other sens | ing experiments c | arried out sugge | est a non- | | | |
| contact method and try to complete its pr | oof of concept. | | | | | |
| | | Total Laborat | ory hours | 30hours | | |
| Mode of Evaluation:Continuous Assessment and FAT | | | | | | |
| Recommended by Board of Studies 26-06-2019 | | | | | | |
| Approved by Academic Council | No. 55 Date 13-06-2019 | | | | | |

| Course code | Course title | L | T | P | J | C |
|---------------|---|----|------------------|---|-----|---|
| ECE5061 | ECE5061 IoT Fundamentals and Architecture | | 0 | 0 | 0 | 3 |
| Pre-requisite | Nil | Sy | Syllabus version | | ion | |
| _ | | | v. 1.00 | | | |

- 1. Introduce evolution of internet technology and need for IoT.
- 2. Discuss on IoT reference layer and various protocols and software.
- 3. Train the students to build IoT systems using sensors, single board computers and open source IoT platforms.
- 4. Make the students to apply IoT data for business solution in various domain in secured manner.

Expected Course Outcome:

- 1. Identify the IoT networking components with respect to OSI layer.
- 2. Build schematic for IoT solutions.
- 3. Design and develop IoT based sensor systems.
- 4. Select IoT protocols and software.
- 5. Evaluate the wireless technologies for IoT.
- 6. Appreciate the need for IoT Trust and variants of IoT.

Module:1 | Evolution of IoT

7 hours

Review of computer communication concepts (OSI layers, components, packet communication, Networks, TCP-IP, subnetting, IPV4 addressing and challenges). IPV6 addressing. IoT architecture reference layer.

Module:2 | **Introduction to IoT components**

6 hours

Characteristics IoT sensor nodes, Edge computer, cloud and peripheral cloud, single board computers, open source hardwares, Examples of IoT infrastructure

Module:3 IoT protocols and softwares

6 hours

MQTT, UDP, MQTT brokers, publish subscribe modes, HTTP, COAP,XMPP and gateway protocols,

Module:4 IoT point to point communication technologies

6 hours

IoTCommunicationPattern,IoTprotocolArchitecture, Selection of Wireless technologies (6LoWPAN, Zigbee, WIFI, BT, BLE,SIG,NFC, LORA,Lifi,Widi)

Module:5 Introduction to Cloud computation and Big data analytics

6hours

Evolution of Cloud Computation, Commercial clouds and their features, open source IoT platforms, cloud dashboards, Introduction to big data analytics and Hadoop.

Module:6 | **IoT security**

6hours

Need for encryption, standard encryption protocol, light weight cryptography, Quadruple Trust Model for IoT-A – Threat Analysis and model for IoT-A, Cloud security

Module:7 | IoT application and its Variants.

6 hours

Case studies: IoT for smart cities, health care, agriculture, smart meters.M2M, Web of things,

| Cel | lular IoT | , Industrial IoT, Industry 4. | 0,IoT standards. | | | | |
|-----|-------------------|---|---------------------|---------|---------------|------------|--|
| Mo | dule:8 | Contemporary issues: | | | | 2hours | |
| | | | Total Lecture ho | urs: | 45hours | | |
| | | | | | | | |
| Tex | kt Book(| s) | | | | | |
| 1. | Sebasti | ndro Bassi, Martin Bauer, an Lange, Stefan Meissner Architecture Reference Mo | , "Enabling things | to ta | lk – Designin | | |
| 2. | Jan Ho David l | oller, Vlasios Tsiatsis, Cat Boyle, "From Machine to M | therine Mulligan, | Stama | itis Karnousk | | |
| | ference l | | | | | | |
| 1. | | Yan Zhang, Laurence T. Y Next-Generation Pervasive 1 | | | | | |
| 2. | | Madisetti , Arshdeep Bahga, et of Things A Hands-on-A | | ` | , · | • | |
| 3. | Asoke 2010. | K Talukder and Roopa R Y | avagal, "Mobile Co | omput | ing," Tata Mc | Graw Hill, | |
| 4 | Barrie S | Sosinsky, "Cloud Computir | ng Bible", Wiley-In | dia, 2 | 010 | | |
| 5 | | | | | | | |
| Mo | | aluation: CAT / Assignmen | | oject / | Seminar | | |
| Rec | commend | led by Board of Studies | 26-04-2019 | | | | |
| App | proved b | y Academic Council | No. 55 | Date | 13-06-20 | 119 | |

| Course Code | Course Title | L | T | P | J | C |
|---------------|------------------|----|------------------|-----|-----|---|
| ECE5062 | DATA ACQUISITION | 0 | 0 | 4 | 0 | 2 |
| Pre-requisite | NIL | Sy | Syllabus Version | | ion | |
| | | | | 1.0 | | |
| 0 01: 4: | | | | | | |

- 1. To explore the fundamentals of data acquisition using sensors, NI data acquisition hardware, and LabVIEW.
- 2. To teach the basics of hardware selection, including resolution and sample rate, and the foundation of sensor connectivity, including grounding and wiring configurations.
- 3. To provide knowledge on using the NI-DAQmx driver to measure, generate, and synchronize data acquisition tasks and analyze the data in MATLAB/ LabVIEW
- 4. To impart adequate knowledge on programming finite and continuous acquisitions, as well as best practices in hardware/software timing, triggering, and logging.
- 5. To give hands-on experience configuring and programming NI data acquisition hardware using NI-DAQmx and LabVIEW.

Course Outcomes:

- 1. Develop PC-based data acquisition and signal conditioning.
- 2. Understand how to control the analog input, analog output, counter/timer, and digital I/O subsystems of a DAQ device.
- 3. Perform different types of data acquisition and identify the correct sensor for their measurements. Develop integrated, high-performance data acquisition systems that produce accurate measurements
- 4. Acquire data from sensors, such as thermocouples and strain gages, using NI DAQ hardware and analyse the results in LabVIEW and MATLAB
- 5. Apply advanced understanding of LabVIEW and the NI-DAQmx API to create applications

| Task 1 | | 8 hours | |
|--------------|---|--------------------------------------|-------------|
| LabVIEW | Graphical Programming, NI DAQmx, D | ata acquisition Toolbox to read data | into MATLAB |
| and Simuli | nk and write data into DAQ device. | _ | |
| | | | |
| Task 2 | | 6 hours | |
| Acquire an | d generate analog signals. | • | |
| | | | |
| Task 3 | | 6 hours | |
| Acquire an | d generate non-clocked digital data. | | |
| | | | |
| Task 4 | | 6 hours | |
| Measure from | equency, pulse width and count pulses u | sing NI devices | |
| | | | |
| Task 5 | | 6 hours | |
| Generate P | ulse Width Modulated signal | | |
| | | | |
| Task 6 | | 4 hours | |
| Acquire an | d generate audio signals | | |
| | | | |
| Task 7 | | 6 hours | |

| Simultane | ous and synchronized data acquisitio | n | | |
|------------|---|-----------------|-------------------------------|------------|
| Task 8 | | | 4 hours | |
| Simulink o | data acquisition | | | |
| Task 9 | | | 6 hours | |
| | ased multi-channel data acquisition | | V HOUIS | |
| Tituullo 0 | asea matti enaimei data aequisition | | | |
| Task 10 | | | 8 hours | |
| Remote da | nta acquisition with NI WSN Gatewa | y and nodes, C | C3200 (WiFi) | |
| | • | | | |
| | | Total Pract | ical Hours 60 hours | |
| Text Bool | | | | |
| 1. | BehzadAhzani "Data Acquisition | using LabVIEV | W" Packt Publishing, 2017 | |
| 2. | Data Acquisition Toolbox – User' | s Guide, Math | Works, 2016 | |
| Reference | e Book(s) | | | |
| 1. | Lab VIEW: A Developer's Guide Anne Brumfield, 2011, CRC Press | | Integration edited by Ian Fai | r weather, |
| 2. | DSP for Matlab and LabVIEW: and Claypool Publishers, 2009 | Fundamentals | of discrete signal processing | g, Morgan |
| 3. | Maurizio Di Paolo Emilio, "Da Design", Springer, 2013. | ta Acquisition | Systems- Fundamentals to | Applied |
| 4. | "Data Acquisition Handbook", M | leasurement and | d computing corporation, 20 | 12 |
| Mode of E | Evaluation:Continuous Assessment an | nd FAT | - | |
| Recomme | nded by Board of Studies | 26/04/2019 | | |
| | by Academic Council | 55 | Date: 13/06/2019 | |

| ECE5063 SYSTEM DYNAMICS AND CONTROL 0 0 4 0 2 Prerequisite: Nil | Course Code | Course Title | L T P J C |
|--|--------------------|-----------------------------|-----------|
| Prerequisite: Nil | ECE5063 | SYSTEM DYNAMICS AND CONTROL | 0 0 4 0 2 |
| | Prerequisite: | Nil | |
| | | | |

- To impart knowledge on performance specification, limitations and structure of controllers
- To impart knowledge on design of controllers using root-locus and frequency domain techniques

Course Outcome

7

- 1. Realize the need of control system and its recent developments. Able to model the system and simulate the model.
- 2. Analyze the behavior of the first and second order systems in time domain and frequency domain.
- 3. Analyze the system stability based on time domain, frequency domain and root locus techniques.
- 4. Indentify the need for incorporating the three term controller based on the customized requirement of the control action
- 5. Analyze the systems behavior in digital domain and develop digital control algorithm for the

| ٥. | corrective action. | algorithm for the | | | | |
|--------|---|-----------------------------|--|--|--|--|
| Text | Book(s) | | | | | |
| 1. | Katsuhiko Ogata, "Modern Control Engineering", 2010, 5 th ed., Prentice Ha USA. | all, New Jersey | | | | |
| 2. | M. Gopal "Modern Control System Theory", 2014, 2 nd ed. New Age International, New Delhi, India. | | | | | |
| Refer | rence Book(s) | | | | | |
| 1. | M. Gopal,"Digital control and state variable methods", 2012, 4 th ed., Tata USA. | McGraw Hill, | | | | |
| 2. | Webb & Reis, "Programmable Logic Controller - Principles and Application ed., PHI, New Delhi, India. | ons", 2012, 5 th | | | | |
| 3. | I. J. Nagrath and M. Gopal, "Control Systems Engineering", 2017, 6 th International (p) Limited. New Delhi, India. | Ed., New Age | | | | |
| List o | f Experiments: (Through Inlab/Remotelab) | | | | | |
| 1. | Introduction to real time controller system operations | 4 hours | | | | |
| 2. | Speed regulation measurement of DC motor using armature control system | 4 hours | | | | |
| 3. | Speed regulation and torque measurement of AC Servomotor using armature control system | 4 hours | | | | |
| 4. | Modeling and performance analysis of stepper motor position control system | 4 hours | | | | |
| 5. | Performance analysis of BLDC motor control system and its parameter estimation | 4 hours | | | | |
| 6. | ON/OFF temperature control system using LabVIEW platform | 4 hours | | | | |

4 hours

Step response analysis of second order system using Matlab

| 8 | Frequency response analysis of | LEAD/LAG compens | sating network | 6 hours | |
|--------|---|--------------------|---------------------|------------|--|
| 9 | Temperature control of a pla platform/MSP430 | 6 hours | | | |
| 10 | Modelling and implementation of | 6 hours | | | |
| 11 | Modelling and implementation of a. Speed regulation of se with Matlab/MSP430 b. Water level controller c. Comparison of plant p controller | 6 hours | | | |
| 12 | | | | | |
| | | Tot | al Laboratory Hours | 60 hours | |
| Mode o | f Evaluation: Continuous Assessm | ent LabCAT and Lab | oFAT | | |
| Recomr | mended by Board of Studies | | | | |
| Approv | ed by Academic Council | No. 55 | Date | 13-06-2019 | |
| | | | | | |

| Course Code | Course Title | | L | T | P | J | C |
|--|---|--|-----------------------|--|-------------|--------------|------------|
| ECE5064 | Programming and scripting lan | guages | 0 | 0 | 4 | 0 | 2 |
| Prerequisite: | Nil | | Sy | llabı | ıs V | ersio | n |
| | | | | | 1.0 | | |
| Course Object | ives: | | | | | | |
| | se the students to the fundamentals of embedo | | ing. | | | | |
| | duce the GNU C, C++ Programming Tool Ch | nain in Linux. | | | | | |
| | y the basic programming of Python and R. | | | | | | |
| Expected Outo | | | | | | | |
| The students wi | | | | | | | |
| - | roblems using C | | | | | | |
| | ate and apply C++ tasks using linux scripts. | | | | | | |
| | anding the basic concepts of process and IPC | maahanisms | | | | | |
| | anding the basic concepts of process and IPC R for simple data oriented applications | meenamsiiis | | | | | |
| J. Trogram | 1 K for simple data offended applications | | | | | | |
| | | | | | | | |
| Task1 Er | nbedded Programming | 12 hours | | | | | |
| | g, Declarations and Expressions, Arrays, Poi | inters, Constru | cts, Dat | ta stı | ructu | ires | and |
| | bedded C (Keil). | | | | | | |
| Linked list, Elli | bedded C (Kell). | | | | | | |
| Linked list, Ein | bedded C (Kell). | | | | | | |
| | , | 12 hours | | | | | |
| Task:2 C- | ++ Programming. | 12 hours | ncancula | ntion | inh | erita | nce |
| Task:2 C-Programs for c | ++ Programming. lass, objects, member functions, access modifications. | fiers, OOPS en | | | | | nce |
| Task:2 C-Programs for cl | ++ Programming. | fiers, OOPS en | | | | | nce |
| Task:2 C-Programs for classification polymorphism | ++ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream | fiers, OOPS en n class to perfo | | | | | nce |
| Task:2 C-Programs for classification of the Polymorphism Task 3 Py | + Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream without Programming | fiers, OOPS en class to perfo | orm File | inpu | ıt-ou | | nce |
| Task:2 C-Programs for classification of the Polymorphism Task 3 Py | ++ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream | fiers, OOPS en class to perfo | orm File | inpu | ıt-ou | | nce |
| Task:2 C- Programs for cl polymorphism Task 3 Py Basic operation | + Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream without Programming | fiers, OOPS en class to perfo | orm File | inpu | ıt-ou | | nce |
| Task:2 C- Programs for cl polymorphism Task 3 Py Basic operation Task 4 Li | H+ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream thon Programming s, String manipulation, Dictionary, Signal plo | fiers, OOPS en class to perform class to perform 12 hours tting and proce | essing, (| inpu Grapl | ıt-ou | | nce |
| Task:2 C- Programs for cl polymorphism Task 3 Py Basic operation Task 4 Li | H+ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream thon Programming s, String manipulation, Dictionary, Signal plo | fiers, OOPS en class to perform class to perform 12 hours tting and proce | essing, (| inpu Grapl | ıt-ou | | nce |
| Task:2 C- Programs for cl polymorphism Task 3 Py Basic operation Task 4 Li Shell programm | H+ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream thon Programming s, String manipulation, Dictionary, Signal plo | fiers, OOPS en class to perform class to perform 12 hours tting and proce | essing, (| inpu Grapl | ıt-ou | | nce |
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| Task:2 C- Programs for classing polymorphism Task 3 Py Basic operation Task 4 Li Shell programm Task 5 R Data types, Data | H+ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream thon Programming s, String manipulation, Dictionary, Signal plo nux ning, Regular expression, Process creation, Interprogramming | fiers, OOPS en class to perform class to perform 12 hours entring and process ter process compared 2 hours | essing, (| inpu Grapl | ıt-ou | | nce |
| Task:2 C- Programs for cl polymorphism Task 3 Py Basic operation Task 4 Li Shell programm Task 5 R Data types, Data Text Book(s) | H+ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream thon Programming s, String manipulation, Dictionary, Signal plo nux ning, Regular expression, Process creation, Interprogramming a plotting ,analysis and regression, Machine in | fiers, OOPS en class to perform class to perform 12 hours tting and proce 6 hours ter process com 2 hours ntelligence | essing, C | Grapl | nics | tput | |
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| Task:2 C- Programs for classic operation Task 3 Py Basic operation Task 4 Li Shell programm Task 5 R Data types, Date Text Book(s) 1. David For developm 2. Brandon ed. edition 3. Garrett | Hass, objects, member functions, access modifications, constructors, and destructors Stream than Programming s, String manipulation, Dictionary, Signal plomus mux ming, Regular expression, Process creation, Interprogramming a plotting ,analysis and regression, Machine in Russell, "Introduction to Embedded systemment Environment", 2010, 1rd edition, Morgan Rhodes, John Goerzen, "Foundations of Python Apress Publisher Grolemund, "Hands-On Programming with | fiers, OOPS en class to perform class compared to class compared to class | essing, Communication | Graple ation ation of the results of | hhe //, 20 | Ardu | ino 3rd |
| Task:2 C- Programs for cl polymorphism Task 3 Py Basic operation Task 4 Li Shell programm Task 5 R Data types, Dat Text Book(s) 1. David F developm 2. Brandon ed. editic 3. Garrett G Simulation | H+ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream rthon Programming s, String manipulation, Dictionary, Signal plo nux ning, Regular expression, Process creation, Interprogramming a plotting ,analysis and regression, Machine in Russell, "Introduction to Embedded systemment Environment", 2010, 1 rd edition, Morgan Rhodes, John Goerzen, "Foundations of Python Apress Publisher Grolemund, "Hands-On Programming with ons", 2014, Shroff/O'Reilly Publisher | 12 hours tting and proce 6 hours ter process com 2 hours ntelligence as Using ANS a & Claypool Process on Network Process Com R: Write Yours | essing, Communication | Graple of the street of the st | hhe Annetic | Ardu 014, | ino 3rd |
| Task:2 C- Programs for classic operation Task 3 Py Basic operation Task 4 Li Shell programm Task 5 R Data types, Data Text Book(s) 1. David For developm 2. Brandon ed. edition 3. Garrett Constitution | Hass, objects, member functions, access modifications, constructors, and destructors Stream Thon Programming s, String manipulation, Dictionary, Signal ploe nux ning, Regular expression, Process creation, Interprogramming a plotting ,analysis and regression, Machine in Russell, "Introduction to Embedded systemment Environment", 2010, 1 rd edition, Morgan Rhodes, John Goerzen, "Foundations of Python Apress Publisher Grolemund, "Hands-On Programming with ons", 2014, Shroff/O'Reilly Publisher Petersen, "Linux: The Complete Reference | 12 hours tting and proce 6 hours ter process com 2 hours ntelligence as Using ANS a & Claypool Process on Network Process Com R: Write Yours | essing, Communication | Graple of the street of the st | hhe Annetic | Ardu 014, | ino 3rd |
| Task:2 C- Programs for classing polymorphism Task 3 Py Basic operation Task 4 Li Shell programm Task 5 R Data types, Date Text Book(s) 1. David Find developm 2. Brandon ed. edition 3. Garrett Simulation 4. Richard Education | Hass, objects, member functions, access modifications, constructors, and destructors Stream and Programming so the Programming | 12 hours tting and proce 6 hours ter process com 2 hours ntelligence as Using ANS a & Claypool Process on Network Process Com R: Write Yours | essing, Communication | Graple of the street of the st | hhe Annetic | Ardu 014, | ino 3rd |
| Task:2 C- Programs for classic operation Task 3 Py Basic operation Task 4 Li Shell programm Task 5 R Data types, Data types, Data types, Data developm 1. David Factorial developm 2. Brandon ed. edition 3. Garrett Grands Simulation 4. Richard Education Mode of Evaluation | H+ Programming. lass, objects, member functions, access modifications, constructors, and destructors Stream withon Programming s, String manipulation, Dictionary, Signal plo nux ning, Regular expression, Process creation, Interprogramming a plotting ,analysis and regression, Machine in Russell, "Introduction to Embedded systemment Environment", 2010, 1 rd edition, Morgan Rhodes, John Goerzen, "Foundations of Python Apress Publisher Grolemund, "Hands-On Programming with ons", 2014, Shroff/O'Reilly Publisher Petersen, "Linux: The Complete Reference on ation:Continuous Assessment and FAT | 12 hours tting and proce 6 hours ter process com 2 hours ntelligence as Using ANS a & Claypool Process on Network Process Com R: Write Yours | essing, Communication | Graple of the street of the st | hhe Annetic | Ardu 014, | ino 3rd |

| Course Code | Course Title | L | T | P | J | C |
|--------------------|--------------------------------------|-----|-------|------|-----|-----|
| ECE5065 | MICROCONTROLLERS FOR IOT PROTOTYPING | 2 | 0 | 2 | 0 | 3 |
| Prerequisite: | Prerequisite: Nil | | llabı | us V | ers | ion |
| | | 1.0 |) | | | |

Course Objectives: The course is aimed to

- 1. Introduce low power microcontrollers and to develop the skill set of programming low power sensing applications.
- 2. Impart the knowledge of various peripheral related to sensing and communication using wired or wireless means.
- 3. Upgrade the students by introducing them Advanced ARM Cortex microcontrollers
- 4. Develop the skill set of students to build IoT systems and sensor interfacing.

Course Outcomes (CO): At the end of the course the student should be able to

- 1. Design and develop embedded programs for low power microcontrollers for sensor applications.
- 2. Develop ARM basic and advanced programs.
- 3. Interface and deploy analog and digital sensors
- 4. Develop communication system with sensor units
- 5. Design develop IoT systems using Wi-Fi CC3200.
- 6. Program the single board computers to read sensor data and posting in cloud.

Module:1 MSP430 microcontrollers

6 hours

Architecture of the MSP430, Memory, Addressing modes, Reflections on the CPU instruction set. Clock system, Exceptions: Interrupts and resets. Functions and subroutines, Mixing C and assembly language, Interrupts, Interrupt service routines, Issues associated with interrupts, Lowpower modes of operation.

Module:2 ARM Cortex MX microcontroller

6 hours

ARM Cortex M4: Assembly language basics, Thumb-2 Technology, ARM Instruction set, Cortex M4 architecture, advantages, peripherals, instruction set, floating point operations, Advanced Cortex MX Microcontroller, core, architecture, on-chip wi-fi.

Module:3 Display and Communication modules

4 hours

GPIO, LCD display, graphical display, relays, Peripheral programming SPI, I2C, UART, Zigbee controller.

Module:4 | Sensors interfacing

4 hours

Sensors interfacing techniques- Port Programming, ADC, SPI thermometer, I2C thermometer, PWM generation and demodulation, DTH11, single wire thermometer, Frequency counters.

Module:5 | **Microcontrollers for IoT**

2 hours

ESP8266,NodeMCU,TI-CC3200,Access point and station point mode, HTTP, MQTT, transmission and receiving, Intel-Gallileo boards.

| Mo | dule:6 | Single board computers | | 4 | hours | |
|--------------|-----------|--|---------------------|----------------------|-------------------------------|----------------------------|
| | | pi board, porting Raspbian, | sensor interface e | xamples | , Python programm | ing for cloud |
| acce | ess, sens | sor systems using Arduino b | oards | | | |
| | | | | | | |
| | dule:7 | Cloud interfacing | | | hours | |
| Inte | erfacing | and data logging with cloud | : Thing speak, Thi | ngs boa | rd, Blync platform. | |
| N/L- | J10 | C | | 12 | 1 | |
| IVIO | dule:8 | Contemporary Issues | | Z | hours | |
| | | | Total Lect | ure: 3 | 0 hours | |
| Tex | xt Book | (s) | 10001200 | ure. o | o nours | |
| 1. | John I | H. Davies, "MSP430 Microc | ontroller Basics", | 2011, 2 ⁿ | d ed., Newnes publi | shing, New |
| | York. | E 1 (II 1D 1 CM | 1 0 1 | · D · | 1 4 1' ' | 22 2014 4th |
| 2. | | Fraden, "Hand Book of Mod ringer, New York. | lern Sensors: phys: | ics, Desi | gns and Application | ns", 2014, 4" |
| Ref | ference | | | | | |
| 1. | | Y. Yurish,"Digital Sensors | and Sensor System | ns: Pract | tical Design", 2011. | 1 st ed., IFSA |
| • | | ning, New York. | and Sensor Syster | 115. 1 140 | | 1 00., 11 511 |
| 2. | | an W Valvano, "Introduction | on to ARM Corte | x –M3 | Microcontrollers", | 2012, 5 th ed., |
| | | Space publishing, New Yor | | | | |
| 3. | | nmad Ali Mazidi, Shujen O | | | | |
| | | mming and Interfacing: U | Jsing C Languag | e", 201 | 5, 2 nd ed., Mazid | i and Naimi |
| M | | ning, New York. | | 1: | D | : D:4 |
| | | valuation:CAT, Digital Assi Makeathon and FAT. | gnments, Quiz, O | nime co | urse, Paper publicat | ion, Projects, |
| | | periments: (Indicative) | | | | |
| | | with MSP430 (CCStudio) | | | | 6 hours |
| | _ | Task 1: Port programming | of MSP430 micro | controlle | rs | |
| | | Task 2: Analog to Digital C | | | | |
| | | Task 3: LCD display of cha | racters and number | ers. | | |
| | | Task 4: Timer | | | | |
| 2. V | | g with ARM (Keil and energ | | | | 8 hours |
| | | Task 1: Peripheral program | ming of ARM/ bo | ard | | |
| | | Task 2: PWM generation Task 3:Configuring CC320 | 0 wifi aanfigurati | on UTT | TD and MOTT | |
| | | cocol | o, will configurati | 011 ,111 1 | r and MQ11 | |
| 3. 1 | | wer wireless transmission us | ing Zighee | | | 8 hours |
| | _ | Task 1 : Interfacing Zigbee | | SP 430 1 | microcontroller | |
| | | g SPI/UART. | | | | |
| | • Sub | Task 2: Programming sleep | and wake up mod | le of MS | P 430. | |
| 4. Io | oT syste | ems | | | | 8 hours |
| | | rking with Raspberry pi usin | ng Python. | | | |
| | | uino platform | .1 | | | |
| | • WOI | rking with open source cloud | us | Total | I I abaratany Hauma | 30 hours |
| Mo | de of Fx | valuation:Continuous Assess | ement and FAT | 10ta | l Laboratory Hours | 30 Hours |
| | | ded by Board of Studies | 26/04/2019 | | | |
| | | by Academic Council | 55 | Date | 13/06/2019 | |
| 1/1 | 1 3 4 6 | <i>J</i> | - - | | | |

| Course Code | Course Title | L | T | P | J | C |
|--------------------|---|---|------|------|-------|----|
| ECE6001 | WIRELESS SENSOR NETWORKS AND IoT | 2 | 0 | 0 | 4 | 3 |
| Pre-requisite | ECE 5061- IoT Fundamentals and Architecture | | llab | us V | 'ersi | on |
| | | | | 1.0 | | |

- 1. To identify and expose the students to the central elements in the design of communication protocols for the WSNs.
- 2. To disseminate the design knowledge in analyzing the specific requirements for applications in WSNs regarding energy supply, memory, processing, and transmission capacity
- 3. To get the perception of mobile ad hoc networks, design, implementation issues, and solutions based on different algorithms and protocols for power management, sensor data routing and query processing.
- 4. To associate, hardware platforms and software frameworks used to realize dynamic Wireless sensor network

Course Outcomes

- 1. Assess the applicability and limitations of communication protocols for a real time WSN application.
- 2. Confirms the behavior of mobile ad hoc networks (MANETs)and correlates the infrastructure-based networks.
- 3. Proactive in understating the routing protocols function and their implications on data transmission delay and bandwidth.
- 4. Able to establish networks with an attempt to reduce issue of broadcast and flooding techniques.
- 5. Contribute appropriate algorithms to improve existing or to develop new wireless sensor network applications.
- 6. Familiarize the protocol, design requirements, suitable algorithms, and the state-of-the-art cloud platform to meet the industrial requirement.
- 7. On a profound level to implement hardware & software for wireless sensor networks in day to day life

| Module:1 | Network for embedded systems | 3 hours | | | | |
|--|---|------------------------------------|--|--|--|--|
| RS232, RS485, SPI, I2C, CAN, LIN, FLEXRAY. | | | | | | |
| | | | | | | |
| Module:2 | Embedded wireless communication and | 5 hours | | | | |
| | Protocols | | | | | |
| Bluetooth, Zigbee, V | Wifi, MiWi, Nrf24, Wireless LAN &PAN, UWB | | | | | |
| | | | | | | |
| Module:3 | Wireless sensor network (WSN) | 4 hours | | | | |
| Characteristic and c | challenges, WSN vs Adhoc Networks, Sensor nod | e architecture, Physical layer and | | | | |
| transceiver design | considerations in WSNs, Energy usage profile, | Choice of modulation scheme, | | | | |
| Dynamic modulation scaling, Antenna considerations. | | | | | | |
| | | | | | | |
| Module:4 | WSN (Medium access control) | 5 hours | | | | |
| Fundamentals of MAC protocols - Low duty cycle protocols and wakeup concepts, Contention Based | | | | | | |
| protocols, Schedule-based protocols - SMAC - BMAC, Traffic-adaptive medium access protocol | | | | | | |

(TRAMA), The IEEE 802.15.4 MAC protocol. Module:5 **Sensor Network Architecture** 5 hours Data Dissemination, Flooding and Gossiping-Data gathering Sensor Network Scenarios, Optimization Goals and Figures of Merit, Design Principles for WSNs- Gateway Concepts, Need for gateway, WSN and Internet Communication, WSN Tunneling IP based WSN Module:6 Circuit switching, packet switching, concept of IPV4, IPV6, 6LOWPAN and IP, IP based WSN, 6LOWPAN based WSN. Module:7 **Tiny OS** 2 hours Tiny OS for WSN and IoT, M2M communication, Alljoyn network Module:8 **Contemporary issues** 2 hours Total Lecture hours: 30 hours **Text Book(s):** Holger Karl, Andreas Willig, "Protocols and Architectures for Wireless Sensor Networks" 1. 2011, 1st ed., John Wiley & Sons, New Jersey. Jun Zheng, Abbas Jamalipour, "Wireless Sensor Networks: A Networking Perspective", 2 2014, 1st ed., Wiley-IEEE Press, USA. Reference Book(s) Waltenegus W. Dargie, Christian Poellabauer, "Fundamentals of Wireless Sensor 1. Networks: Theory and Practice", 2014, 1st ed., John Wiley & Sons, New Jersey. 2 Ian F. Akyildiz, Mehmet Can Vuran, "Wireless Sensor Networks", 2011, 1st ed., John Wiley & Sons, New Jersey. Zach Shelby, Carsten Bormann, "6LoWPAN: The Wireless Embedded Internet", 2009, 1st 3 ed., John Wiley & Sons, New Jersey. Mode of Evaluation: CAT, Digital Assignments, Quiz, Online course, Paper publication, Projects, Hackathon/Makeathon and FAT **List of Projects: (Indicative) 15 Hours SLO: 6.7**

- 1. Smart door locks offer sophisticated "access control" features to any home or business. Proximity sensors like Bluetooth and NFC can enable a door to unlock whenever an authorized user's smartphone approaches. Users can also remotely lock and unlock the door, or share access with any number of others, using mobile apps. Keeping the above design parameters implement a Smart locks for apartment's security using IoT principle.
- 2. The refrigerator is the most frequently used domiciliary/kitchen electrical appliance all over the world for food storage. Implement a Smart refrigeration module designed to convert any existing normal refrigerator into a smart and low-cost machine using sensors. Smart refrigerator compares the status of the food for e.g. weight, quantity etc. The smart refrigerator must also able be remotely controlled and notifies the user about scarce products via wifi module (internet) on user's mobile android application. Add functionality which includes the ice ready indication, power saving, smell detection, overweighting etc.
- 3. Water has become a scarce resource and is crucial to the production of food. Therefore, design and implement a wireless sensor network to manage and conserve this vital resource. Part of the system

includes the design and development of three sensor nodes to monitor soil moisture. An interface to display and store the status of the water content and also to be uploaded to a web server.

- 4. Design and provide necessary modules and service, such as command dissemination, feedback module, data logging and collection module, network programming module and time synchronization service between different sensor nodes.
- 5. WSN has a variety of services based on sensor network architecture. Common issues such as network bandwidth reduction, collision occurrence and performance deterioration due to the broadcasting of message in large-scale networks have become main challenges. To overcome these issues implement routing algorithm based on data-centric routing and address-based routing schemes, by which the query messages are delivered to the target area by using address-based routing scheme, then, the broadcast scheme.

Mode of Evaluation:Review I,II,III

| Recommended by Board of Studies | ded by Board of Studies 26/04/2019 | | |
|---------------------------------|------------------------------------|------|------------|
| Approved by Academic Council | No. 55 | Date | 13/06/2019 |

| Course Code | Course Title | L | T | P | J | C |
|--------------------|--|---|------|------|------|----|
| ECE6030 | SIGNAL PROCESSING AND DATA ANALYTICS | 2 | 0 | 2 | 0 | 3 |
| Pre-requisite | Pre-requisite ECE5062 - Data Acquisition | | llab | us v | ersi | on |
| | | | | v.1 | | |

- 1. To introduce the concepts of *discrete* time *signal processing* and the characterization of *random signals*.
- 2. To present the basic theory of modeling the signals and the methods of estimating the unknowns using prediction filters
- 3. To provide a comprehensive understanding on applying FFT, DCT, and wavelet techniques for extracting the signal features.
- 4. To provide an overview of analysing big data using intelligent techniques and an in-depth introduction to two main areas of *Machine Learning:* supervised and unsupervised.

Expected Course Outcomes:

Module:6 | Machine learning

- 1. Apply FFT, DCT wavelet techniques for extracting the features from the big data
- 2. Develop algorithms that can be used to analyse the real-world univariate and multivariate time series data.
- 3. Design an approach to leverage data using the steps in the machine learning process.
- 4. Understand and apply both supervised and unsupervised classification methods to detect and characterize patterns in real-world data.
- 5. Estimate the signal parameters and identify the model using ARMA models and prediction filters.
- 6. Understand the methods of visualization and analysis of big data.

Module:1 Discrete Random Signal Processing 4 hours Random Processes, Ensemble Average, Gaussian Process, Multi variate Gaussian Process, Stationary process, Autocorrelation, Auto Covariance, Ergodicity, White noise, Power Spectrum, Filtering of Random Process Module:2 | Signal Modeling 4 hours ARMA, AR, MA Models. Wiener filter, Linear prediction, Kalman Filter. **Module:3** | **Feature extraction** FFT, Power spectrum, DCT, filter banks, Wavelet, Wavelet Packets, Cepstrum **Module:4** | Time series analysis 4 hours Basic analysis, Univariate time series analysis, Multivariate time series analysis, non stationary time series. **Module:5** | **Reduction of dimensionality** 4 hours Bayesian decision, Linear discrimination, Principal Component analysis, SVD, Independent Component Analysis.

4 hours

| - | | learning, generative algorithm ering, Neural network (SOM, A | | | 1 |
|-----|---|--|---------------------|------------------------------|---------------------------------|
| Mo | dule:7 | Big Data Analytics | | 4 hours | |
| | | Big data analytics, visualiz | | exploration, bas | sic and intermediate |
| | - | ear and logistic regression, dec | cision tree. | | |
| Mo | dule:8 | Contemporary Issues | | | 2 hours |
| | | | Total Lecture: | 30 hours | |
| Tex | xt Book(| (s) | | 1 | |
| 1. | J. G. | Proakis, DG. Manolakis and mms and applications", 2012, 4 | | | rocessing principles, |
| 2. | Sophoo Delhi I | eles J. Orfanidis, "Inroduction | to signal Processin | ng" 2010, 2 nd ed | ., Prentice Hall, New |
| Ref | ference : | Books | | | |
| 1. | | niem V. A.V and Schaffer R. V e Hall,. New Delhi, India | W, "Discrete- time | signal Processi | ng", 2014, 3 rd ed., |
| 2. | | s A. Runkler, "Data Analyt is", 2016, 2 nd ed., Springer Ver | | Algorithms fo | r Intelligent Data |
| 3. | Kevin Press, | P. Murphy, "Machine Learning | ng: A Probabilistic | Perspective" 2 | 2012, 1 st ed., MIT |
| | | | | | |
| | | Evaluation: CAT, Digital As ackathon/Makeathon and FAT | signments, Quiz, | Online course | e, Paper publication, |
| | • | llenging Experiments (Indica | ntive) | | |
| 1. | Design | and implementation of Wiener | r filter and Kalmar | n filter. | 6 hours |
| 2. | _ | and implementation of filter b (speech, audio). | anks and wavelets | for random | 6 hours |
| 3. | _ | and implementation of Principagle Value Decomposition (SV | - | alysis (PCA) | 6 hours |
| 4. | Design an expert system for simple application (speech recognition, speaker recognition, face recognition). | | | 6 hours | |
| 5. | Consid | er a real time data available in c system to determine the avera | college campus an | | a 6 hours |
| | | | | Laboratory Hou | rs 30 hours |
| | | aluation:Continuous Assessme | ent and FAT | | |
| Red | commen | ded by Board of Studies | 26/04/2019 | | |
| | | y Academic Council | No.55 | Date | 13/06/2019 |

| Course code | Course title | L | T | P | J | C |
|---------------|-------------------------------|----|------|------|------|----|
| ECE5006 | FLEXIBLE AND WEARABLE SENSORS | 3 | 0 | 0 | 0 | 3 |
| Prerequisite: | ECE5001-Principles of Sensors | Sy | llab | us v | ersi | on |
| | | | | 1.1 | | |

- 1. To provide the overview of flexible electronics technology and the issues with materials processing for thin film electronics.
- 2. To expose the students for the materials selection and patterning methods for thin film electronics development.
- 3. To describe the process involved in transferring the flexible electronics from foils to textiles and also the challenges, opportunities and the future of wearable devices.
- 4. To expose the students to the design, challenges of wearable sensors employed for sensing the physical and biological parameters and the process involved in the conversion of conducting and semiconducting fibers to smart textiles.

Expected Course Outcome:

- 1. Realize the technology developments in the flexible electronics technology.
- 2. Ability to identify the suitable materials and its processing for the development of thin film electronics
- 3. Ability to design the pattern and develop with suitable patterning methods.
- 4. Realize the process involved in the transformation of electronics from foils to textiles
- 5. Acquire the design knowledge for developing wearable sensors for physical and chemical parameters
- 6. Gain the competency in transferring the conducting and semiconducting fibers to smart textiles

Module:1 Overview of flexible electronics technology

5 hours

History of flexible electronics - Materials for flexible electronics: degrees of flexiblility, substrates, backplane electronics, front plane technologies, encapsulation - Fabrication technology for flexible electronics - Fabrication on sheets by batch processing, fabrication on web by Roll-to-Roll processing - Additive printing.

Module:2 Amorphous and nano-crystalline silicon materials and Thin film transistors 7 hours

Fundamental issues for low temperature processing - low temperature amorphous and nanocrystalline silicon - characteristics of low temperature dielectric thin film deposition - low temperature silicon nitride and silicon oxide characteristics - Device structures and materials processing - Device performance - Contacts for the device - Device stability.

Module:3 Materials and Novel patterning methods for flexible electronics 7 hours

Materials considerations for flexible electronics: Overview, Inorganics semiconductors and dielectrics, organic semiconductors and dielectrics, conductors - Print processing options for device fabrication: Overview, control of feature sizes of jet printed liquids, jet printing for etch mask patterning, methods for minimizing feature size, printing active materials.

Module:4 Flexible electronics from foils to textiles 6 hours

Introduction -Thin film transistors: Materials and Technologies - Review of semiconductors employed in flexible electronics - Thin film transistors based on IGZO - Plastic electronics for

| sma | art textile | es - Improvements and limit | tations. | | | | |
|--|--|---|---|--|---|--|--|
| | | | | | | | |
| | | Wearable haptics | | | 6 hours | | |
| Cha | allenges | | re of wearables - | | lothing: The meta wearable - For wearable haptic devices - | | |
| Mo | dule:6 | Wearable Bio, Chemical | and Inertial sensor | rs | 6 hours | | |
| Introduction-Systems design - Challenges in chemical and biochemical sensing - Application areas -Wearable inertial sensors - obtained parameters from inertial sensors - Applications for wearable motion sensors - Practical considerations for wearable inertial sensor - Application in clinical practice and future scope | | | | | | | |
| Mo | dule:7 | Knitted electronic textile | <u> </u> | | 6 hours | | |
| | | | | extile s | ensors for physiological state | | |
| mo | nitoring - | | Noninvasive sweat r | nonitori | ing by textile sensors and other | | |
| 3.5 | 110 | Ct | | | | | |
| Mo | dule:8 | Contemporary issues: | | | 2 hours | | |
| | | | | | | | |
| | | | | | | | |
| | | | Total Lecture hou | re• | 45 hours | | |
| Тех | xt Rook(| s) | Total Lecture hour | rs: | 45 hours | | |
| 1. 2. | Wellnes Willian | I J. McGrath, Cliodhna Ni ss and Environmental Appl n S. Wong, Alberto Salleo, | Scanaill, Dawn Natications", 201, 1 st Ed | fus, "Sei | nsor Technologies: Healthcare, Apress Media LLC, New York. ials and Applications, 2011, 1st | | |
| 1. 2. | Michae Wellnes Willian Edition | I J. McGrath, Cliodhna Ni ss and Environmental Appl n S. Wong, Alberto Salleo, , Springer, New York. | Scanaill, Dawn Natications", 201, 1 st Ed | fus, "Sei | nsor Technologies: Healthcare, Apress Media LLC, New York. | | |
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| 1. 2. Ref 1. 2 3 | Michae Wellne: William Edition ference I Edward and Ap Kate I interact Guozhe Edition Yugang From I Techno | I J. McGrath, Cliodhna Niss and Environmental Appl a S. Wong, Alberto Salleo, Books Sazonov, Michael R. New plications", 2014, 1st Editional In Shen, Editional Environmental Editional Editions In Shen, Zhiyong Fan, "Flow of the Market Wearable Editions of the Editional Edition Edition Edition Editional Edition Editions of the Edition Edition Edition Edition Editions of the Edition Edition Edition Edition Editions of the Edition | Scanaill, Dawn Natications", 201, 1st Ed Flexible Electronics man, "Wearable Sen on, Academic Press, One Electronics: Destition, Marker Media lexible Electronics: Ing Co, Singapore. Semiconductor Nandalics to Sensors and William Andrew, Ne | Fus, "Section, A section of the sect | nsor Technologies: Healthcare, Apress Media LLC, New York. ials and Applications, 2011, 1 st and amentals, Implementation lge. ototype, and wear your own lands. Interials to Devices", 2015, 1 st als for Flexible Technologies: gy Storage (Micro and Nano | | |
| 1. 2. Ref 1. 2 3 | Michae Wellne: William Edition ference I Edward and Ap Kate I interact Guozhe Edition Yugang From I Techno | I J. McGrath, Cliodhna Niss and Environmental Appl a S. Wong, Alberto Salleo, Springer, New York. Books Sazonov, Michael R. New plications", 2014, 1st Edition Iartman, "Make: Wearable ive garments", 2014, 1st Edition En Shen, Zhiyong Fan, "Flaton, World Scientific Publishing, Sun, John A. Rogers, "Photovoltaics and Electron | Scanaill, Dawn Natications", 201, 1st Ed Flexible Electronics man, "Wearable Sen on, Academic Press, One Electronics: Destition, Marker Media lexible Electronics: Ing Co, Singapore. Semiconductor Nandalics to Sensors and William Andrew, Ne | Fus, "Section, A section of the sect | nsor Technologies: Healthcare, Apress Media LLC, New York. ials and Applications, 2011, 1 st and amentals, Implementation lge. ototype, and wear your own lands. Interials to Devices", 2015, 1 st als for Flexible Technologies: gy Storage (Micro and Nano | | |
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| Course code | Course title | L | T | P | J | C |
|---------------|-------------------------|---|------|-------|------|-----|
| ECE5008 | MICRO AND NANO FLUIDICS | 2 | 0 | 0 | 4 | 3 |
| Prerequisite: | Nil | S | llat | ous v | vers | ion |
| | | | | | | 1.0 |

- 1. Introduce and discuss the fundamental physics of micro and nano scale fluids and their hydrodynamics.
- 2. Comprehend techniques of miniaturization, methods and tools to create microfluidic architectures and discuss various existing microfluidic devices.
- 3. Discuss and identify the usage of microfluidics in various lab-on-chip and bioreactor applications
- 4. Investigate and compare microfabrication techniques to design vasculature and 3D microchannels.

Expected Course Outcome:

- 1. Identify and understand the fundamental physics of micro and nano scale fluids and their hydrodynamics. Comprehend the basics of miniaturization, methods and tools to create microfluidic architectures.
- 2. Recognise and interpret the working principle of various existing microfluidic devices.
- 3. Describe various microfluidic lab-on-chip applications.
- 4. Acquaint with various bioreactor based microchips
- 5. Investigate and compare various microfabrication techniques to design vasculature and 3D micro channels with existing techniques.
- 6. Incorporate simulation and microfluidic device fabrication knowledge for developing various microfluidic devices.

Module:1 Fundamentals for Microscale and Nanoscale 5 hours

Fluids and nonfluids, properties of fluids, classification of fluids, Newtonian and Non Newtonian fluids, pressure driven flow, reynolds number, Electrokinetic phenomena, Electric double layer, debye length, coupling species transport and fluid mechanics, Micro channel Resistance, Shear stress, capillary flow, flow through porous media, Diffusion, surface tension, contact angle and Wetting.

Module:2 Hydrodynamics 4 hours

Introduction to surface, surface charge, surface energy, Thermodynamics of surfaces, Fluids in Electrical fields, The Navier Strokes equation, Boundary and Initial conditions problems,

Module:3 Fabrication methods and techniques 4 hours

Patterning, Photolithography, Micromachining, Micromolding, Soft lithography, PDMS properties, Fabrication of microfludics channels.

Module:4 | Microfluidic Devices | 3 hours

Droplet Microfluids, Active Flow control, Microvalves, Electrically actuated microvalves, Micromixers, Combinational Mixers, Elastomeric Micromixers

| Module:5 Microfluidics Lab on Chip 3 hours | |
|--|--|
|--|--|

| Microfluidic for Flow cytometry, cell sorting, cell trapping, Cell culture in microenvironment. | | | | | | | |
|---|---|-------------------------|---------|---------|-----------|----------------------|--|
| | | | | | | | |
| Module:6 | Bioreactors on Microchi | | | 4 ho | | | |
| Enzyme assay and inhibition, Chemical synthesis in microreactors, Sequential reaction and | | | | | | | |
| Parallel read | ction in micro reactors, cher | nical separation, lic | quid c | chrom | atograph | y | |
| | | | | 1 | | | |
| | 3D Vascular Network for | | | 5 ho | | | |
| | Microfabrication of vascu | · · | | | | · · | |
| | nined 3D channels, Introdu | | Multip | ohysic | s, Mathe | matical Modeling of | |
| Microchann | els in Microfludics Model b | ouilder. | | | | | |
| | | | | I | | | |
| Module:8 | Contemporary issues: | | | | | 2 hours | |
| | | | | | | | |
| | | | | 20.1 | | | |
| | | Total Lecture ho | urs: | 30 h | ours | | |
| | | | | | | | |
| Text Book(| | | | | | | |
| 1. Cleme | , | | | luidic | s: The | ory and Selected | |
| | cations",2013, 1 st ed., John van Prakash, JunghoonYee | | | | 1' Cl' | 1: Ct 1 | |
| | | | | | | lics: Systems and | |
| Reference l | ations",2014, 1 st ed., Willian | ii Andrew; Norwic | n, ne | ew ro | ork. | | |
| | | MEMS" 2012 1st | 24 C | DC D | rogg Ilni | tad Vinadam | |
| | Folch, "Introduction to Biol Tabeling, "Introduction | | | | | | |
| | Great Britain. | to Microffuldics, | 2011 | 1, Ke | print ea. | , Oxioid Oniversity | |
| | 1 James Li, Yu Zhou , "Mi | arofluidia Daviass | for E | Diama | dical An | nlications" 2012 1st | |
| - 3 | Vood head Publishing, Cam | | 101 1 | Sioine | uicai Ap | plications, 2013, 1 | |
| | ice Conlisk. A, "Essentials | | Nanot | fluidia | ec. With | Applications to the | |
| | gical and Chemical Sciences | | | | | | |
| | aluation: CAT / Assignmen | | | | | y 11055, 110W 1 OIK. | |
| 111000 01 111 | aradion. Crit / ribbigilillon | ., Zuiz/1111/11 | oject / | , Delli | .11141 | | |
| Mode of ass | essment: Continuous Asses | sment and FAT | | | | | |
| | ded by Board of Studies | 21-08-2017 | | | | | |
| | y Academic Council | 1 | Date | | 05-10-20 | 17 | |
| TF-5.500 | <i>J</i> | | | 1 | | - | |

| Course Code | Course Title | L | T | P | J | C | | |
|--|-----------------------------------|---|---|------------------|---|---|--|--|
| ECE5066 | Chemical and Environmental Sensor | 2 | 0 | 2 | 0 | 3 | | |
| Pre-requisite: ECE5060-Principles of Sensors and Signal Conditioning | | | | Syllabus Version | | | | |
| | | | | 1.0 | | | | |

- 1. To extend engineering principles to electrochemical sensor development with a clear understating of oxidation and reduction of an electrolytic cell.
- 2. To propound the conception of ion selective and enzyme stabilized electrodes for the detection of chemical and biomolecules.
- **3.** To be expedient in applying specific interaction methods in the recognition of ion selective gases using metal oxide based sensors.
- **4.** Ability to analyze the modes of vibration and develop the suitable mass and thermal sensitive sensors.

Course Outcomes

- 1. Realize the need for half-cell and to analyze potential developed in any electrochemical cell. Apply the same for ion selective measurement
- 2. Be familiar with a wide range of chemical sensing methods and material characteristics to be applied in biosensors.
- 3. Ability to design gas sensors for commercial and industrial applications.
- 4. Gain knowledge of nanomaterials for biological and medical applications
- 5. Able to discuss, develop and apply site specific antigen-antibody sensors design for most common diseases like metabolic disorders

Evaluate process design criteria for gas treatment and air quality analysis

Module:1 Electrochemistry

4 hours

Thermodynamics, , Enthalpy, Entropy, Gibbs free Energy, Law of Mass Action, simple Galvanic Cells, Electrode – Electrolyte Interface, Fluid Electrolytes, Dissociation of Salt, Solubility Product, Ion Product, pH Value, Ionic Conductivity, Ionic Mobility, Phase Diagrams.

Module:2 Transduction Principles

4 hours

Transduction Elements- Electrochemical Transducers-Introduction Potentiometry and Ion-Selective Electrodes: The Nernst Equation Voltametry and amperometry, conductivity, FET, Modified Electrodes, Thin-Film Electrodes and Screen-Printed electrodes, photometric sensors

Module:3 Chemical Sensing Elements

4 hours

Ionic recognition, molecular recognition-chemical recognition agent, spectroscopic recognition, biological recognition agents. Immobilization of biological components, performance factors of Urea Biosensors, Amino Acid Biosensors, Glucose Biosensors and Uric Acid, factors affecting the performance of sensors.

Module:4 Potentiometric and Amperometric Sensors

4 hours

Potentiometric- Ion selective electrodes- pH linked, Ammonia linked, CO2 linked, Silver sulfide linked, Iodine selective, amperometric -bio sensors and gas sensors, Amperometric enzyme electrodes: substrate and enzyme activity, Detection mode and transduction method, mediated and modified electrodes, pH glass and ion selective electrodes, solid state and redox electrodes,

| Module:5 Optical Biosensor and Immunosensors Biosensor | | 4 hours |
|--|--|-------------------------------|
| Fiber ontic bio | sensor Fluorophore and chromophore based b | piosensor Bioluminescence and |

chemiluminescence based biosensors, Non labled and labled immune sensors, Microbial Biosensors: electrochemical, photomicrobial, Microbial thermistor. Application of microbial biosensors in glucose, ammonia, acetic acid, alcohol, BOD, methane sensing

Sensors in exhaust gas treatment Module:6 4 hours Engine combustion process, Catalytic exhaust after treatment, Emission limits, Exhaust sensors and Engine control, Emission test cycles, On-board diagnose (OBD): Diagnose Strategies, Exhaust sensors for OBD, Control Sensors: Hydro-Carbon Sensors, NOx-Sensors, Temperature Sensors, Oxygen Sensors. Measurement techniques for air quality Module:7 4 hours Measurement techniques for particulate matter in air. Specific gaseous pollutants analysis and control- Measurement of oxides of sulphur, oxides of nitrogen unburnt hydrocarbons, carbonmonoxide, dust mist and fog. **Module:8 Contemporary Issues** 2 hours Total Lecture: | 30 hours Text Book(s) Janata, Jiri, "Principles of Chemical sensors", 2014, 2nd edition, Springer, New York. Reference Book(s) Brian R Eggins, "Chemical Sensors and Biosensors", (Part of AnTS Series), 2010, 1st edition, John Wiley Sons Ltd, New York. Peter Grundler, "Chemical Sensors: Introduction for Scientists and Engineers", 2011, 1st 2. edition, Springer, New York. 3. R.G.Jackson, "Novel Sensors and Sensing", 2012, 1st edition, Philadelphia Institute of Physics. 4. Florinel-Gabriel Banica "Chemical Sensors and Biosensors: Fundamentals Applications" 2012, 1st edition, Wiley-Blackwell, New Jersey. M. Campbell, "Sensor Systems for Environmental Monitoring: 5. Environmental Monitoring", 2011, 1st Edition, Springer, New York. Mode of Evaluation: CAT, Digital Assignments, Quiz, Online course, Paper publication, Projects, Hackathon/Makeathon and FAT **List of Challenging Experiments: (Indicative)** Develop a suitable electrochemical cell which can distinguish normal and 6 hours contaminated water samples. Cyclic voltammetry technique can be used as the detection method. Develop the electronic circuitry and display to indicate the type of water. Interdigitated Electrodes (IDT) are required for effective chemical sensing 2 6 hours application. Using copper as the electrode material, develop IDT finger type electrodes using suitable deposition method. 3 After analysing the advantages and drawbacks of various methods used for 6 hours depositing the oxide materials on planar rigid substrates, deposit zirconium oxide on the IDT electrodes fabricated on alumina substrate using the suitable deposition method. Among the various types of conductometric sensors, identify a suitable 4 6 hours sensor which can measure the humidity and develop asensor system which

can measure the relative humidity in the range of 40 to 60 percent.

| 5 | Develop a potentiostat circuit for a chemoresistive sensor which can be used for gas sensing application. The nominal resistance of the sensor will be 100 to 130 ohms and the expected change in resistance will +/-5%. Develop the electronic circuit which can convert the change in resistance in to a voltage signal/current signal. | | | | | | |
|---|---|---------|--|--|--|--|--|
| | ory Hours | 30hours | | | | | |
| Mode of Evaluation: Continuous Assessment and FAT | | | | | | | |
| Recom | | | | | | | |
| Approv | Approved by Academic Council No. 55 Date 13-06-2019 | | | | | | |

| Course code | Course Title | L | T | P | J | C |
|--------------|--|------------------|---|------|-----|---|
| ECE5067 | ECE5067 Cloud and Fog Computing | | | | | |
| Prerequisite | ECE5061- IoT Fundamentals and Architecture | Syllabus Version | | | ion | |
| | | | | 1.00 |) | |

Objectives:

The course is aimed to

- 1. Introduce cloud computing and enabling technologies
- 2. Explore the need for fog and edge computation
- 3. Impart the knowledge to log the sensor data and to perform further data analytics

Expected Outcome:

At the end of the course student will be able to

- 1. Deploy their data in the cloud for simple applications
- 2. Apply the analytics in cloud to extract information
- 3. Appreciate and deploy fog data processing layers
- 4. Integrate sensor data to cloud through fog computation layers
- 5. Understand and implement edge computation
- 6. Develop edge analytics using python and tensor flow
- 7. Perform data pushing and processing in commercial clouds.

| Module 1 | Cloud technol | Computing ogies | basics | and | enabling | 5 hours |
|----------|------------------|-----------------|--------|-----|----------|---------|

Basics of cloud computing-Need for clouds- concepts and models: Roles and boundaries – Cloud characteristics – Cloud delivery models – Cloud deployment models. Broadband Networks and Internet Architecture – Data Center Technology – Virtualization Technology.

Module 2 | Cloud Virtualisation 5 hours

Server oriented – Virtual Machines (IaaS), Modern Serverless Configurations- Functions/ (PaaS) Lambda functions – App, Biz function, logics, data ingestion (elasticity, scalability – on demand)

DB services, Analytics services (SaaS).

| Module 3 | Cloud Application Development in Python | 4 hours |
|-------------------------|--|------------------------------------|
| Python for MapReduce | Cloud: Amazon Web Services – Google Cloud | - Windows Azure. Python for |
| Module 4 | Federated Cloud Service Management and IoT | 3 hours |
| | vice management (federated) –Cloud Life Cycl s -Self organizing cloud architectures | e-service and management-Cloud |
| Module 5 | Fog computing | 4 hours |
| _ | ocess integration – Big data interfaces – Wireless e Harmonization Between Cloud Radio Access I | _ |
| Module 6 | Fog and edge computing | 4 hours |
| diagnostics, | edge computation-Edge computing architectu SW update, Geo distributed computing-concept of a width networks/ Security/ protcols), WAN vs Low b | cloud orchestration, Edge Networks |
| Module 7 | Overview of Edge Data Analytics tools | 3 hours |
| Python adva | ance libraries(Pandas, Scikit Learn), Tensor flow an | d Yolo |
| Module 8 | Contemporary Issues | 2 hours |
| | Total Lecture: | 30 hours |
| Text Books | | Jo nours |
| Techn | as Erl, Zaigham Mahmood, and Ricardo Puttin ology & Architecture", Arcitura Education, 2013. | |
| 3. Ovidio | eep Bahga, Vijay Madisetti, "Cloud Computing: A U Vermesan, Peter Friess, "Internet of Things – I t Deployment", River Publishers, 2014. | |

| 4. | Michael Missbach, Thorsten Staerk, Camer | ron Gardiner, | , Josł | nua McC | loud, Robert Madl, | | | |
|------|--|---------------|--------|------------|-----------------------------------|--|--|--|
| | Mark Tempes, George Anderson, "SAP on C | loud", Spring | ger, 2 | 016. | | | | |
| | | | | | | | | |
| 5 | John Mutumba Bilay, Peter Gutsche, Mandy | | | | | | | |
| | Platform Integration: The Comprehensive Gu | uide", Rheinw | verg p | ublishin | g, 2 nd edition, 2019, | | | |
| Refe | erence Books: | | | | | | | |
| 1. | Honbo Zhou, "The Internet of Things in the O | Cloud: A Mid | ldlew | are Persp | pective", CRC Press, | | | |
| | 2012. | | | | | | | |
| 2. | SC. Hung et al.: Architecture Harmonization | n Between Cl | loud | RANs an | d Fog Networks, | | | |
| | IEEE Access: The Journal for rapid open acc | ess publishin | g, Vo | 1.3, pp: 3 | 3019 - 3034, 2015. | | | |
| Lab | Tasks (30 Hours) | | | | SLOs: 5,14 | | | |
| Clou | d Platforms: Microsoft Azure/IBM Bluemi | X | | | | | | |
| Lan | guage: Python | | | | | | | |
| Lan | guage. I ython | | | | | | | |
| 1 | . Pushing documents | | | | | | | |
| 2 | 2. Pushing Images and Processing | | | | | | | |
| 3 | 6. Mini Weather Station | | | | | | | |
| 4 | . Image analytics at cloud | | | | | | | |
| 5 | 5. Python Scikit learn | | | | | | | |
| | Tensor flow | | | | | | | |
| 7 | . Live video | | | | | | | |
| Reco | ommended by Board of Studies | 13-09-2019 | | | | | | |
| ĺ | | | | | | | | |

No. 56

Date

24-09-2019

Approved by Academic Council

| Course code | Course Title | L | T | P | J | C | | |
|--|------------------------|---|---|-----|---------|---|--|--|
| ECE5068 | IoT Security and Trust | 2 | 0 | 0 | 4 | 3 | | |
| Pre-Requisite: ECE6001-Wireless Sensor Networks and IoT | | | | | Version | | | |
| | | | | 1.0 | | | | |
| Objectives | | | | | | | | |

Objectives:

To impart the knowledge and technical skills in designing secured and trustable IoT systems.

Expected Outcome:

At the end of the course students will be able to

- 1. Design and implement cryptography algorithms using C programs
- 2. Solve network security problems in various networks
- 3. Build security systems using elementary blocks
- 4. Build Trustable cloud based IoT systems
- 5. Solve IoT security problems using light weight cryptography
- 6. Appreciate the need for cyber security laws and methods.

| Module 1 | Fundamentals | of | encryption | for | cyber | 5 hours |
|----------|--------------|----|------------|-----|-------|---------|
| | security. | | | | | |

Cryptography – Need and the Mathematical basics- History of cryptography, symmetric ciphers, block ciphers, DES – AES. Public-key cryptography: RSA, Diffie-Hellman Algorithm, Elliptic Curve Cryptosystems, Algebraic structure, Triple Data Encryption Algorithm (TDEA) Block cipher,

Module 2 IoT security framework

5 hours

IIOT security frame work, Security in hardware, Bootprocess, OS & Kernel, application, run time environment and containers. Need and methods of Edge Security, Network Security: Internet, Intranet, LAN, Wireless Networks, Wireless cellular networks, Cellular Networks and VOIP.

Module 3 Elementary blocks of IoT Security & Models for Identity Management 4 Hours

Vulnerability of IoT and elementary blocks of IoT Security, Threat modeling – Key elements. Identity management Models and Identity management in IoT, Approaches using User-centric, Device-centric and Hybrid.

Module 4 Identity Management and Trust Establishment 4 Hours

Trust management lifecycle, Identity and Trust, Web of trust models. Establishment: Cryptosystems – Mutual establishment phases – Comparison on security analysis. Identity management framework.

Module 5 Access Control in IoT and light weight cryptography 3 Hours

Capability-based access control schemes, Concepts, identity-based and identity-driven, Light weight cryptography, need and methods, IoT use cases

| Module 6 | Security | and | Digital | Identity | in | Cloud | 4 Hours |
|----------|----------|-----|---------|----------|----|-------|---------|
| | Computin | g | | | | | |

Cloud security, Digital identity management in cloud, Classical solutions, alternative solutions, Management of privacy and personal data in Cloud.

| Mo | dule 7 | Cyber Crimes, Hackers and Fores | nsics | | 3 Hours |
|-----|----------|---|------------------|-----------------|----------------------|
| Cył | er Crim | es and Laws – Hackers – Dealing with | h the rise tide | of Cyber Crime | es – Cyber Forensics |
| | | Response – Network Forensics. | | | |
| | | | | | |
| Mo | dule:8 | Contemporary Issues | | | 2 Hours |
| | | | | | |
| | | To | tal Lecture: | 30 Hours | |
| Tex | t Books | : | | | |
| 1. | John R | Vacca, "Computer and Information S | Security Hand | book", Elsevier | , 2013. |
| | Pariksh | it Narendra Mahalle, Poonam N. | Railkar, "Ide | ntity Managem | nent for Internet of |
| | | ', River Publishers, 2015. | | | |
| 2. | | n Stallings, "Cryptography and Ne | etwork securi | ty: Principles | and Practice", 5th |
| | | , 2014, Pearson Education, India. | | | |
| 3. | | ne Laurent, Samia Bouzefrane, "Digital | | | evier, 2015. |
| 4. | | Migga Kizza, "Computer Network Se | curity", Sprin | ger, 2005. | |
| Ref | erence l | | | | |
| 1. | | f Paar and Jan Pelzl, "Understanding | g Cryptograpl | hy – A Textboo | ok for Students and |
| | | oners", Springer, 2014. | | | |
| 2. | | z A.Forouzan : Cryptography & Ne | twork Securi | ty – The McG | raw Hill Company, |
| | 2007. | | | | |
| 3. | Charlie | , | | r, Network | |
| | | unication in a public World", PTR Pre | | | 002. |
| 4. | | r Gilchrist, "IoT security Issues", Ore | illy publication | ons, 2017. | 1 |
| Ty | | t of Projects(not limited to) | | | SLO: 5,6,14 |
| | | t weight cryptography | | | |
| | | rid block ciphers. | | | |
| | | yption using applets | | | |
| | | tal signatures | | | |
| | | ew of Trust in IoT transactions. | | | |
| | | ot analysis | | | |
| | | id security | | | |
| | | t management in clouds | | | |
| | | ded by Board of Studies | 13-09-2019 | | |
| Ap | proved l | oy Academic Council | No. 56 | Date | 24-09-2019 |

| Course code | Course Title | L | T | P | J | C |
|--------------------|--|-----------------|-------|-------|------|---|
| ECE5069 | IoT Applications and Web development | 2 | 0 | 0 | 4 | 3 |
| Pre-requisite | ECE5061-IoT fundamentals and Architecture | Syllabus versio | | ion | | |
| v. 1.00 | | | | | 00 | |
| Course Objectiv | es: | | | | | |
| 1. To acquire spe | cific scripting knowledge to develop interactive applications. | | | | | |
| 2. To understand | the basics of android application development. | | | | | |
| 3. To apply the p | rogramming skills in developing application pertaining to Indu | ıstria | al, m | nedio | cal, | |
| agricultural, etc. | | | | | | |

Expected Course Outcome: Students will be able to

- 1. Design dynamic web forms to acquire and process user & sensor data
- 2. Interactive forms using Java Script with a focus on internet of things
- 3. Implement mobile application using android SDK
- 4. Solve the need for smart systems in a distributed environment
- 5. Understand the IoT architecture and building blocks for various domains
- 6. Devise multidisciplinary case to case modelling and execute wide range of application
- 5. Having design thinking capability
- 7. Having computational thinking (Ability to translate vast data in to abstract concepts and to understand database reasoning)
- **20.** Having a good digital footprint

Module:1 | Markup Language

3 hours

Introduction to Markup language, HTML document structure, HTML forms, Style (CSS), Multiple CSS stylesheets, DHTML, Tools for image creation and manipulation, User experience design, IoT development using charts

Module:2 | Scripting Language

4 hours

Introduction to JavaScript, Functions, DOM, Forms, and Event Handlers, Object Handlers, Input validation, J2ME, application design using J2ME, IoT development using Real time rules, platforms, alerts

Module:3 | Android Programing Framework

5 hours

Mobile app development: Android Development environment, Simple UI Layouts and layout properties, GUI objects, Event Driven Programming, opening and closing a Database

Module:4 | Industrial Internet Application

4 hours

IIoT Fundamentals and Components, Industrial Manufacturing, Monitoring, Control, Optimization and Autonomy, Introduction to Hadoop and big data analytics

Module:5 Applications in agriculture

3 hours

Smart Farming: Weather monitoring, Precision farming, Smart Greenhouse, Drones for pesticides.

Module:6 | Applications in IoT enabled Smart Cities

4 hours

Energy Consumption Monitoring, Smart Energy Meters, Home automation, Smart Grid and Solar Energy Harvesting, Intelligent Parking, Data lake services scenarios.

Module:7 | Healthcare applications

5 hours

architecture. Use Cases: Wearable devices for Remote monitoring of Physiological parameter, ECG, EEG, Diabetes and Blood Pressure. **Contemporary issues:** Module:8 2 hours Total Lecture hours: 30 hours Text Book(s) John Dean, Web Programming with HTML5, CSS and JavaScript, 2018, Jones and Bartlett Publishers Inc., ISBN-10: 9781284091793 DiMarzio J. F., Beginning Android Programming with Android Studio, 2016, 4th ed., Wiley, ISBN-10: 9788126565580 **Reference Books** Fadi Al-Turjman, Intelligence in IoT- enabled Smart Cities, 2019, 1st edition, CRC Press, ISBN-10: 1138316849 Giacomo Veneri, and Antonio Capasso, Hands-on Industrial Internet of Things: Create a powerful industrial IoT infrastructure using Industry 4.0, 2018, Packt Publishing. Subhas Chandra Mukhopadhyay, Smart Sensing Technology for Agriculture and Environmental Monitoring, 2012, Springer, ISBN-10: 3642276377 Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar **List of Challenging Experiments (Indicative)** Design and development of wireless video surveillance robot 15 hours Design and implementation of wearable glove to enable sign to speech conversation IoT based home automation with security features Smart farming: IoT based system for smart agriculture IoT application to improvise industrial automation Smart Energy meters to minimize power consumptions with a statistical Bringing intelligence body area network – Smart Healthcare systems 7. Mode of assessment: Mid CAT, FAT Recommended by Board of Studies 13-09-2019 Approved by Academic Council No. 56 Date 24-09-2019

Architecture of IoT for Healthcare, Multiple views coalescence, SBC-ADL to construct the system

| Course code | code Course title | | | | J | C |
|--------------|--|---|------|------|------|----|
| ECE6003 | MICROSYSTEMS AND HYBRID TECHNOLOGY | 2 | 0 | 2 | 0 | 3 |
| Prerequisite | Prerequisite ECE5001 Principles of Sensors | | llab | us v | ersi | on |
| | | | | 1.1 | | |

- 1. To introduce the fundamental concepts of MEMS based sensors and actuators.
- 2. To acquaint the students with various materials and material properties for Microsystem designing.
- 3. To provide comprehensive understanding of various micromachining techniques and expose the students to design, simulation and analysis software.
- 4. Enhancing the basics of thick film and hybrid technologies for sensor development.

Expected Course Outcome:

- 1. Identify and understand the fundamental concepts and background of MEMS and Microsystems
- 2. Familiar with the basics of various sensors and actuators.
- 3. The students were acquainted with various materials for Microsystem designing.
- 4. Determine and compare the scaling effects in miniaturizing devices.
- 5. Recognize and interpret various micromachining techniques and design, analysis and applications of various MEMS devices micromachining tools and techniques
- 6. Acquainted with thick film and hybrid technologies for sensor development.
- 7. Incorporate simulation and micro-fabrication knowledge for developing various MEMS devices.

Module:1 Introduction to MEMS and Microsystems

3 hours

MEMS and Microsystems, Miniaturization, Benefits of Microsystems, Typical MEMS and Microsystems products, Evolution of Micro fabrication and Applications.

Module:2 Introduction to Sensors and Actuators

3 hours

Various domains and classification of transducers: electrostatic, piezoelectric, thermal. Sensing principles: electrostatic, resistive, chemical etc. SAW devices. Micro actuators, Design of Micro accelerometers, Engineering Science for Microsystem design and fabrication.

Module:3 | Materials for Microsystems

4 hours

Silicon, Silicon compounds, Silicon Piezo resistors, Gallium Arsenide, Quartz, Piezoelectric materials, Polymers, Shape Memory Alloys, ferroelectric and rheological materials.

Module:4 | Scaling Effects in Microsystems

4 hours

Introduction to Scaling, Scaling laws, Scaling in Geometry, Scaling in Rigid body dynamics, Scaling in Electromagnetic, Electrostatic, magnetic, optical and Thermal domains. Scaling in Fluid mechanics.

Module:5 | Micromachining Technologies

4 hours

Overview of silicon processes techniques, Photolithography, Ion Implantation, Diffusion, Chemical Vapor Deposition, Physical vapor Deposition, Epitaxy, Etching, Bulk micromachining, Surface Micromachining, LIGA and other techniques.

Module:6 | **MEMS** and micro systems applications

4 hours

Details of application in actual systems, introduction to RF- MEMS, MOEMS, future of smart structures and MEMS leading to NEMS. Packaging, test and calibration of MEMS.

| Module:7 Hybrid Technology 2 ho |
|--|
| Thick-film and hybrid technology in sensor production. Basic materials, compone manufacturing Screen manufacturing, Screen printing, Parameters, Comparison: thick- vs. the film technology Structure dimensions, Assembly and packaging Surface mount technology (SN Active and passive devices (SMD), Connection technologies, Packaging. Module:8 Contemporary issues: 2 ho |
| manufacturing Screen manufacturing, Screen printing, Parameters, Comparison: thick- vs. the film technology Structure dimensions, Assembly and packaging Surface mount technology (SM Active and passive devices (SMD), Connection technologies, Packaging. Module:8 Contemporary issues: 2 ho |
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| Total Lecture hours: 30 hours Text Book(s) 1. G.K.Ananthasuresh, K J Vinoy, S Gopalakrishnan, KN Bhatt, V K Aatre," Micro and sn systems", 2012, 1 st ed., Wiley, New York. 2. Tai-Ran Hsu, "MEMS & Microsystem, Design and Manufacture", 2017, 1 st ed., McGraw India, New Delhi. Reference Books 1. Mahalick NP, "MEMS", 2017, 1 st ed., Tata McGraw Hill, New Delhi 2. Wolfgang Menz, Jürgen Mohr, Oliver Paul, "Microsystem Technology", 2011, 2 nd ed., Wi New York. 3. Banks H.T. Smith R.C. and Wang Y.Smart, 'Material Structures – Modeling, Estimation Control', 2011, 1 st ed., John Wiley & Sons, NewYork. 4. Massood Tabib – Arar, 'Microactuators – Electrical, Magnetic Thermal, Optical, Mechanical |
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| Control', 2011, 1 st ed., John Wiley & Sons, NewYork. 4 Massood Tabib – Arar, 'Microactuators – Electrical, Magnetic Thermal, Optical, Mechanic |
| 4 Massood Tabib - Arar, 'Microactuators - Electrical, Magnetic Thermal, Optical, Mechanic |
| |
| Chemical and Smart structures, 2014, 1st ad Kluwar Academic publishers, New York |
| |
| Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar |
| List of Challenging Experiments (Indicative) |
| 1. Design and Simulation of MEMS Capacitance based Accelerometer: 15 hours |
| |
| In this topic, you need to design a capacitive accelerometer that has a full- |
| scale Measurement range of \pm 10 g. The accelerometer may be designed |
| using a closed loop or an open-loop. You need to have reasonable over range |
| protection in your device. |
| Specification: |
| Measurement range: ± 10g |
| Output capacitance: at least tens of fF level |
| Device simulation results (must take into account parasitic capacitance of |
| your design): |
| (a) Static analyses: |
| Gap vs. acceleration |
| Capacitance (or differential capacitance) vs. acceleration |
| (identify sensitivity [F/g]) |
| (b) Dynamic analyses: |
| Your device's response on vibration. |
| 2. Piezoresistive barometric pressure sensor: 15 hours |
| In this topic, you need to design a piezoresistive pressure sensor that has the |
| measurement range of 0 - 1.1 bar. You need to have a reasonable over range |
| protection in your device. |

| | Specification: | | | | | |
|-----|---|------------|-----------|---------------|----------|--|
| | Measurement range: 0 -1.1 bar. | | | | | |
| | Device simulation results: | | | | | |
| | (i) Strain in the piezoresistor vs. | pressure | | | | |
| | (ii) Resistance vs. pressure | | | | | |
| | | | | | | |
| | Circuit integration issues: | | | | | |
| | Temperature compensation circ | uit design | | | | |
| | | | Total Lab | oratory Hours | 30 hours | |
| Mo | Mode of assessment: Continuous Assessment and FAT | | | | | |
| Rec | commended by Board of Studies | 28.01.2017 | | | | |
| App | proved by Academic Council | No. 47 | Date | 05-10-2017 | | |

| Course code | Course title | L | T | P | J | C |
|---------------|-------------------------------|----|------|------|------|-----|
| ECE6004 | RF AND MICROWAVE SENSORS | 3 | 0 | 0 | 0 | 3 |
| Prerequisite: | ECE5001-Principles of Sensors | Sy | llab | us v | ersi | ion |
| | | | | 1.0 | | |

- 1. To introduce the students with different RF and Microwave sensors,
- 2. To familiarize antenna design with a good understanding of their parameters and applications.
- 3. To introduce comprehensive knowledge of wearable antenna.
- 4. To explore and understand basics of RFID technology.

Expected Course Outcome:

- 1. Select a proper antenna design to be used in the RF spectral region
- 2. Model specific radiation pattern and evaluate them in different domains
- 3. Correlate the principle behind different radar systems and determine various applications based on the radar systems.
- 4. Apply the basic knowledge in the measurement of RF radiation.
- 5. Gain knowledge about the RFID technology.

Module:1 | RF Sensors

6 hours

Microwave Antenna-Introduction, types of Antenna, fundamental parameters of antennas, radiation mechanism, Fresnel and Fraunhofer regions. Antenna for communication and Antenna for sensing, radiometer and radar

Module:2 | Antenna for personal area communication.

5 hours

Concepts of Printed Antennas, Broadband Microstrip Patch Antennas, Antennas for Wearable Devices, Design Requirements, Modeling and Characterization of Wearable Antennas, WBAN Radio Channel Characterization and Effect of Wearable Antennas, Domains of Operation, Sources on the Human Body, Compact Wearable Antenna for different applications.

Module:3 Radar

5 hours

Introduction to RADAR, RADAR range equation, MTI and pulse Doppler RADAR, Tracking RADAR, SAR pulse RADAR, CW RADAR

Module:4 | **Applications of Radar**

6 hours

Automotive, remote sensing, agriculture, medicine, detection of buried objects, NDT, defense factors affecting the performance of RADAR, RADAR transmitters, Receivers,

Module:5 Radiometers

6 hours

Radiative transfer theory, SMMR, Types of radiometers - and Bolometers, Applications in automotive, agriculture, medicine, weather forecasting

Module:6 | **Microwave power Sensors**

6 hours

Diode Sensors: Diode detector principles, dynamic range average power sensors, signal waveform effects on the measurement uncertainty of diode sensors. Thermocouple Sensors: Principles of Thermocouple sensor, power meters for thermocouple sensors.

| Mo | dule:7 | RFID Sensors | | | | 8 hours |
|------|-----------|----------------------------|---------------------------------|---------|----------------|-----------------------------------|
| Intr | roduction | , Components of RFID sys | tems, hardware an | d soft | ware compone | ents, RFID standards, |
| RF | ID applic | cations. | | | | |
| | | | | | | |
| Mo | dule:8 | Contemporary issues: | | | | 2 hours |
| | | | | | | |
| | | | | | | |
| | | | Total Lecture ho | urs: | 45 hours | |
| | | | | | | |
| Tex | xt Book(| s) | | ı | | |
| 1. | Finken | zeuer Klaus, "RFID Handbo | ook", 2011, 3 rd edi | tion, J | ohn Wiley and | d Sons, New Jersey. |
| 2. | Consta | ntine A. Balanis, "Antenn | a Theory Analysi | s and | Design", 20 | 16, 4 th edition, John |
| | Wiley a | and Sons, New Jersey. | | | | |
| Ref | ference l | Books | | | | |
| 1. | B. Hof | fman - Wellenhof, H.Lichte | negger and J.Colli | ns, "G | PS: Theory at | nd Practice ", 5 th |
| | edition, | Springer, New York, 2012 | | | | |
| 2 | Lillesa | nd & Kiefer, "Remote Se | nsing and Image | Interp | oretation", 20 | 11, 6 th edition, John |
| | | and Sons, New Jersey. | | - | | |
| Mo | de of Ev | aluation: CAT / Assignmen | nt / Quiz / FAT / Pr | oject / | Seminar / | |
| Rec | commend | led by Board of Studies | 28.01.2017 | | | |
| - | | y Academic Council | No. 47 | Date | 05-10-20 |)17 |
| | | * | | | | |

| Course code | Course title | L | T | P | J | C |
|---------------|-------------------------------|----|------|------|------|----|
| ECE6007 | BIOMEDICAL SENSORS | 2 | 0 | 2 | 0 | 3 |
| Prerequisite: | ECE5001-Principles of Sensors | Sy | llab | us v | ersi | on |
| | | | | 1.1 | | |

- 1. Introduce the students to different types of electrodes used in bio potential recording
- 2. To facilitate the students in recognizing electrode configuration and issues related with the electrode relative motions.
- 3. To expose the students to perceive the need for bio amplifiers and their characteristics needed to be design for various bandwidth and frequency response.
- 4. Review the cardiac, respiratory and muscular physiological systems. Study the designs of several instruments used to acquire signals from living systems.
- 5. To proclaim the conception in detection of chemical and biomolecules.
- 6. Students will be expedient in applying specific radiology methods in diagnostics and analysis.
- 7. The students also understand the theory behind the sound and tissue interaction, and able to apply in therapeutic application.

Expected Course Outcome:

- 1. Realize the need for reusable electrodes and understands the method of implementation.
- 2. Will be familiar with electrode placements for various biopotential recording as per the voltage range.
- 3. Capable of understanding the design principles of bio-amplifiers and drawback related with noises.
- 4. Gain knowledge for implementing different types of physiological parameter measurement using appropriate sensors.
- 5. Able to discuss, develop and apply site specific chemical sensors design and imaging techniques for typical issues
 - a. To disseminate the design knowledge in analyzing in-vivo ailments

Module:1 | **Biopotential Electrodes**

3 hours

Origin of bio potential and its propagation. Electrode-electrolyte interface, electrode-skin interface, half-cell potential, impedance, polarization effects of electrode – nonpolarizable electrodes. Types of electrodes - surface, needle and micro electrodes and their equivalent circuits. Recording problems - measurement with two electrodes.

Module:2 | EEG, EMG & ECG

3 hours

Bio signal characteristics – frequency and amplitude ranges. ECG – Einthoven's triangle, standard 12 lead system. EEG – 10-20 electrode system, unipolar, bipolar and average mode. EMG–unipolar and bipolar mode. EEG- procedure, signal artefacts, signal analysis, evoked potential, EMG- procedure and signal analysis, Nerve conduction study

Module:3 | **Bio Amplifiers**

3 hours

Need for bio-amplifier - single ended bio-amplifier, differential bio-amplifier - right leg driven ECG amplifier. Band pass filtering, isolation amplifiers - transformer and optical isolation -

| isolated I | OC amplifier and AC carrier amplifier. Chopper ampl | lifier. Power line | interference |
|-------------|--|--------------------|----------------------|
| | 1 11 1 | | |
| Module:4 | Physical Sensors in Biomedicine | | 8 hours |
| Temperati | re measurement: core temperature,-surface temp | perature- invasi | ve. Blood flow |
| measurem | ent: skin blood- hot film anemometer- Doppler son | nography- electr | omagnetic sensor - |
| blood pre | ssure measurement: noninvasive- hemodynamic | invasive. Spiror | netry- sensors for |
| pressure p | ulses and movement- ocular pressure sensor- acous | tic sensors in he | earing aid, in blood |
| flow mea | surement, sensors for bio-magnetism, tactile sensor | ors for artificial | limbs, sensors in |
| ophthalmo | scopy, artificial retina. | | |
| | | T | |
| Module:5 | | | 3 hours |
| D11 | Biomedicine | | C1 |
| _ | and pH sensor, electrochemical sensor, transcuta | aneous, optical | fiber sensor, mass |
| spectrome | ter, optical oximetry, pulseoximetry, earoximetry. | | |
| Module:6 | Detectors in Radiology | | 4 hours |
| X ray ima | ging with sensors, detectors in nuclear radiology, n | lagnetic field se | |
| | esonance imaging. | lagnetic field se | nisors for imaging, |
| magnetic | obonance magnig. | | |
| Module:7 | Sound in Medicine | | 4 hours |
| Interaction | of Ultrasound with matter; Cavitations, Reflection, | Transmission- S | Scanning systems – |
| Artefacts- | Ultrasound- Doppler-Double Doppler shift-Clinical | Applications | |
| | | | |
| Module:8 | Contemporary issues: | | 2 hours |
| | | | |
| | | 20.1 | |
| | Total Lecture hours: | 30 hours | |
| T4 D1 | (-) | | |
| 1. J. G. | Webster, J. G. Webster, "Medical Instrumentation; A | nnlication and D | osion" John Wilov |
| | ns, Inc., New York, 4 th Edition, 2015 | ppiication and D | esign , John Whey |
| Reference | | | |
| | lpur R.S, "Handbook of Biomedical Instrumentation | n". Tata McGra | w-Hill, New Delhi. |
| | ition ,2014. | 11 , 1 1/12 01 | , |
| | Enderle, Joseph Bronzino, "Introduction to Biomed | ical Engineering | ", Academic Press, |
| | ition, 2011. | | |
| 3 Myer | Kutz, "Biomedical Engineering and Design H | landbook, Volu | me 1: Volume I: |
| | edical Engineering Fundamentals", McGraw Hill Pul | | Edition 2009. |
| | valuation: CAT / Assignment / Quiz / FAT / Project | / Seminar | |
| | allenging Experiments (Indicative) | , | 7.1 |
| | oximetry can be a useful aid in decision-making, e | | |
| | tion fluctuates, due to changing activities and health | | - |
| | uit to determine oxygen range, and record each m | | |
| | ty log. A SpO2 of greater than 95% is generally | | |
| | al. If SpO2 of 92% or less (at sea level) indicate the | _ | |
| | . Use two led source and two detectors to measure | e the saturation | 01 |
| | n in the test subject. verall aim, of this experiment, is to build and test | an ECC amplifi | ier 6 hours |
| | and its noise interference problem. The signals sh | | |
| and s | day to holse interference problem. The signals sir | oura de dispiaye | ла, [|

| 3 | stored and processed. Modify the DC offset cancellation and driven-voltage due to interference and states. Also, include a low-pass filter that Impedance plethysmography is a volumes in the body, based on the body surface. Determine the charvolume which in turn changes the the volume conductor. Measure as system. | right leg circuit to safeguard the patalimits the bandwid method of determeasurement of onge in the conduct distribution of the safeguard of the conduct distribution of the safeguard conduction of t | o reduce c ient from dth of the a rmining ch electric imp activity du he introduce | ommon-mode high voltage. amplifier. nanging tissue pedance at the e to the flow ced current in | 6 hours | | |
|-----|--|--|--|--|---------|--|--|
| 4 | Strain gauge plethysmography hemodynamic changes. Design a which the strain gauges should be gauge is the same as the circumfer. This allows the plethysmograph change. The size for limb strain circumference of the limb so they should be 0.5 cm less than the volume change using a DAQ syste. | designed so that rence of the limb to relate resistate gauges should by will stretch slight circumference of | ased pleth the active or digit be nce chang the 1-3 cm htly. Digits | ysmograph in portion of the ing measured. ge to volume less that the s strain gauge | 6 hours | | |
| 5. | | | | | | | |
| | Total Laboratory Hours | | | | | | |
| Mo | de of assessment: Continuous Asses | ssment and FAT | • | | | | |
| | ommended by Board of Studies | 28.01.2017 | | T | | | |
| App | proved by Academic Council | No. 47 | Date | 05-10-2017 | | | |

| Course Code | Course Title | L | T | P | J | C |
|--------------------|--|------------------|---|-----|---|---|
| ECE6087 | Multi-disciplinary Product Development | 3 | 0 | 0 | 4 | 4 |
| Prerequisite: | Nil | Syllabus Version | | | | |
| | | | | 1.0 | | |

- 1. To develop the students for integrative thinking on good engineering practices.
- 2. To emphasis the students from shifting their mindset from theoretical to practical multidisciplinary skills through installing the know-how of actual practice in industry field.

Expected Outcomes:

The student will be able

- 1. To demonstrate an understanding of the overview of all the product development processes and knowledge of concept generation and selection tools
- 2. To value the voice of the customer in getting the feedback
- 3. To demonstrate an understanding of quality in a product or service through tools.
- 4. To improve the design of the product in accordance with the quality standards
- 5. To apply various strategies of designing experiments, methods to uphold the status of six sigma and improve the reliability of a product.
- 6. Strive towards efficient manufacturing process by systematic resource procurement
- 7. Analyze and demonstrate knowledge in product development

Module:1 | Customer Value and Market Segmentation | 6 hours

The way to measure value by what a customer is willing to pay. It is used as critical input for product function requirement development. No product can satisfy all the customers. Market Segmentation shows the methodology to target a specific customer group for product positioning.

Module:2 Voice of customer 6 hours

Voice of customer: A disciplined approach to directly collecting feedback and input from customers. Used throughout the Engineering and Marketing process.

Module:3 | Quality Function deployment 6 hours

Critical to Quality and Quality function Deployment: Specify and quantify customer needs. Flow down those customer needs in each step of product development.

Module:4 Design of Six Sigma 6 hours

Integrate statistics into quality continuous improvement operation model. Design for Six Sigma used throughout the product development process in order to improve the correction of the first design delivery.

Module:5 Design Principles 6 hours

Sample design Principles: As little design as possible to satisfy customer expectations and eliminating any unnecessary complexity helps maximize business benefit.



| Mo | dule:6 | Design of Manufacturing | - | | | 6 hours |
|-------|----------|--|----------------------|----------|---------------|----------------------------------|
| | | Manufacturing: Consider product mar | yyfootyrobility | durir | a docior | |
| | _ | ciently increases the organization com | • | | ig ucsigi | i pilasc. Manufacture |
| pro | duct em | cientry increases the organization con | ipentive powe | er. | | |
| N/I - | 117 | C44 | | | | 7 1 |
| | dule:7 | Strategic sourcing and e-sourcing | .1 | <u>,</u> | <u> </u> | 7 hours |
| | - | ourcing and Standardized Parts: Lever | - | | | |
| • | _ | es to success. Parts standardization in | - | | _ | • |
| | | ssue. e-sourcing: Leverage web-base | d applications | to de | liver sav | ings and productivity |
| gair | ns while | conducting the strategic sourcing. | | | | |
| | | | | | | |
| Mo | dule:8 | Contemporary Issues | | | | 2 hours |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| | | To | otal Lecture: | 30 | hours | |
| Tex | t Books | : | | | | |
| 1. | | lman, Shercliff, Van Eyben, "Manufa | cturing and D | esign | . Elsevie | r. 1 st edition, 2014 |
| | _ | | | | | |
| 2. | | einstein, "Handbook of Market Segr | | | | |
| | Techno | ology Firms, Third Edition (Haworth | Series in Seg | mente | ed, Targe | eted, and Customized |
| | |), 3 rd ed. Routledge, Taylor and Franc | | | | |
| 3. | | el Lamoureux, "The e-Sourcing Han | | odern | Guide to | o Supply and Spend |
| | Manag | ement Success, Lasta publishing, 2008 | 8 | | | |
| | | | | | - | |
| Mo | de of Ev | raluation:Continuous Assessment and | FAT | | | |
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| Rec | commen | ded by Board of Studies | 26-04-2019 | | | |
| | | ded by Board of Studies y Academic Council | 26-04-2019 No. 55 | | 13 | 3-06-2019 |



| Course Code | Course Title | L | T | P | J | C |
|--------------------|--------------------------------|----|------|------|-------------------|-----|
| ECE6088 | DEEP LEARNING - AN APPROACH TO | 3 | 0 | 0 | 0 | 3 |
| | ARTIFICIAL INTELLIGENCE | | | | | |
| Prerequisite: | Nil | Sy | llab | us V | ⁷ ersi | ion |
| | | | | | | 1.0 |
| Course Objectives | | | | | | |

- 1. To introduce the fundamental theory and concepts of machine learning and artificial intelligence
- 2. To provide a comprehensive foundation to artificial neural networks, neuro-modeling, and their applications to pattern recognition.
- 3. To explore the learning paradigms of supervised and unsupervised shallow/deep neural networks.
- 4. To provide exposure to the recent advances in the field of and facilitate in depth discussions on chosen topic
- 5. To impart adequate knowledge on deep learning frameworks and their applications to solving engineering problems

Course Outcomes:

- 1. Gain knowledge about basic concepts of machine learning algorithms and identify machine learning techniques suitable for the given problem.
- 2. Understand the differences between shallow neural networks and deep neural networks for supervised and unsupervised learning.
- 3. Develop and train neural networks for classification, regression and clustering.
- 4. Understand the foundations of neural networks, how to build neural networks and learn how to lead successful machine learning projects
- 5. Identify the deep feed forward, convolution and recurrent neural networks which are more appropriate for various types of learning tasks in various domains
- 6. Implement deep learning algorithm and solve real world problems

Module:1 Foundations of Machine Learning-I

5 hours

Supervised and unsupervised learning, parametric vs non-parametric models, parametric models for classification and regression- Linear Regression, Logistic Regression, Naïve Bayes classifier, simple non-parametric classifier-K-nearest neighbour, support vector machines.

Module:2 | Foundations of Machine Learning-II

5 hours

Clustering- distance based- K-means, density based, association rule mining, validation techniquescross validations, feature selection and dimensionality reduction, principal component analysis-Eigen values, Eigen vectors, Orthogonality- challenges motivating deep learning

Module:3 | Neural Networks for Classification and Regression

6 hours

ANN as a technique for regression and classification, structure of an artificial neuron, activation functions- linear activation, sigmoid andsoftmax. Feedforward neural networks- shallow model-single layer perceptron, multi-layer perceptron as complex decision classifier- learning XOR-Gradient based learning, Backpropagation algorithm, risk minimization, loss function, regularization, heuristics for faster training and avoiding local minima.

Module:4 | Deep Feed Forward Neural Networks

6 hours



Feed forward neural networks- deep model- output units and hidden units, training deep models-hyper parameters and validation sets-cross validation, capacity, overfitting and under fitting, bias vs variance trade off, cross validation - vanishing gradient problem, new optimization methods (adagrad, adadelta, rmsprop, adam), regularization methods (dropout, batch normalization, dataset augmentation), early stopping.

| Module:5 | Convolutional Neural Networks | | | | 7 hours | |
|--------------|--|------------------|---------------------------------------|----------------|-----------------|--|
| Convolutio | n operation- kernel and feature map | , sparse connect | tivity, equiv | ariance throu | igh parameter | |
| sharing, po | poling function for invariant repre | sentation, conve | olution and | pooling as | strong prior, | |
| convolution | n with stride, effect of zero padding | , single-channel | and multi-c | channel data | types used in | |
| ConvNet, | variants of basic convolution- loca | illy connected, | tiled ConvN | let- spatial s | separable and | |
| - | separable convolutions, fully connec | • | Net archite | cture- layer p | patterns, layer | |
| sizing para | meters, case studies- LeNet, AlexNet | | | | | |
| | | | | | | |
| | Recurrent Neural Networks | | | | 6 hours | |
| - | earning with neural nets, unrolling th | · | _ | | | |
| , | T), vanishing gradient problem, Ga | | nit (GRU), | Long short t | term memory | |
| (LSTM), B | idirectional LSTMs, bidirectional R1 | NNs | | | | |
| | 1 | | J | | | |
| Module:7 | Deep Learning Tools and Applic | | | | 8 hours | |
| | forFlow, Keras, PyTorch, Caffe, Th | | Application | ns: Object d | etection with | |
| RCNN - Y | OLO, SSD. Speech recognition with | RNN. | | | | |
| | T | | T - | | | |
| Module:8 | Contemporary Issues | | 2 | hours | | |
| | T | | | | | |
| T D . I | | Total | Lecture: 4 | 5 hours | | |
| Text Book | | 1 . | · · · · · · · · · · · · · · · · · · · | | # 2015 NOTE | |
| 1. | Bengio, Yoshua, Ian J. Goodfello | w, and Aaron C | Courville. "L | Deep learning | g" 2015, MIT | |
| | Press | (/D I | | | | |
| 2. | Josh Patterson and Adam Gibso | on, "Deep Lear | ning- A Pr | actitioner's | Approach" | |
| D. C | O'Reilly Media Inc., 2017, USA. | | | | | |
| Reference | | 134 1' 1 | | . 2011 | | |
| 1. | Bishop, C., M., Pattern Recognition | | | | 11 ' | |
| 2. | Rich E and Knight K, "Artificial Ir | | | | | |
| 3. | Bengio, Yoshua. "Learning deep architectures for AI- Foundations and trends in | | | | | |
| | Machine Learning, 2(1)- 2009 | | r'11 75 1 | (T. 11.) D. | T - 1 2012 | |
| 4. | Tom M. Mitchell, "Machine Learn | | | | | |
| | Evaluation: CAT, Digital Assignmen | nts, Quiz, Onlin | e course, Pa | aper publicat | ion, Projects, | |
| Hackathon/ | Makeathon and FAT. | | | | | |
| - | 1.11. 7. 1.00. 1 | 26.04.2016 | | | | |
| | ided by Board of Studies | 26-04-2019 | D : 10 ° | . 2010 | | |
| I Annroved ŀ | by Academic Council | No. 55 | Date: 13-06 | 5-2019 | | |



| Course Code | Course Title | L | T | P | J | C |
|--------------------|---|----|------|------|------|----|
| ECE6089 | AUTOMOTIVE SENSORS AND IN-VEHICLE | 2 | 0 | 2 | 0 | 3 |
| | NETWORKING | | | | | |
| Pre-requisite | ECE5060- Principles of Sensors and Signal Conditioning | Sy | llab | us v | ersi | on |
| | | | | 1.00 |) | |

- 1. Acquaint with the basic automotive parts and the need for sensor integration in different automotive systems
- 2. Discuss the basics of various Power train sensors and associated systems for proper vehicle dynamics and stability in Automotive systems.
- 3. Comprehend various sensors for vehicle body management and discuss various sensors and technologies for passenger convenience, safety and security systems.
- 4. Acquaint various communication standards and protocols followed within the automotive systems.

Course Outcome

- 1. Identify and understand the basic automotive parts and the requirement of sensors and their integration in different automotive systems.
- 2. Discus and identify the basics of various Power train sensors.
- 3. Comprehend and analyse various systems like ABS, ESP, TCS, etc for understanding vehicle dynamics and stability.
- 4. Comprehend the various sensors for vehicle body management, convenience & security systems.
- 5. Identify various technologies developed for passenger convenience, Air Bag deployment and Seat Belt Tensioner System, etc with the students
- 6. Recognize various communication standards and protocols followed within the automotive systems.
- 7. Develop and create analytical designing of novel prototype models for various automotive electronic systems.

Module:1 Introduction to Automotive Engineering, Automotive Management systems 4 hours

Power-train, Combustion Engines, Transmission, Differential Gear, Braking Systems, Introduction to Modern Automotive Systems and need for electronics in Automobiles, Application areas of electronics in the automobiles, Possibilities and challenges in the automotive industry, Enabling technologies and Industry trends.

Module:2 Power train Sensors 4 hours

λ sensors, exhaust temperature sensor, NOx sensor, PM sensor, fuel quality sensor, level sensor, torque sensor, speed sensor, mass flow sensor, manifold pressure sensor.

Module:3 Sensors for Chassis management 4 hours

Wheel speed sensors/direction sensors, steering position sensor (multi turn), acceleration sensor (inertia measurement), brake pneumatic pressure sensor, ABS sensor, electronic stability sensor.

| violute.4 Sensors for vehicle body management, | Module:4 Se | ensors fo | r vehicle | body | management, | 6 hours |
|--|-------------|-----------|-----------|------|-------------|---------|
|--|-------------|-----------|-----------|------|-------------|---------|



Sensors for automotive vehicle convenience and security systems

Gas sensors (CO₂), Temperature/humidity sensor, air bag sensor, key less entering sensor, radar sensors. Tire pressure monitoring systems, Two wheeler and Four wheeler security systems, parking guide systems, anti-lock braking system, future safety technologies, Vehicle diagnostics and health monitoring, Safety and Reliability, Traction Control, Vehicle dynamics control, Accelerators and tilt sensors for sensing skidding and anti-collision, Anti-collision techniques using ultrasonic Doppler sensors.

Module:5 Air Bag and Seat Belt Pre tensioner Systems 3 hours Principal Sensor Functions, Distributed Front Air Bag sensing systems, Single-Point Sensing systems, Side-Impact Sensing, and Future Occupant Protection systems. **Module:6** | Passenger Convenience Systems 3 hours Electromechanical Seat, Seat Belt Height, Steering Wheel, and Mirror Adjustments, Central Locking Systems, Tire Pressure Control Systems, Electromechanical Window Drives, etc. **Module:7** | **Modern Trends and Technical Solutions** 4 hours Enabling Connectivity by Networking:-In vehicle communication standards (CAN & LIN), Telematic solutions, Portable or embedded connectivity- Endorsing Dependability in Drive-bywire systems:- Terminology and concepts, Why by-wire, FLEXRAY, Requirements on cost and dependability, Drive-by-wire case studies- prototype development-future of In vehicle communication. **Contemporary Issues** 2 hours Module:8 Total 30 hours Text Book(s) Automotive Electrics, Automotive Electronics: Systems & Components, 2014, 5th Edition, BOSCH. John Turner, Automotive Sensors, 2010, 1st Edition, Momentum Press, New York. **Reference Books** Automotive Sensors Handbook, 8th Edition, 2011, BOSCH. Jiri Marek, Hans-Peter Trah, Yasutoshi Suzuki, IwaoYokomori, Sensors for Automotive 2. Technology, 2010, 4th Edition, Wiley, New York. Ernest O. Doebelin, "Measurement Systems – Application and Design", 2017, 6th Edition, McGraw-Hill, New Delhi. Mode of Evaluation: CAT, Digital Assignments, Quiz, Online course, Paper publication, Projects, Hackathon/Makeathon and FAT **List of Challenging Experiments: (Indicative)** Tire Pressure Monitoring Systems uses a wireless radio frequency signal 6 hours to communicate the tire pressure from sensors inside the wheel to a receiver centrally located in the vehicle. The sensors are powered by batteries that eventually wear out, so the amplitude of the transmitted



| | signal is minimized in order to conser | | | | | |
|----|--|-----------------|--------------------|-------------|--|--|
| | resulted in unreliable communication and it is not uncommon to lose | | | | | |
| | communication with the sensors re | | | | | |
| | indication. Develop a better way of se | nding RF signa | ls from the whee | els | | |
| | to the vehicle to conserve power and in | nprove commun | ication. | | | |
| 2 | After studying the characteristics of | various types o | f thermal senso | rs, 6 hours | | |
| | develop a suitable system which can | ne | | | | |
| | temperature in a non-contact method w | ith an accuracy | of ± -0.5 °C. | | | |
| 3 | Anti-collision system is preferred fo | r all the autor | notive systems | to 6 hours | | |
| | improve the passenger safety. Using the | he Doppler effe | ect as the detecti | on | | |
| | principle, develop an anti-collision syst | s. | | | | |
| 4 | In certain situations, airbag triggering i | be 6 hours | | | | |
| | prevented when deployment would be injurious to one of the vehicle's | | | | | |
| | occupants (for instance, if a child is sitting in the seat next to the driver, | | | | | |
| | or a child's safety seat is fitted). Develop an intelligent occupant | | | | | |
| | classification system which can classify based on distance between hip | | | | | |
| | bones, occupied surface, profile structure and dynamic response. | | | | | |
| 5 | Develop an intelligent inertial navigat | tion system usi | ng motion senso | ors 6 hours | | |
| | (accelerometers), rotation sensors (gyroscopes), and magnetic sensors | | | | | |
| | (magnetometers), to continuously calculate the position, orientation, and | | | | | |
| | velocity (direction and speed of movement) of an automotive system. | | | | | |
| | | urs 30 hours | | | | |
| Mo | ode of Evaluation: Continuous Assessme | nt and FAT | | | | |
| Re | commended by Board of Studies | 26-04-2019 | | | | |
| Ap | proved by Academic Council | No. 55 | Date | 13-06-2019 | | |
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| Course Code | Course Title | L | T | P | J | C |
|-------------------|---|-----|------|------|------|----|
| ECE6090 | Fiber optic Sensors and Photonics | 3 | 0 | 0 | 0 | 3 |
| Prerequisite | ECE5060 Principles of Sensors and Signal Conditioning | Syl | labı | is V | ersi | on |
| | | | | 1.0 | | |
| Course Objectives | | - | | | | |

- To introduce the theory and technology of fiber optics sensing to improve their understanding in rapidly growing field.
- 2. To predict the optical parameters in optical devices to understand the phenomena induced due to intensity based effects.
- 3. To estimate the phase, charge distribution due to polarization effects and its application in optical sensing.
- 4. To analyses and decide the process flow conditions and steps involved for different polymers with appropriate optical characteristic for polymer waveguides based sensing.

Course Outcomes

- 1. Attainment of basic knowledge of optical waveguides and optical devices employed in optical
- 2. Will be conversance in optical parameters involved in active and passive components
- 3. Entrust the characteristics of a suitable optical materials for the sensing device in a given application.
- 4. Identify and apply the knowledge in designing interferometric devices which is more effectively used in sensing.
- 5. Will be aware of different polymers and their chemical, optical characteristics to formulate miniaturized optical devices.

Module:1 **Theory of Optical Waveguides** 7 hours

Wave theory of optical waveguides, formation of guided modes, Slab waveguide, Rectangular waveguide, Radiation fields from waveguide, Effective index method, Marcatili's method, Beam propagation method. Basic characteristic of Optical Fiber Waveguides, Acceptance angle, Numerical aperture, skewrays- Electromagnetic Modes in Cylindrical Waveguides.

Active and Passive Optical Components

Electro-optic and acousto optic wave guide devices, directional couplers, optical switch, phase and amplitude modulators, filtersetc, Yjunction, powersplitters, arrayed waveguided evices, fiberpigtailing, endfiber prism coupling, FBG and fabrication of FBG, Tapered couplers.

Module:3 **Intensity and Polarization Sensors** 7 hours

Intensity sensor: Transmissive concept -Reflective concept-Micro bending concept-Transmission and Reflection with other optic effect-Interferometers -Mach Zehnder-Michelson-Fabry-Perot and Sagnac-Phase sensor: Phase detection-Polarization maintaining fibers. Displacement and temperature sensors: reflective and Micro bending Technology- Applications of displacement and temperature sensors.

Interferometric Sensors

Pressure sensors: Transmissive concepts, Microbending -Intrinsic concepts-Interferometric concepts, Applications. Flow sensors: Turbine flowmeters- Differential pressure flowsensors -Laser Doppler



velocity sensors-Applications- Sagnac Interferometer for rotation sensing. Magnetic and electric field sensors: Intensity and phase modulation types—applications.

| Module:5 | | Polymer based waveguide | in sensing | | | 7 hours | | |
|------------------------|---|--|--|------------|-----------|---------------------------------------|--|--|
| | sed way | reguide, materials, propertie | | cess of | polymer | | | |
| | | al components - Passive, Act | | | | | | |
| • | - | sonator-application in sensin | | , 8 | | , , , , , , , , , , , , , , , , , , , | | |
| | | ** | | | | | | |
| Module:6 | | Fiber based Chemical Sen | | | | 5 hours | | |
| Fiber base | d Chen | nical Sensing : Absorption | on, Fluorescence, | Chemi- | -luminesc | ence, Vibrational | | |
| Spectroscop | ic, SPR. | | | | | | | |
| | | | | | | | | |
| Module:7 | | Fiber based Bio-Senors | | | | 3 hours | | |
| | l Bio-me | olecules sensing: High Inde | ex, SPR, Hollow | core fibe | er probes | , Label Free bio- | | |
| nolecules. | | | | | | | | |
| | | | | | | | | |
| Module:8 | | | | | | 2 hours | | |
| | | | D / 17 / 1 | 45.1 | | | | |
| | |] | Total Lecture hou | rs: 45 I | iours | | | |
| | | | | | | | | |
| Text Book(| / | | | | | | | |
| 1. | | | A. Krohn, Trevor W. MacDougall, Alexis Mendez, "Fiber Optic Sensors: | | | | | |
| , | Fundamentals and Applications" SPIE Press, 4th ed. 2015. ISBN: 1628411805 | | | | | | | |
| 2. | | ric Udd , William B. Spillman Jr., "Fiber Optic Sensors: An Introduction for Engineers and Scientists", Wiley, 2nd Ed., 2011. ISBN: 0470126841 | | | | | | |
| Reference I | | entists, whey, and Ed., 201 | 1. ISBN. 04/0120 | 041 | | | | |
| l. | | ang & et al "Fundamentale | of Ontical Fiber | Sancare! | Wiley 1 | st Ed. 2012 ISBN: | | |
| 1. | Zujie Fang & et. al., "Fundamentals of Optical Fiber Sensors" Wiley, 1 st Ed., 2012.ISBN: 0470575409 | | | | | | | |
| 2 | Shizhuo Yin, Paul B. Ruffin, and Francis T.S. Yu, "Fiber Optic Sensors", CRC Press, 2 Ed, | | | | | | | |
| 2017. ASIN: B078JN75QW | | | | | | ,erc 11055, 2 Lu, | | |
| | | | | | | II: Mathematics, | | |
| 3 | | and Chemistry, Springer, 20 | | | | , | | |
| 3 | Physics | | | | T. | | | |
| | | CAT, Digital Assignments, O | Quiz, Online course | e and FA | T | | | |
| | | CAT, Digital Assignments, O | Quiz, Online course | e and FA | Ι΄ | | | |
| | aluation | CAT, Digital Assignments, Compared by Board of Studies | Quiz, Online course 26/04/2019 | e and FA | T | | | |